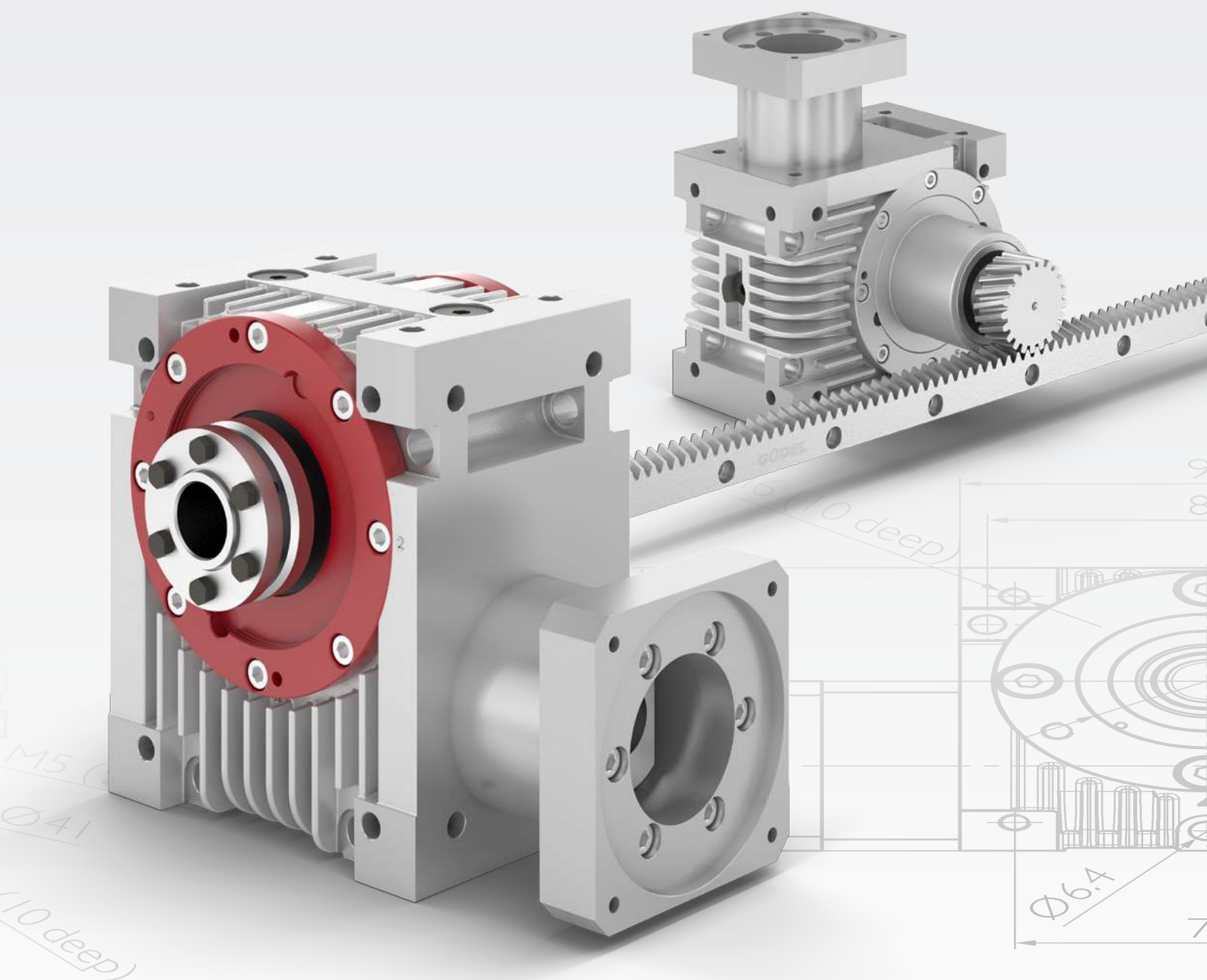


High Performance Angle Gearboxes



High Performance Angle Gearboxes

GÜDEL



Dear Customers,

Welcome to our fully revised catalog, featuring our current range of high-performance angle gearboxes. We are delighted at your interest, and to have this opportunity to present our products and their advantages in greater detail. As a leading supplier of linear drive and system technology, with a broad range of products and services and more than 60 years' experience in the industry, we see ourselves as your competent and reliable partner for all aspects of automation.

To start with, the catalog provides an overview of our six different sizes. With thirteen gear ratios and two precision grades, our high-performance angle gearboxes enable you to cover an extremely broad spectrum of use, for virtually all typical applications.

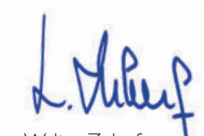
Our gearboxes are optimally complemented by our complete function packages, consisting of racks and pinions – we have everything you need. Benefit from our high level of vertical manufacturing, extensive know-how, and many decades of experience. This enables us to offer special solutions tailored specifically to your needs. Our configuration matrix will give you an initial overview of the range and help you select the high-performance angle gearbox that is right for you.

The main focus of our catalog is the technical data, which we have laid out in a clear, user-friendly manner. A double-page spread for each type of gearbox shows all key technical details. This is followed by useful information regarding our ordering codes and your individual options regarding motor flanges, gearboxes and function packages.

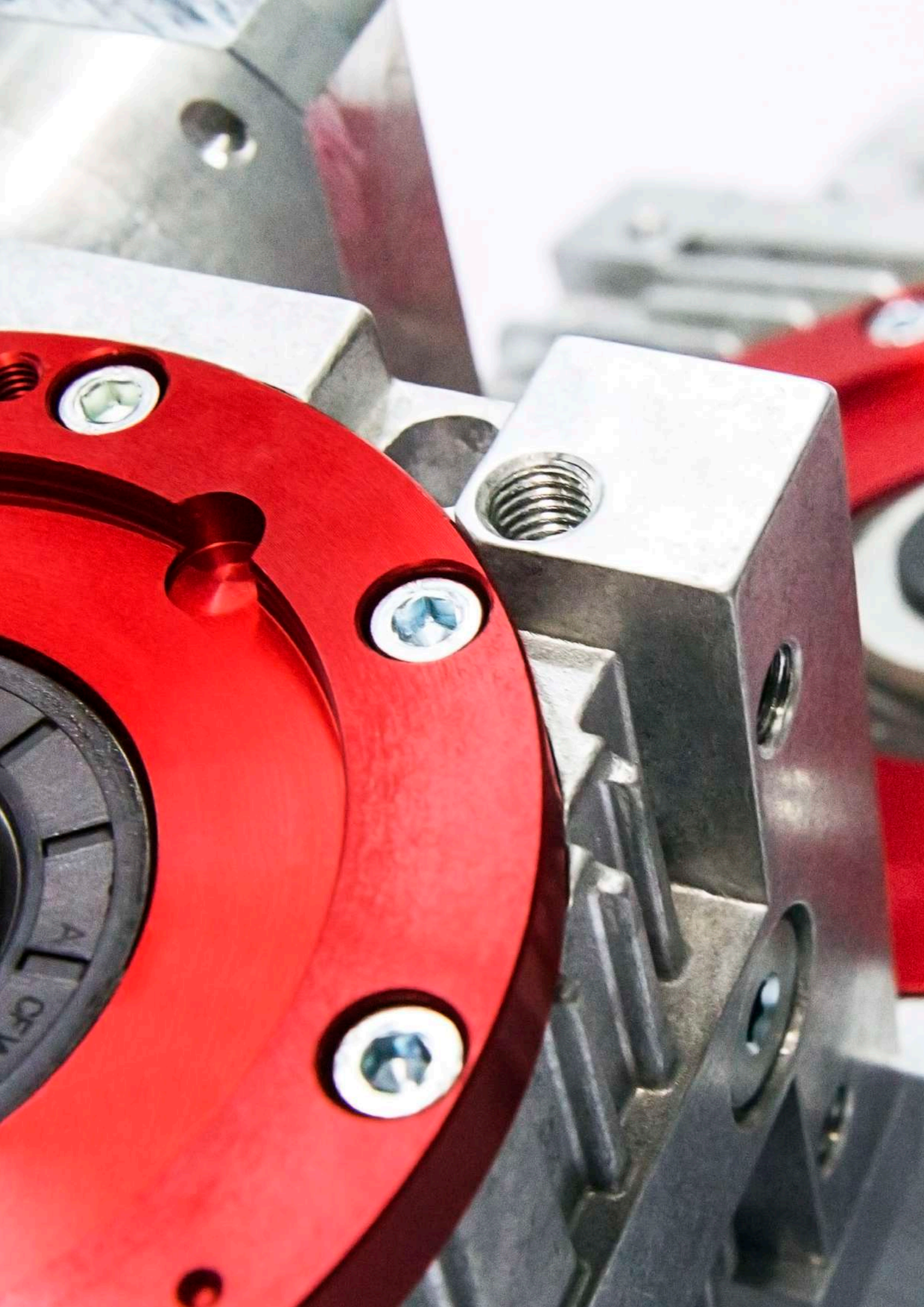
To always provide you with the optimal one-stop solution, we are constantly developing our range of services and products. Our colleagues will be happy to provide you with any further information that you require, or with an individual consultation.

We hope that you enjoy reading and looking through our catalog. We have taken great care to create an attractively designed document that both helps you to swiftly select the right product for your needs and entices you to browse and find inspiration for new ideas.

Best regards,


Walter Zulauf
CTO Güdel Group AG


Markus Ruprecht
CEO Güdel AG



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All about Six – All Sizes at a Glance

Our portfolio of high-performance angle gearboxes covers six different sizes. The names for the different sizes correspond to the center distance (in mm) between the input and output shafts: 030, 045, 060, 090, 120 and 180. An extremely broad choice of gear ratios – thirteen in total, ranging from 2 to 60 – enables you to cover the most common areas of application.

Our high-performance angle gearboxes are ideal for all types of angular drives. They are used in mechanical engineering, handling technology and various process applications, and are characterized by their high quality, long service life and minimal maintenance requirements. Our high-performance angle gearboxes are ideally suited for harsh working environments. They are dirt-resistant and can also cope with applications that use very long strokes. Their cooling fins guarantee optimal heat dissipation.

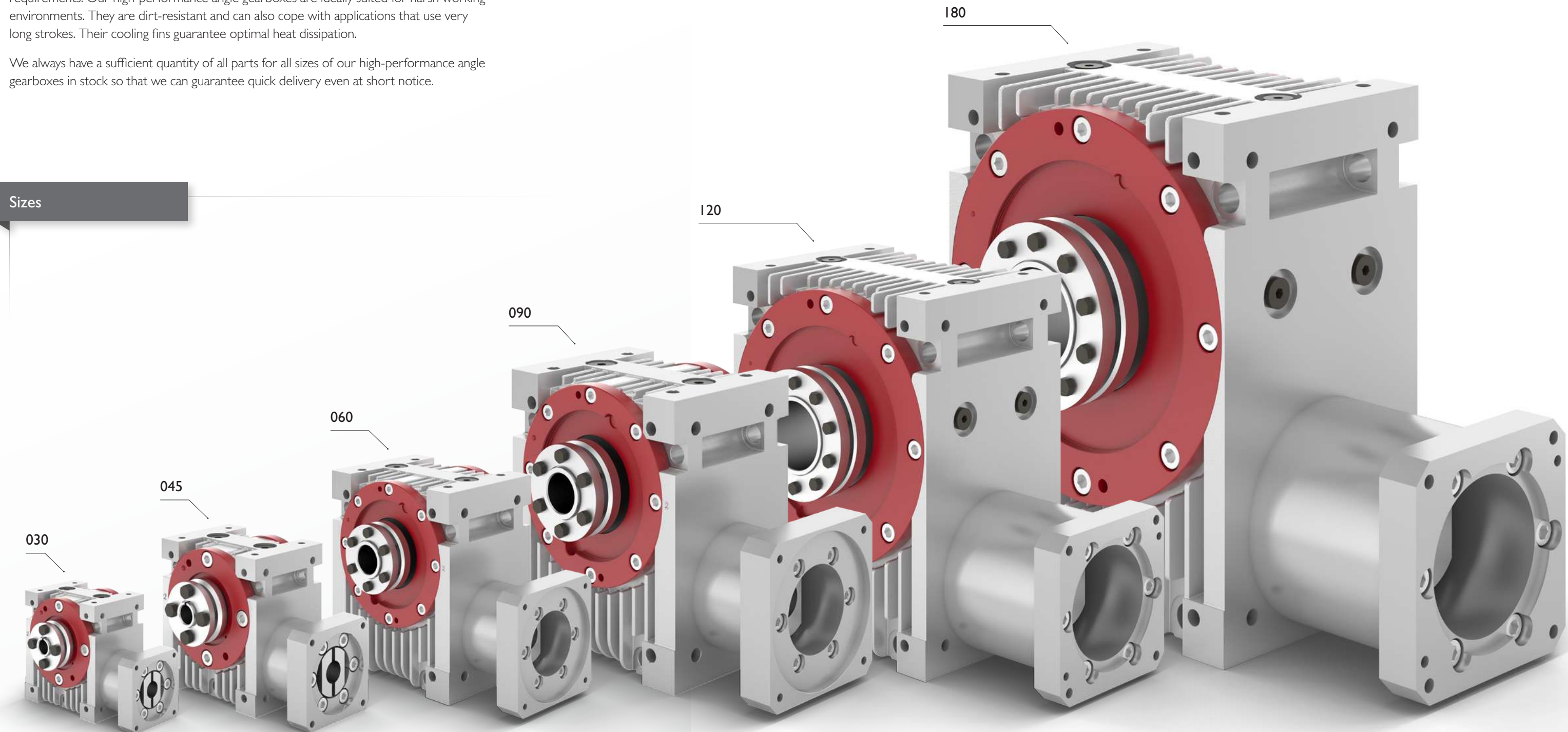
We always have a sufficient quantity of all parts for all sizes of our high-performance angle gearboxes in stock so that we can guarantee quick delivery even at short notice.

Our modular principle allows all the input and output variants within a given size to be combined however you want, in order to achieve a result that is perfectly tuned to your specific application needs. Depending on the gear ratio, you can use the self-locking or no self-locking properties, or the transition area for your requirements.

In addition to their high availability and universal build, our high-performance angle gearboxes also boast special design features such as: closed casing for a range of installation positions, the option to adjust the precision (backlash), great flexibility as regards the motor choice and coupling (motor – gearbox), lubrication, a range of mounting options on all sides, centering at the output and options for centering at the input. All these design features help you to perfectly integrate the angle gearboxes into your machinery or equipment.

We manufacture and assemble the gearboxes in-house, using state-of-the-art aproduction equipment. They are then thoroughly tested in accordance with our rigorous quality standards.

Sizes



Precise or Extra-precise – A Choice of two Grades

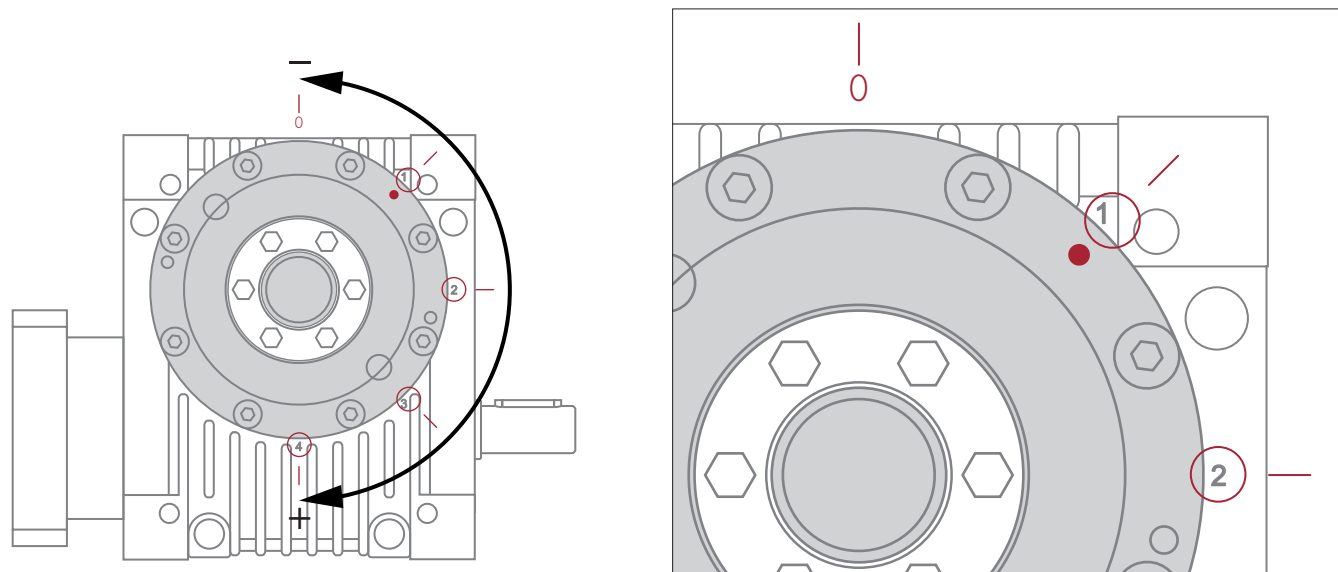
Our high-performance angle gearboxes are available in two precision grades. Precision grade PS stands for standard circumferential backlash and precision grade PR for reduced circumferential backlash. On the higher-precision gearbox (PR), the gear play can be more finely adjusted, with the gear play corresponding to the output shaft's angle of twist (arcmin). To allow for precision re-adjustments, an easy-to-use eccentric system in the output shaft area is standard on all gearboxes, making it possible to set and re-adjust the backlash quickly and easily.

The gearboxes are preset in the factory to the selected precision grade. No re-adjustment is necessary under normal operating conditions, as the increase in backlash should be minimal for gearboxes that are correctly dimensioned and maintained.

Nevertheless, with our re-adjustment mechanism you can reset the backlash quickly, easily and safely over the entire service life – guaranteed. And there is no need to open up the gearbox to do this. You can easily make the re-adjustment yourself using the symmetric rotation of the eccentric flanges on either side of the output bearing. The position markings on the casing help you to define the eccentric position.

Unique Güdel Gear Teeth

Unique Güdel gear teeth, the backlash can be re-adjusted via the output lid. Rotate both covers in the direction of the next higher number, (marked in red).



Your initial Selection – Speed & Torque

On this page you can narrow down your choice between our high-performance angle gearboxes. Make a selection based on your key requirements – speed and torque – to find the correct gearbox for your application.

Ratio & Precision Grades

Precision Grade PS – standard circumferential backlash [arcmin]

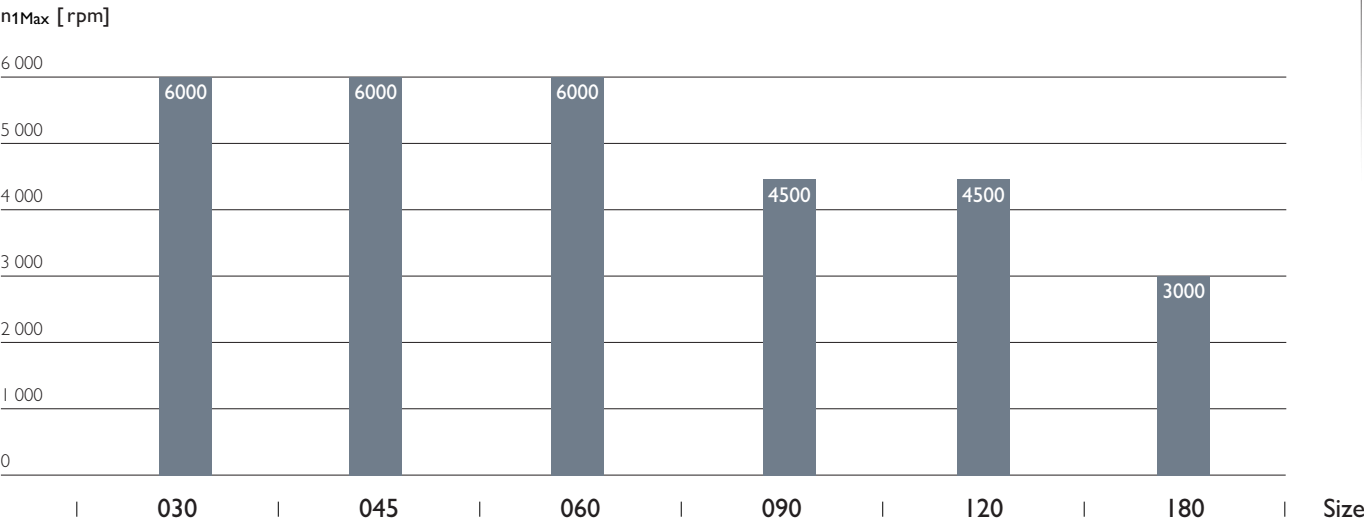
Size	PS												
	Ratio i												
	no self-locking									transition area		self-locking	
	2	3	4	5	6	8	10	13.33	16	24	30	47	60
030	22	18	16	16	14	12	12	12	12	12	11	11	11
045	15	12	11	11	9	8	8	8	8	8	7	7	7
060	13	10	9	9	8	7	7	7	7	7	6	6	6
090	10	8	7	7	6	6	6	6	6	6	5	5	5
120	8	7	6	6	5	5	5	5	5	5	4	4	4
180	5	4	4	4	3	3	3	3	3	3	2.5	2.5	2.5

Precision Grade PR – reduced circumferential backlash [arcmin]

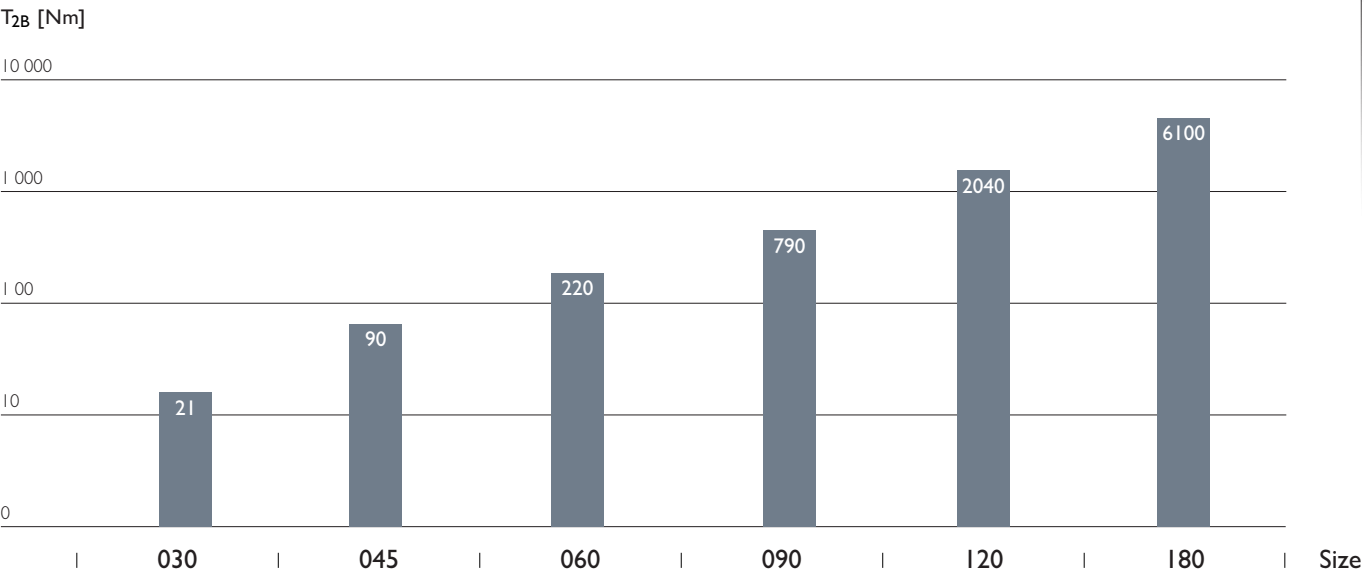
Size	PR												
	Ratio i												
	no self-locking									transition area		self-locking	
	2	3	4	5	6	8	10	13.33	16	24	30	47	60
045	10	8	7	7	6	5.5	5.5	5.5	5.5	5.5	5	5	5
060	9	7	6	6	5	4.5	4.5	4.5	4.5	4.5	4	4	4
090	6.5	5	4.5	4	4	3.5	3.5	3.5	3.5	3.5	3	3	3
120	5.5	4.5	4	3.5	3	3	3	3	3	3	2.5	2.5	2.5

The following diagrams offer you a preselection of sizes based on the most important performance parameters, maximum speed and maximum torque. The values apply for a sample ratio i = 24.

Maximum Rotation Speed



Maximum Torque

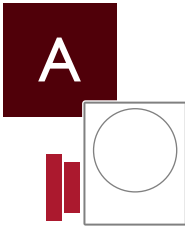
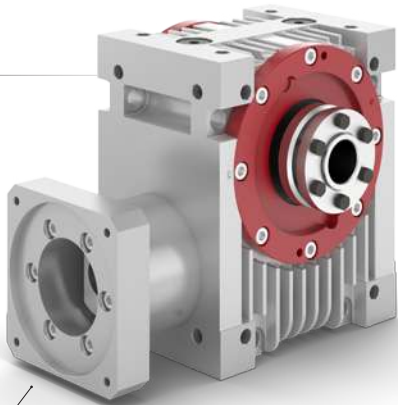


A wide Range of Inputs

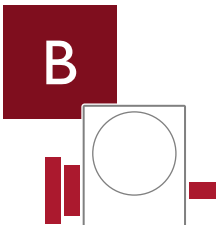
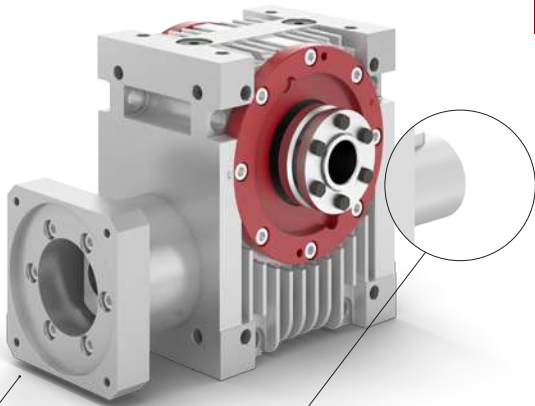
Choose between four different input varieties. Our two standard inputs come with either a motor flange or an input shaft. Our optional inputs offer you the choice of a motor flange with input shaft, or input shafts on both sides.

On the input side of the gearbox there is a low-backlash, positive-locking special coupling, and on the output side there is a shrink disc coupling. These guarantee a backlash-free power train and make it possible to attach a variety of motors. Their dimensions are determined by the mounting dimensions of the motors.

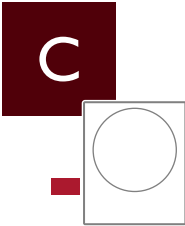
Input with Motor Flange



Motor Flange on one side

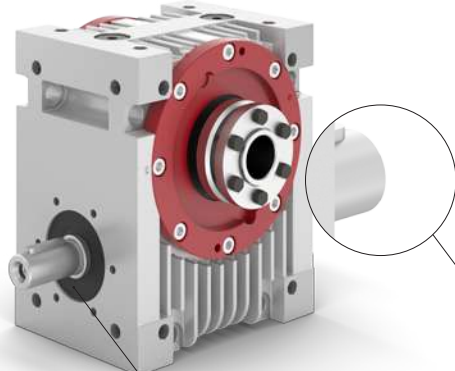
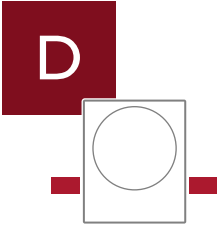


Motor Flange & Input Shaft

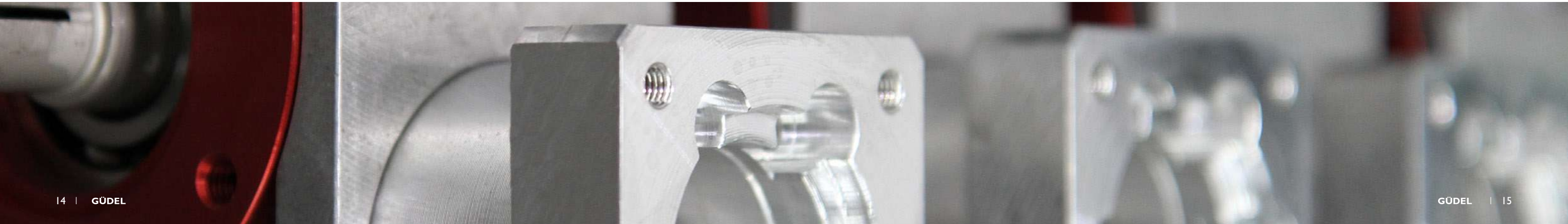


Input Shaft

Input Shaft on one side



Input Shaft on both sides



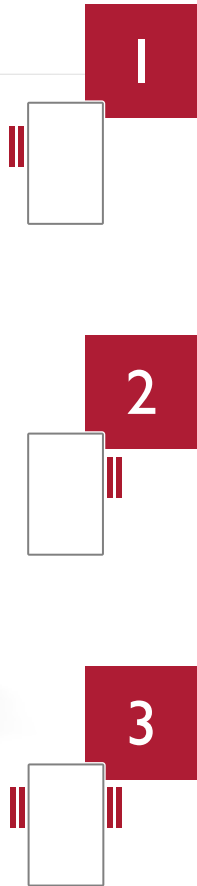
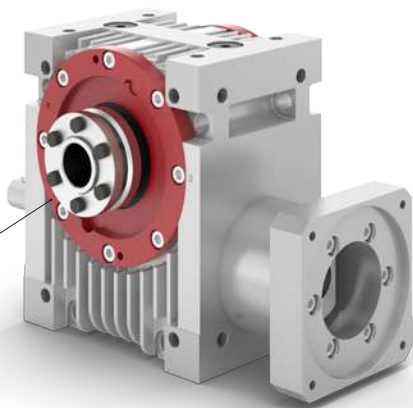
Meeting all your Needs – Standard & Optional Outputs

With our comprehensive range of outputs, you are ideally equipped for every application. Our standard outputs allow you to choose whether you prefer the shrink disc on the right, or left-hand side, or even on both sides.

We offer three standard outputs and four optional outputs. The standard outputs include a hollow shaft with shrink disc on the left, hollow shaft with output on the right, and a hollow shaft with shrink disc on both sides of the output. The optional outputs include a shaft on the left of the output, on the right of the output, on both sides of the output, and a hollow shaft on both sides of the output.

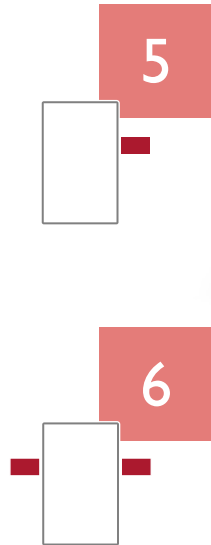
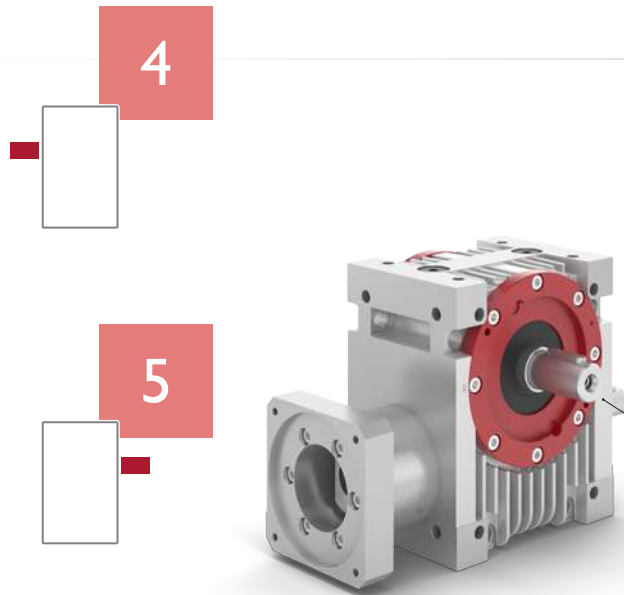
Standard Output with Shrink Disc

Shrink Disc
to the left (1),
to the right (2)* or
on both sides (3)

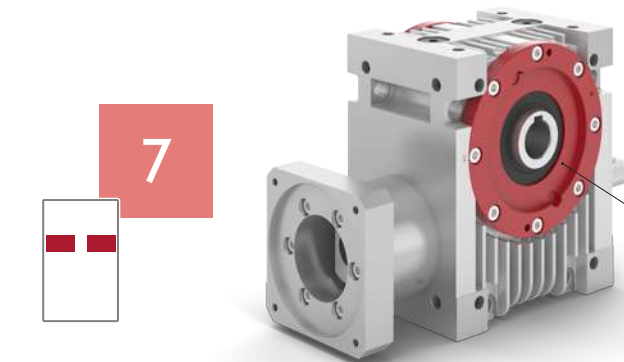


Optional Output Shaft

Shaft on the Output
to the left (4),
to the right (5)* or
on both sides (6)



Hollow Shaft of the output
on both sides (7)



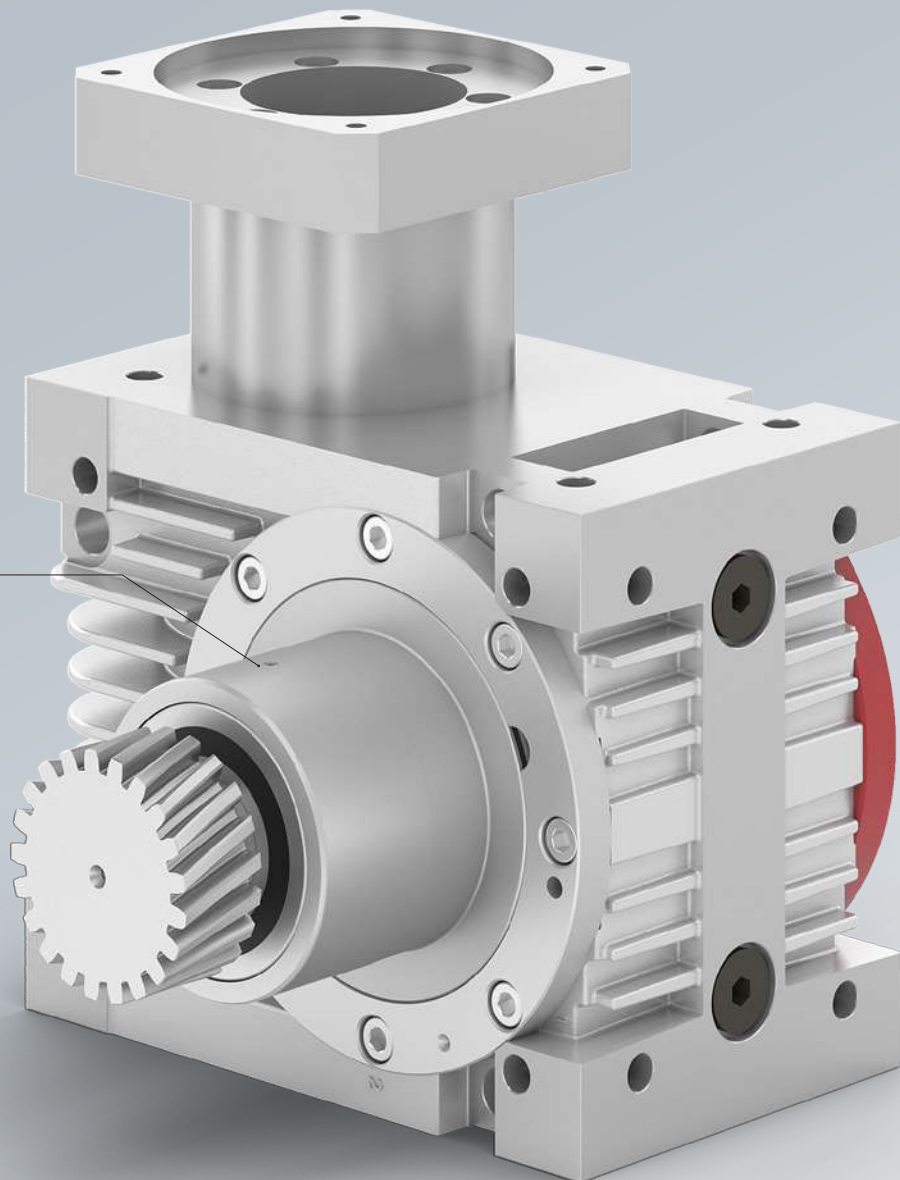
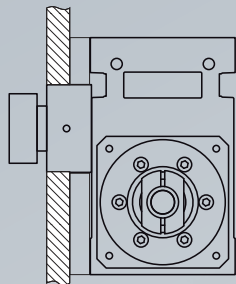
* Position right and left is defined by the motor view.

Adaptation Options – Preferably as a Package

Standard outputs can easily be expanded to packages with our pinion and our output flange. The following choices are available: Shrink disc on the left with pinion and output flange, shrink disc on the right with pinion and output flange. In gearboxes with shrink discs on both sides of the output, an output flange can be positioned on either the left or the right side.

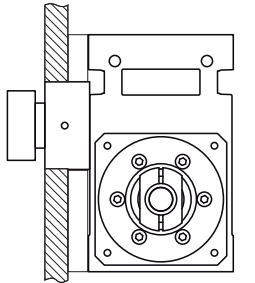
Package

Good support for the output bearing must be ensured.



Spacer Elements

The optional distance elements enable you to attach large, powerful motors to your gearbox easily and without having to carry out any complex additional work on your existing component structure. Depending on the size, we provide spacing strips or plates as assembly elements.



Additional Benefits

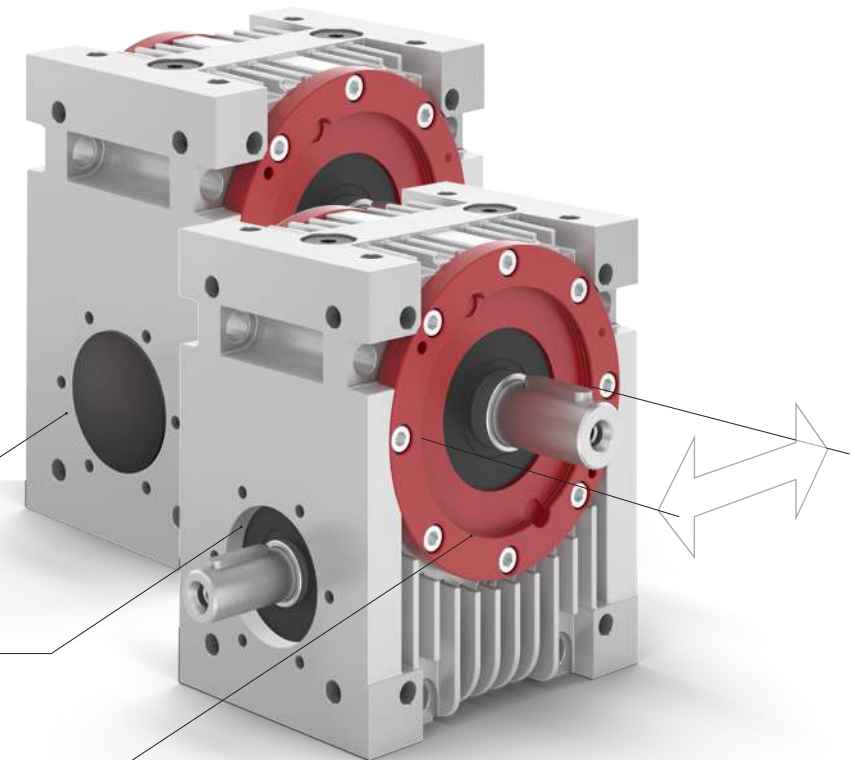
Precision centering Option thanks to an additional Function

Our high-performance angle gearboxes have a precise centering collar in the eccentric cover on the output side. This centering collar enables you to accurately align and mount the gearbox onto a shaft or bore hole on the output side. If required we can position the shaft seal or sealing cover further inwards. This will enable you to center and mount your attachments as you wish.

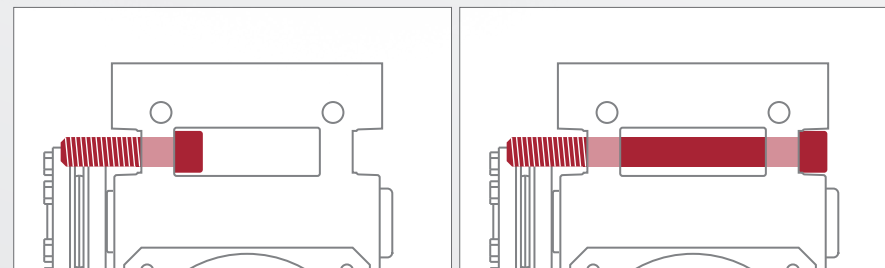
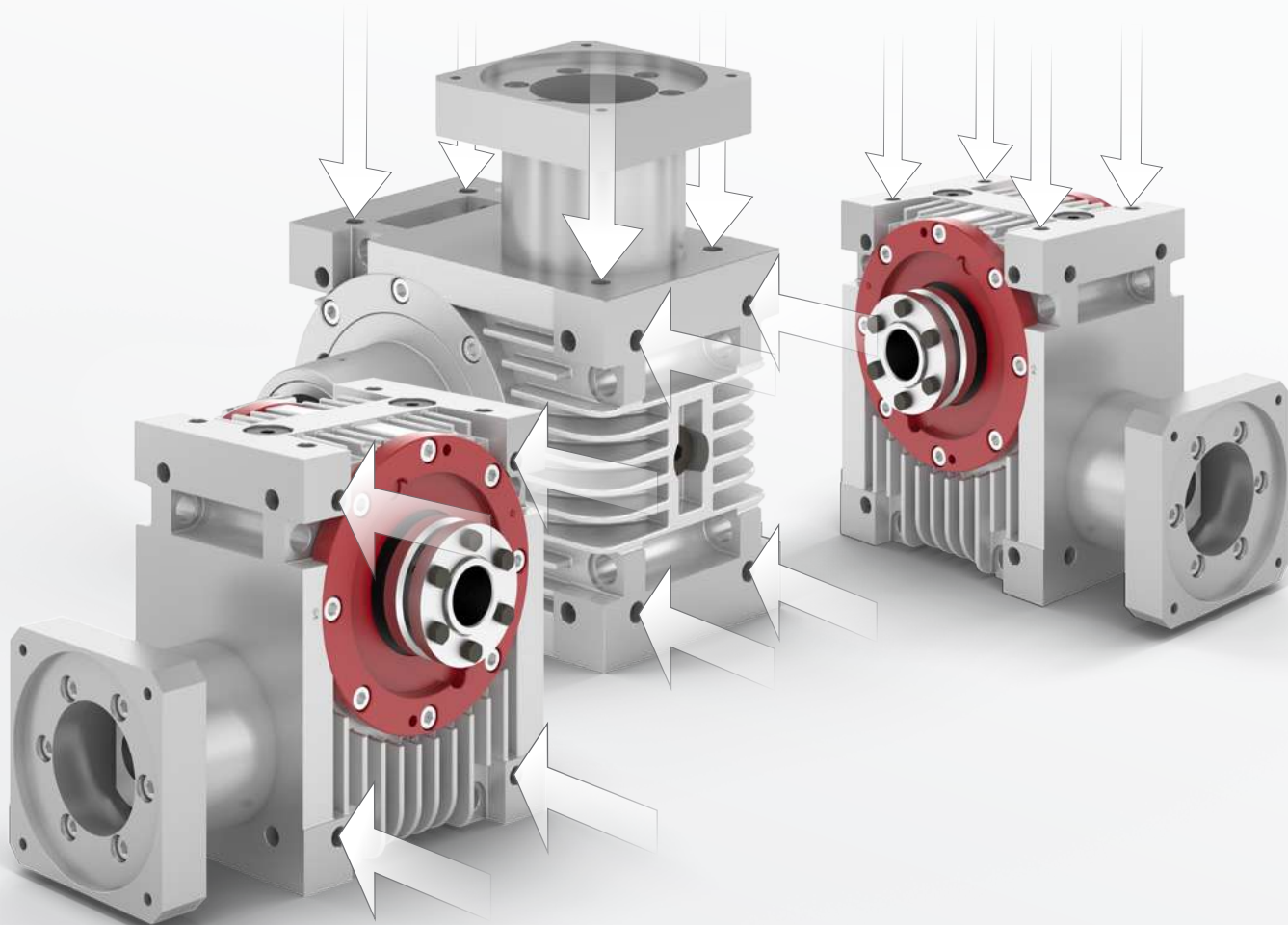
Cover shifted inwards

Shaft Seal shifted inwards

Centering collar on the eccentric cover

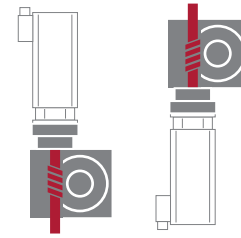


Universal fastening Methods & Positioning of your Gearbox

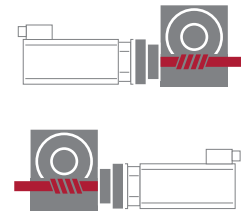


A huge range of fastening methods is possible, for example with long or short screws, as well as as through the multi-directional thread in the casing.

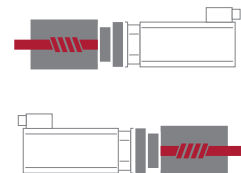
SS vertical standing worm



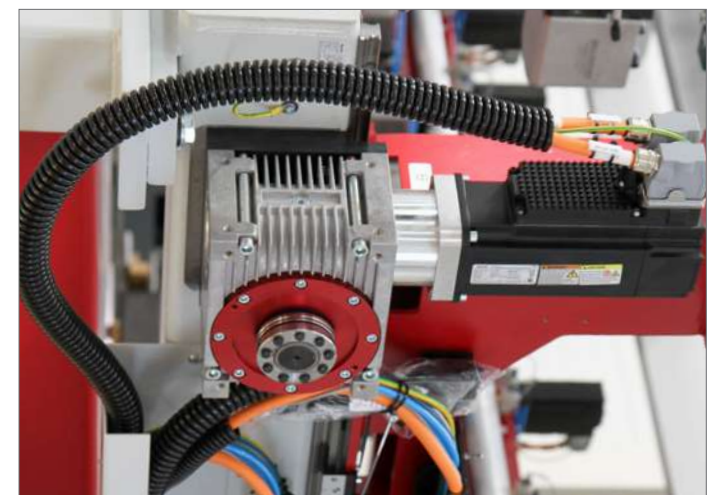
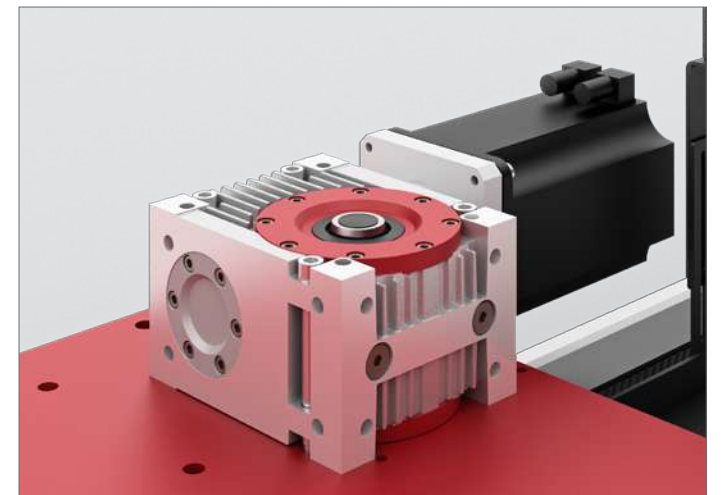
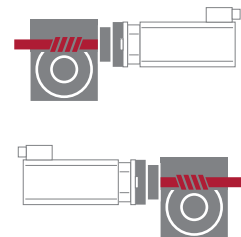
SU vertical worm below



SL flat lying worm



SO vertical worm top



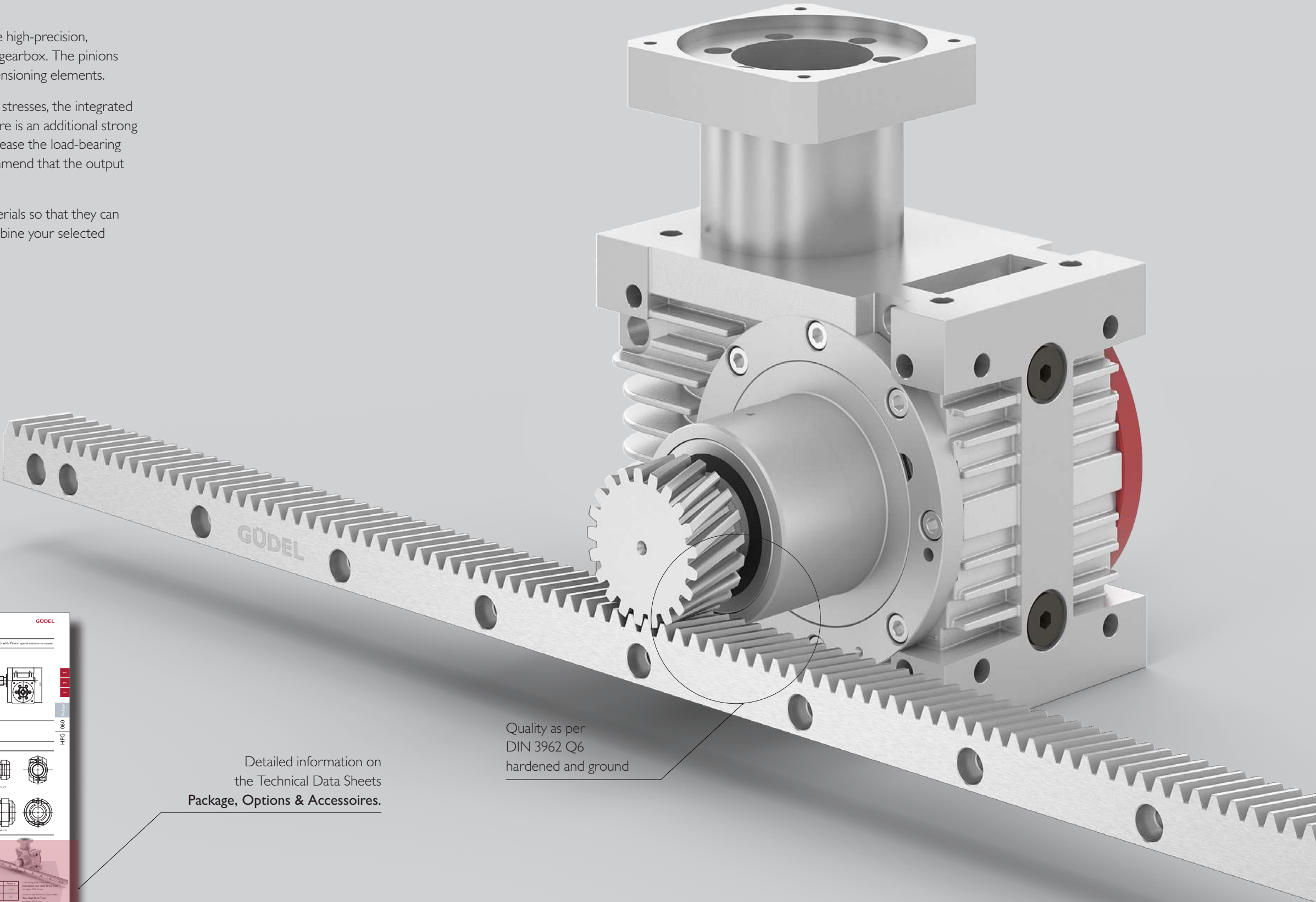
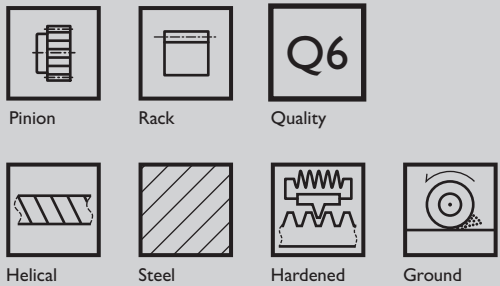
Your ideal Drive Train - Gearbox, Rack & Pinion

Our gearboxes can be easily combined with our racks and pinions into complete functional packages. The components from our product portfolio are ideal for your high-performance drive train.

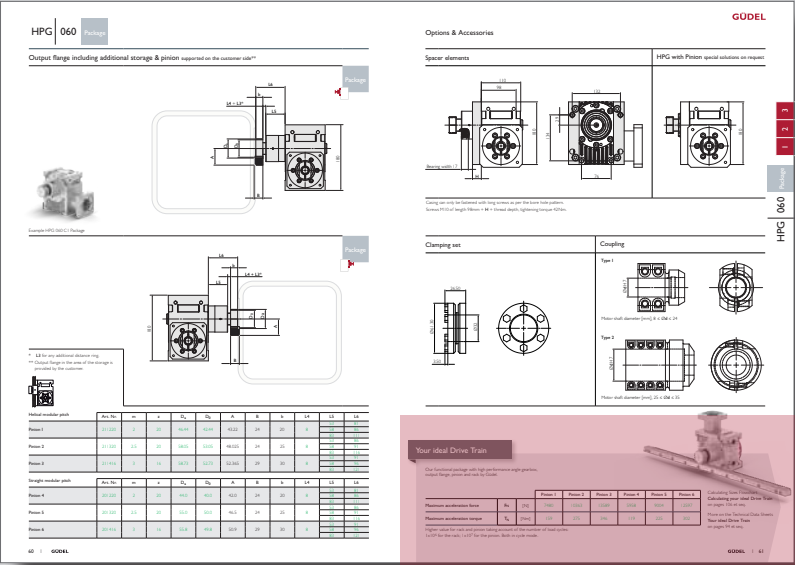
For linear systems with a rack-and-pinion drive, you can integrate high-precision, powerful drive pinions directly into our high-performance angle gearbox. The pinions are connected to the output with no backlash via non-positive tensioning elements.

For particularly demanding drive trains which are subject to high stresses, the integrated pinion can be given additional support from a output flange. There is an additional strong bearing in this output flange. This enables you to significantly increase the load-bearing capacity, service life, and rigidity of the pinion bearing. We recommend that the output flange be supported in a precision bore hole.

We offer our modular pinion and rack portfolio in different materials so that they can also be used in the food and chemical industry. You can also combine your selected gearbox with other Güdel products.



Detailed information on
the Technical Data Sheets
Package, Options & Accessoires.



Find your appropriate Size & Configuration

Inputs with Motor Flange

Motor Flange

Motor Flange & Input Shaft

Inputs with Shaft

Input Shaft

Input Shaft on both sides

Standard Outputs

Hollow Shaft with Shrink Disc

left

right

both sides

1

Package

2

Package

3

Size	Page	Page	Page	Page	Page
030	28-29	32-33	28-29	32-33	28-29
045	42-43	46-47	42-43	46-47	42-43
060	56-57	60-61	56-57	60-61	56-57
090	70-71	74-75	70-71	74-75	70-71
120	84-85	88-89	84-85	88-89	84-85
180	98-99	100-101	98-99	100-101	*

C

D

Size	Page	Page	Page	Page	Page
030	28-29	32-33	28-29	32-33	28-29
045	42-43	42-43	42-43	42-43	42-43
060	56-57	60-61	56-57	60-61	56-57
090	70-71	74-75	70-71	74-75	70-71
120	84-85	88-89	84-85	88-89	84-85

Optional Outputs

Output Shaft

left

right

both sides

4

5

6

7

Page	Page	Page	Page
34-35	34-35	34-35	38-39
48-49	48-49	48-49	52-53
62-63	62-63	62-63	66-67
76-77	76-77	76-77	80-81
90-91	90-91	90-91	94-95
102-103	102-103	102-103	*

36-37

50-51

64-65

78-79

92-93

Page	Page	Page	Page
34-35	34-35	34-35	38-39
48-49	48-49	48-49	52-53
62-63	62-63	62-63	66-67
76-77	76-77	76-77	80-81
90-91	90-91	90-91	94-95

36-37

50-51

64-65

78-79

92-93

Your ideal Drive Train

Rack & Pinion Program

104-107

A

B

C

D

030

045

060

090

120

030

045

060

090

120

Motor Flange

Motor Flange & Input Shaft

Input Shaft

Input Shaft on both sides

* no request

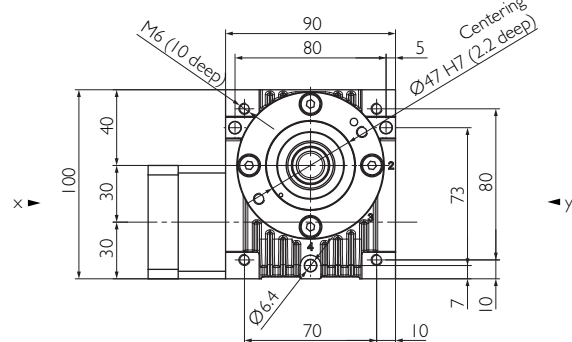
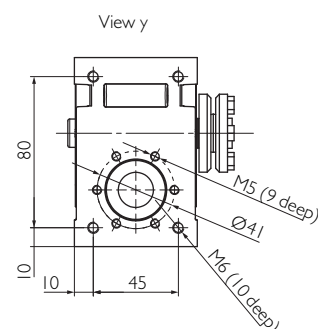
24 | GÜDEL

GÜDEL | 25

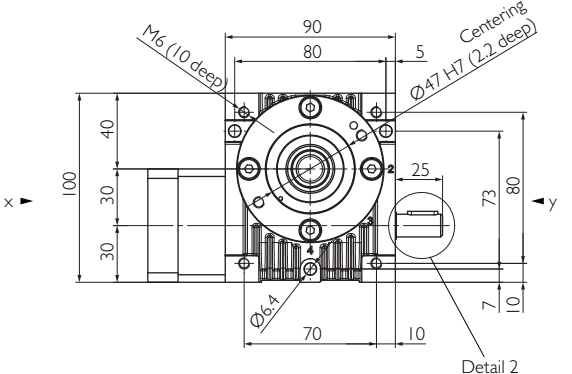
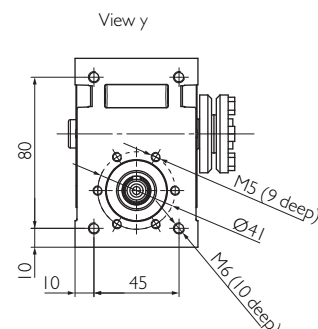


Technical Data Sheets

GÜDEL

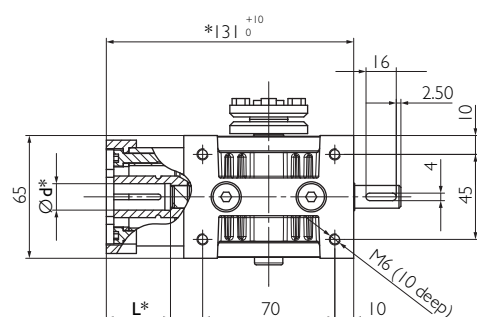
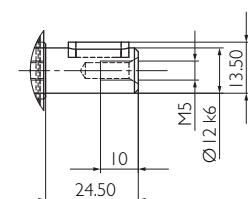


Example HPG 030 A2

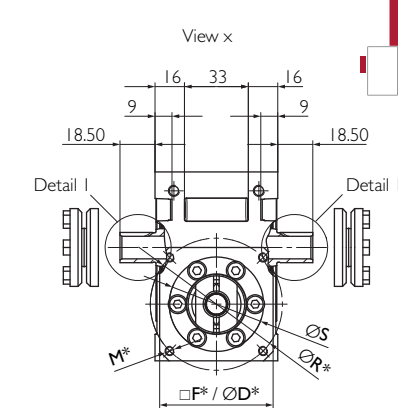
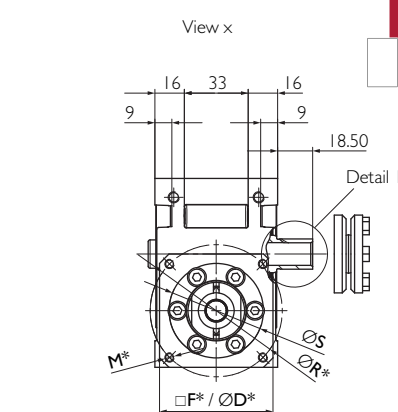
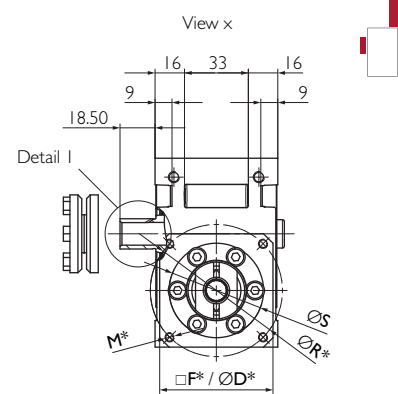


* Motor-specific gearbox dimensions
 $\varnothing d$: $\varnothing$ motor shaft [mm], $4 \leq \varnothing d \leq 19$
 L : Motor shaft length [mm], $20 \leq L \leq 33$

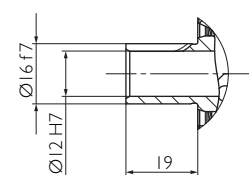
Detail 2



* Motor-specific gearbox dimensions
S: min. 32 [mm], **R:** Pitch circle Ø [mm], **M:** Bore hole Ø or thread [mm], **□F/ØD:** Specify flange [mm]



Detail 1

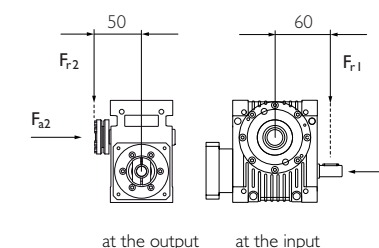


High Performance Angle Gearboxes

Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60	
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N}	[Nm]	12.9	17.9	20.1	19.2	16.9	19.4	17.9	17.5	19.5	19.0	8.6	18.8	8.6	
		η	[%]	85	84	83	81	80	76	74	67	63	54	48	40	30	30
	n _{1N} = 1000rpm	T _{2N}	[Nm]	11.3	16.0	18.3	17.5	15.5	17.9	16.6	16.2	18.1	17.6	8.6	17.5	8.6	
		η	[%]	86	86	85	83	81	77	74	68	65	55	50	44	40	40
	n _{1N} =1500rpm	T _{2N}	[Nm]	10.0	14.4	16.7	16.2	14.3	16.6	15.4	15.1	16.9	16.4	8.6	16.3	8.6	
		η	[%]	86	86	85	83	80	77	73	68	64	54	49	45	40	40
	n _{1N} = 3000rpm	T _{2N}	[Nm]	7.4	11.2	13.3	13.1	11.7	13.7	12.8	12.6	14.0	13.7	8.6	13.6	8.6	
η		[%]	84	84	83	81	77	74	71	67	62	53	48	44	40	40	
n _{1N} = 4500rpm	T _{2N}	[Nm]	5.9	9.2	11.0	11.0	9.9	11.6	10.9	10.8	12.0	11.8	10.0	11.7	10.0		
	η	[%]	81	82	81	78	76	73	69	65	60	51	47	42	37	37	
n _{1N} = 6000rpm	T _{2N}	[Nm]	4.9	7.8	9.4	9.4	8.6	10.1	9.5	9.4	10.5	10.3	10.0	10.2	10.0		
	η	[%]	79	79	78	77	75	72	68	62	56	47	42	37	33	33	
Max. acceleration torque		T _{2B}	[Nm]	13	21									10	21	10	
Emergency stop torque		T _{2Not}	[Nm]	35									20	35	20		
Idling torque ³⁾		T ₀₁₂	[Nm]	0.65				0.6				0.5					
Max. input speed		n _{1Max}	[rpm]	6000													
Max. backlash ^{b)} at the output		PS	j _c	[arcmin]	<22	<18	<16	<16	<14	<12				<11			
Torsional rigidity vom Abtrieb zum Eintrieb		C ₁₂₁	[Nm/arcmin]	0.3	0.45	0.58	0.63	0.66	0.68	0.72	0.74	0.78	0.8	0.75	0.85	0.75	
Stability at the output		C _{2K}	[Nm/arcmin]	27													
Max. axial force ^{c)} d) at the output		F _{a2max}	[N]	910	1200	1500	1800	2200	2100	2300	2500	2700	2900	3100	2900	3100	
Max. radial force ^{c)} e) at the output		F _{r2max}	[N]	640	740	850	970	1100	980	1000	1000	1100	1200	1300	1300	1300	
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	32	37	42	48	54	49	50	52	54	60	67	65	67	
Max. axial force ^{c)} d) at the input		F _{a1max}	[N]	890	740	700	780	890	820	890	910	860	880	1100	890	1100	
Max. radial force ^{c)} f) at the input		F _{r1max}	[N]	280	270	280	300	320	320	330	340	330	340	360	340	360	
Mass moment of inertia ^{g)}		Type 1 ^{h)}	J ₁	[10 ⁻⁷ kg m ²]	344	224	182	163	152	142	137	133	132	130	129	129	
Service life		L _h	[h]	25000													
Weight without motor components		m	[kg]	2													
Max. permissible housing temperature			[°C]	+90													
Ambient temperature			[°C]	-15 up to +50													
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)															
Painting		None															
Protection class		IP65															

- approximate, at $n_1 = 3000$ rpm and operating temperature.
- Precision grade PS (standard backlash) for classic mechanical engineering applications.
- Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{1}{3} T_{2N}$ and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
- d) in relation to shaft center.
- e) at a distance of 50 mm from the middle of the casing.
- f) at a distance of 60 mm from the middle of the casing.
- g) in relation to the input, including coupling and shrink disc at the output (output 1 & 2) with two shrink discs (output 3) increase values by $360/i^2$.
- g) h) Motor shaft diameter $\varnothing d$ from $\varnothing 4$ to $\varnothing 19$, calculated at $\varnothing 9$ mm.

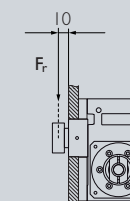
Bearing forces



Package

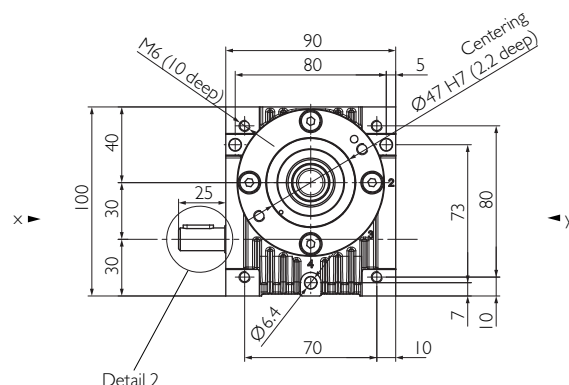
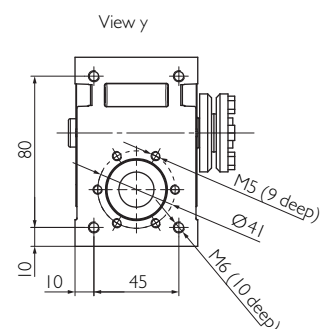
			Output Flange including Bearing & Pinion				
Radial rigidity	C ₃	[N/mm]	22000				
Speed	n _{2N}	[rpm]	1500	750	400	150	100
Max. radial force ¹⁾	F _{rmax}	[N]	1100	1350	1500	1600	1700

- j) Bearing forces: Values valid at duty cycle of 40% at a distance of 10mm from the end of the bearing.

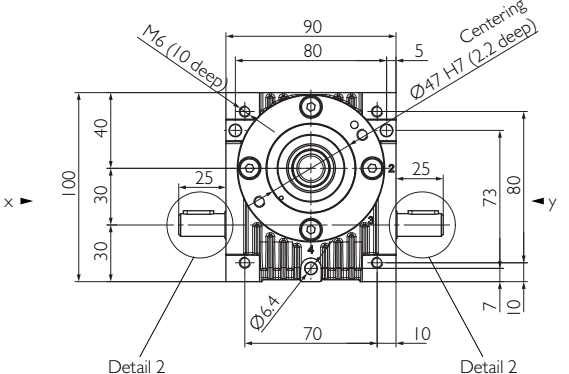
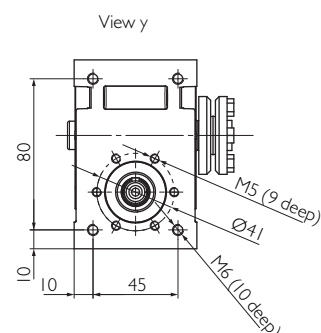


Detailed information about the **Package, Options & Accessories** on pages 32 and 33.

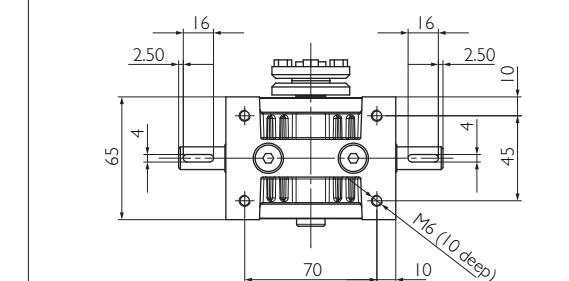
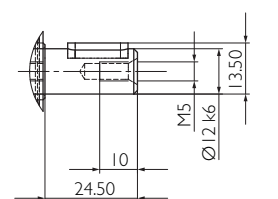
Input



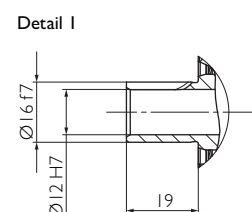
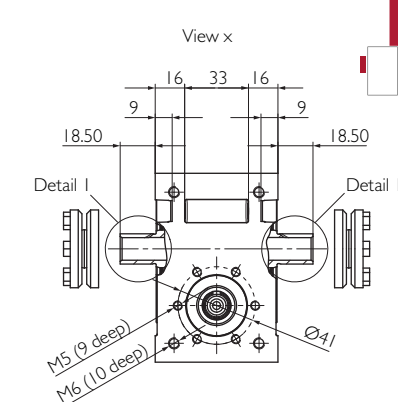
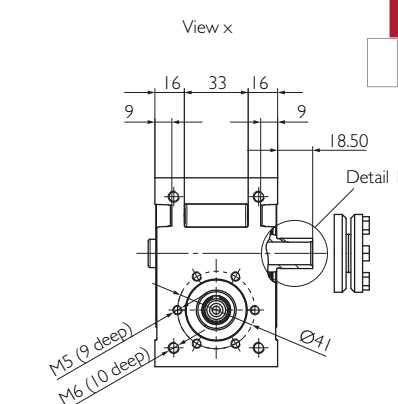
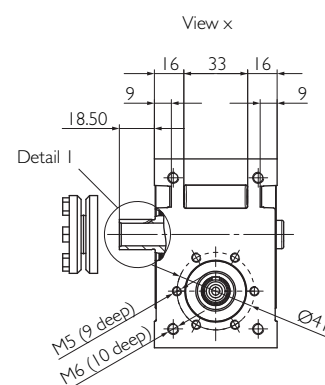
Example HPG 030 CI



Detail 2



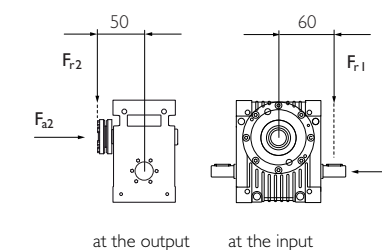
Output



Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60	
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N}	[Nm]	12.9	17.9	20.1	19.2	16.9	19.4	17.9	17.5	19.5	19.0	8.6	18.8	8.6	
		η	[%]	85	84	83	81	80	76	74	67	63	54	48	40	30	30
	n _{1N} = 1000rpm	T _{2N}	[Nm]	11.3	16.0	18.3	17.5	15.5	17.9	16.6	16.2	18.1	17.6	8.6	17.5	8.6	
		η	[%]	86	86	85	83	81	77	74	68	65	55	50	44	40	40
	n _{1N} =1500rpm	T _{2N}	[Nm]	10.0	14.4	16.7	16.2	14.3	16.6	15.4	15.1	16.9	16.4	8.6	16.3	8.6	
		η	[%]	86	86	85	83	80	77	73	68	64	54	49	45	40	40
	n _{1N} = 3000rpm	T _{2N}	[Nm]	7.4	11.2	13.3	13.1	11.7	13.7	12.8	12.6	14.0	13.7	8.6	13.6	8.6	
		η	[%]	84	84	83	81	77	74	71	67	62	53	48	44	40	40
	n _{1N} = 4500rpm	T _{2N}	[Nm]	5.9	9.2	11.0	11.0	9.9	11.6	10.9	10.8	12.0	11.8	10.0	11.7	10.0	
		η	[%]	81	82	81	78	76	73	69	65	60	51	47	42	37	37
	n _{1N} = 6000rpm	T _{2N}	[Nm]	4.9	7.8	9.4	9.4	8.6	10.1	9.5	9.4	10.5	10.3	10.0	10.2	10.0	
		η	[%]	79	79	78	77	75	72	68	62	56	47	42	37	33	33
Max. acceleration torque		T _{2B}	[Nm]	13	21									10	21	10	
Emergency stop torque		T _{2Not}	[Nm]	35									20	35	20		
Idling torque ³⁾		T ₀₁₂	[Nm]	0.65				0.6				0.5					
Max. input speed		n _{1Max}	[rpm]	6000													
Max. backlash ^{b)} at the output		PS	j _c	[arcmin]	<22	<18	<16	<16	<14	<12					<11		
Torsional rigidity vom Abtrieb zum Eintrieb		C ₁₂₁	[Nm/arcmin]	0.3	0.45	0.58	0.63	0.66	0.68	0.72	0.74	0.78	0.8	0.75	0.85	0.75	
Stability at the output		C _{2K}	[Nm/arcmin]	27													
Max. axial force ^{c)} d) at the output		F _{a2max}	[N]	910	1200	1500	1800	2200	2100	2300	2500	2700	2900	3100	2900	3100	
Max. radial force ^{c)} e) at the output		F _{r2max}	[N]	640	740	850	970	1100	980	1000	1000	1100	1200	1300	1300	1300	
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	32	37	42	48	54	49	50	52	54	60	67	65	67	
Max. axial force ^{c)} d) at the input		F _{a1max}	[N]	890	740	700	780	890	820	890	910	860	880	1100	890	1100	
Max. radial force ^{c)} f) at the input		F _{r1max}	[N]	280	270	280	300	320	320	330	340	330	340	360	340	360	
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁷ kg m ²]	230	110	68	49	38	28	23	19	18	16	15	15	15	
Service life		L _h	[h]	25000													
Weight without motor components		m	[kg]	1.7													
Max. permissible housing temperature			[°C]	+90													
Ambient temperature			[°C]	-15 up to +50													
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)															
Painting		None															
Protection class		IP65															

- a) approximate, at $n_1 = 3000$ rpm and operating temperature.
- b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
- c) Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{2}{3} T_{2N}$ and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
- c) d) in relation to shaft center:
- c) e) at a distance of 50 mm from the middle of the casing.
- c) f) at a distance of 60 mm from the middle of the casing.
- g) in relation to the input, including shrink disc at the output (output 1 & 2), with two shrink discs (output 3) increase values by $360/l^2$.

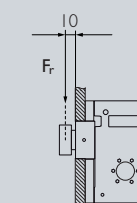
Bearing forces



Package

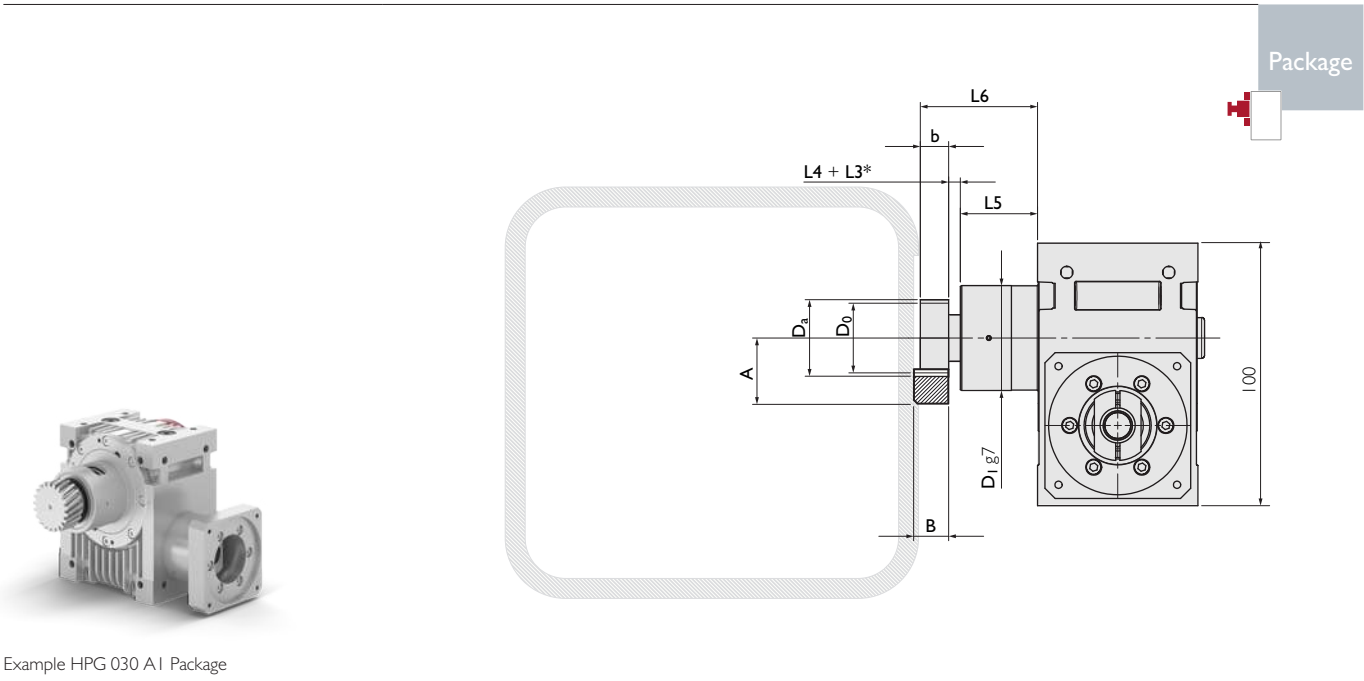
			Output Flange including Bearing & Pinion				
Radial rigidity	C ₃	[N/mm]	22000				
Speed	n _{2N}	[rpm]	1500	750	400	150	100
Max. radial force ¹⁾	F _{rmax}	[N]	1100	1350	1500	1600	1700

- j) Bearing forces: Values valid at duty cycle of 40% at a distance of 10mm from the end of the bearing.

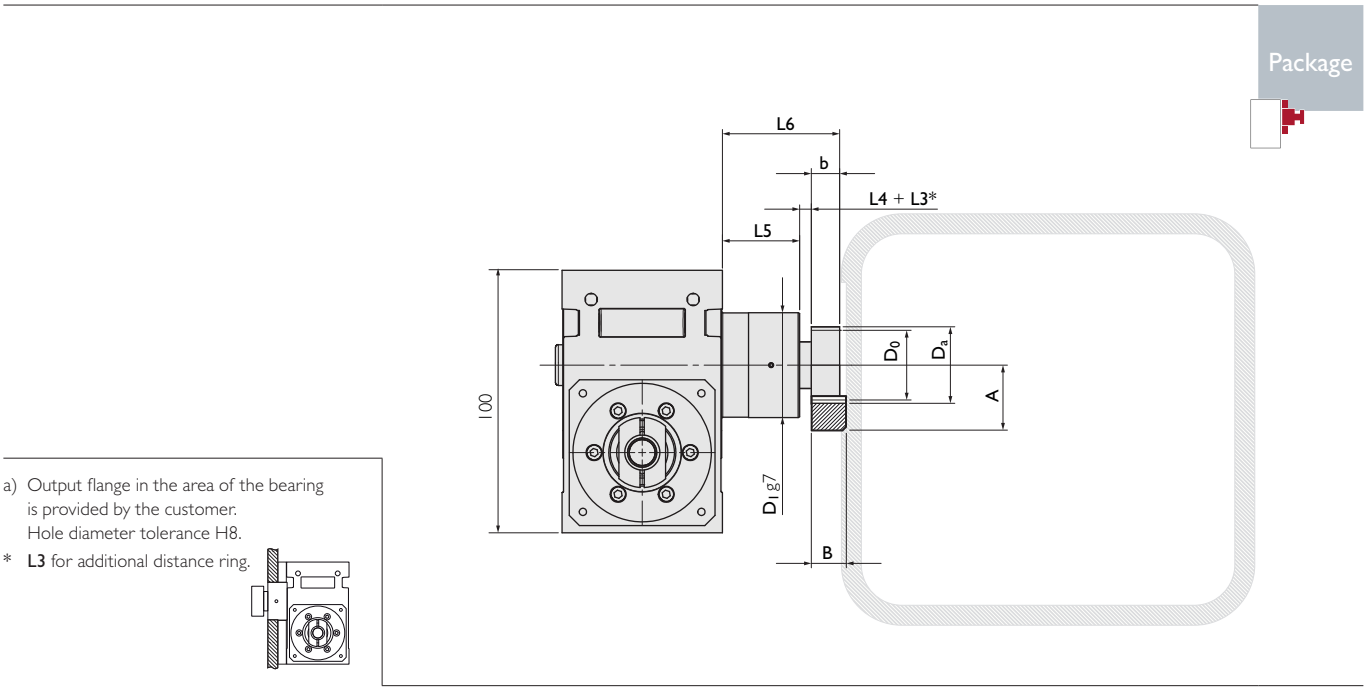


Detailed information about the **Package, Options & Accessories** on pages 32 and 33.

Output Flange including Bearing & Pinion^{a)}



Example HPG 030 A1 Package



a) Output flange in the area of the bearing is provided by the customer. Hole diameter tolerance H8.
* L3 for additional distance ring.

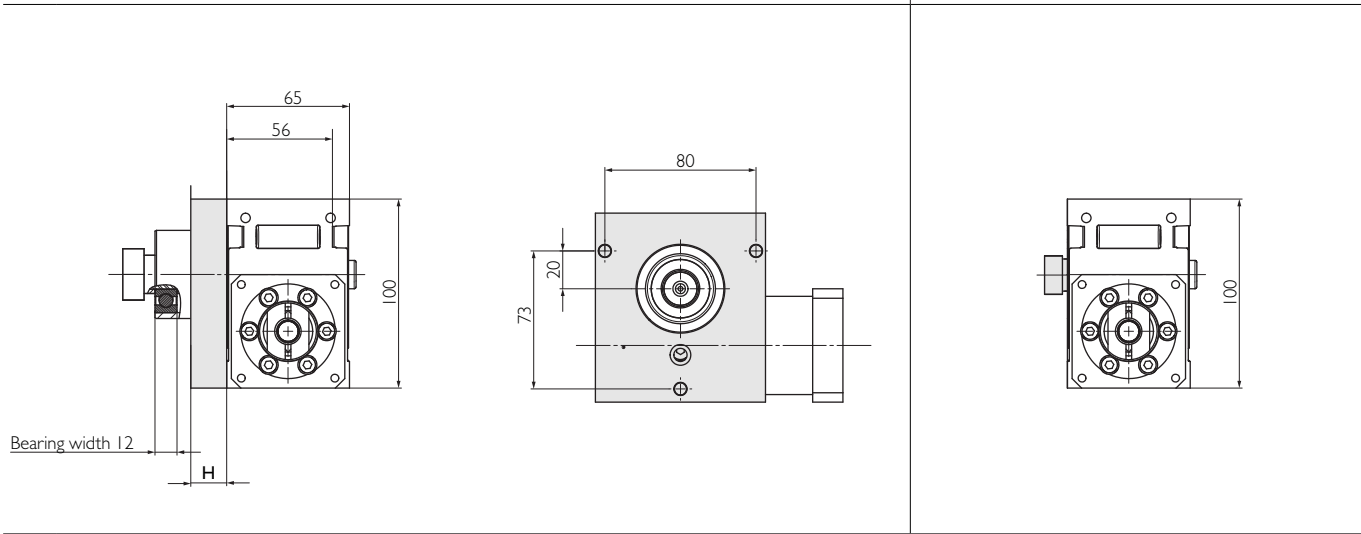
Geometric information

Helical modular pitch	Art. Nr.	m	z	A	b	B	D _a	D ₀	D _I	L4	L5	L6
Pinion I	211116	1.5	16	30.68	20	19	29.36	26.36	47	4.5	38	62.5
											43	67.5

Straight modular pitch	Art. Nr.	m	z	A	b	B	D _a	D ₀	D _I	L4	L5	L6
Pinion 2	201116	1.5	16	29.95	20	19	27.9	24.9	47	4.5	38	62.5
											43	67.5

Spacer Elements

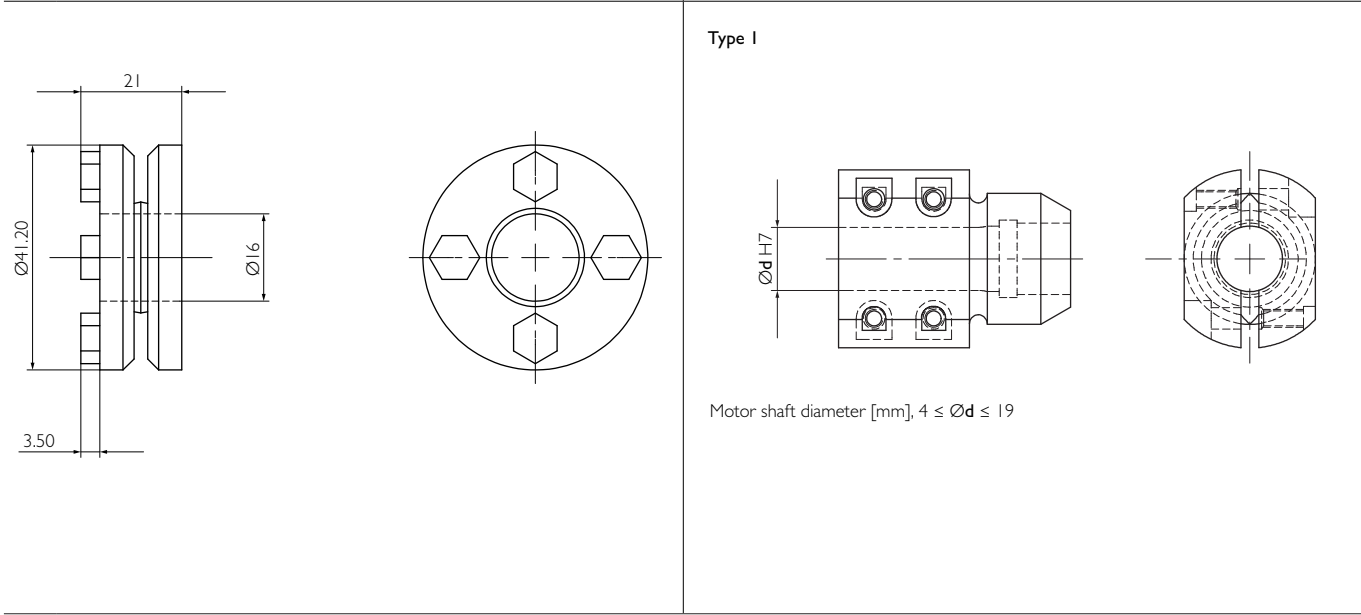
with Pinion special solutions on request



Casing can only be fastened with long screws as per the bore hole pattern. Screws M6 of length 56mm + H + thread depth, tightening torque 9Nm.

Shrink Disc

Coupling

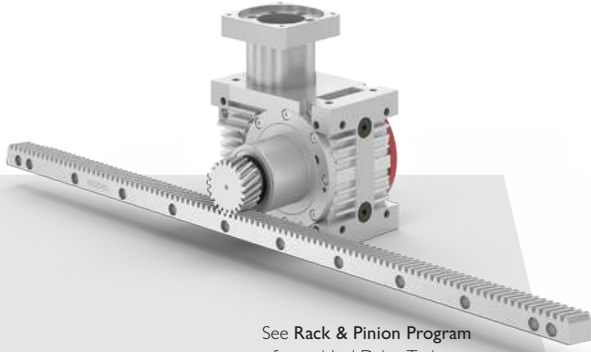


Your ideal Drive Train

Our Function Package with high-performance angle gearbox, output flange, pinion and rack by Güdel.

			Pinion I	Pinion 2
Maximum acceleration force	F _N	[N]	3178	2888
Maximum acceleration torque	T _N	[Nm]	41	35

Higher value for rack and pinion taking account of the number of load cycles: 1x10⁶ for the rack; 1x10⁷ for the pinion. Both in cycle mode.

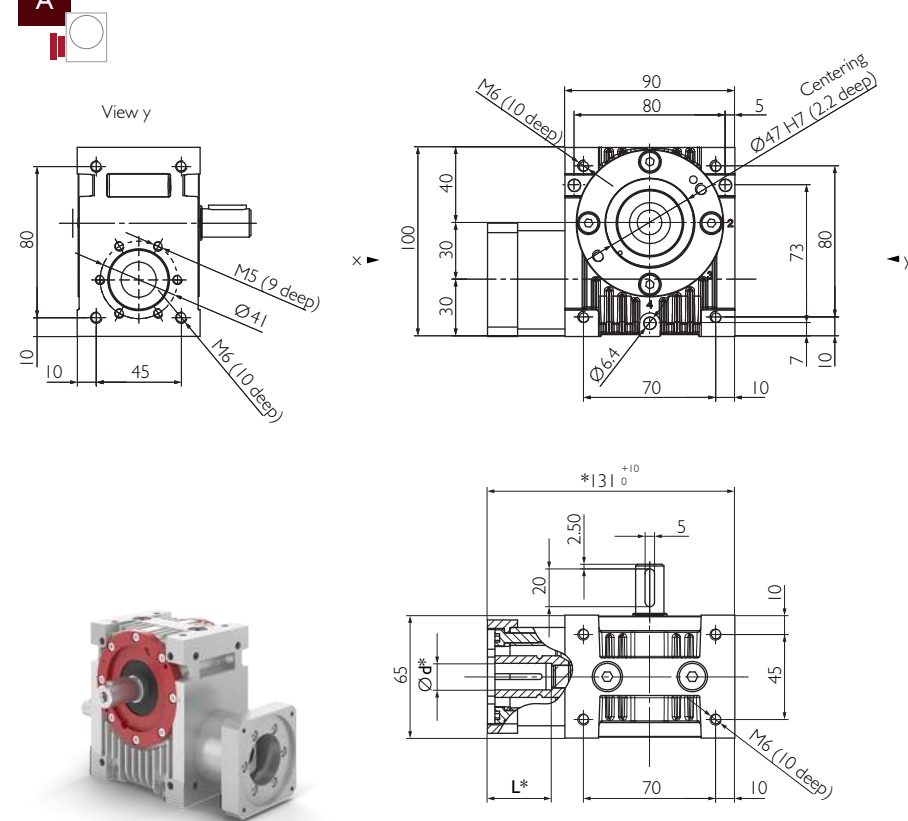


See **Rack & Pinion Program** of your ideal Drive Train on pages 104 et seq.

See **Flowcharts** to find your ideal Drive Train on pages 116 et seq.

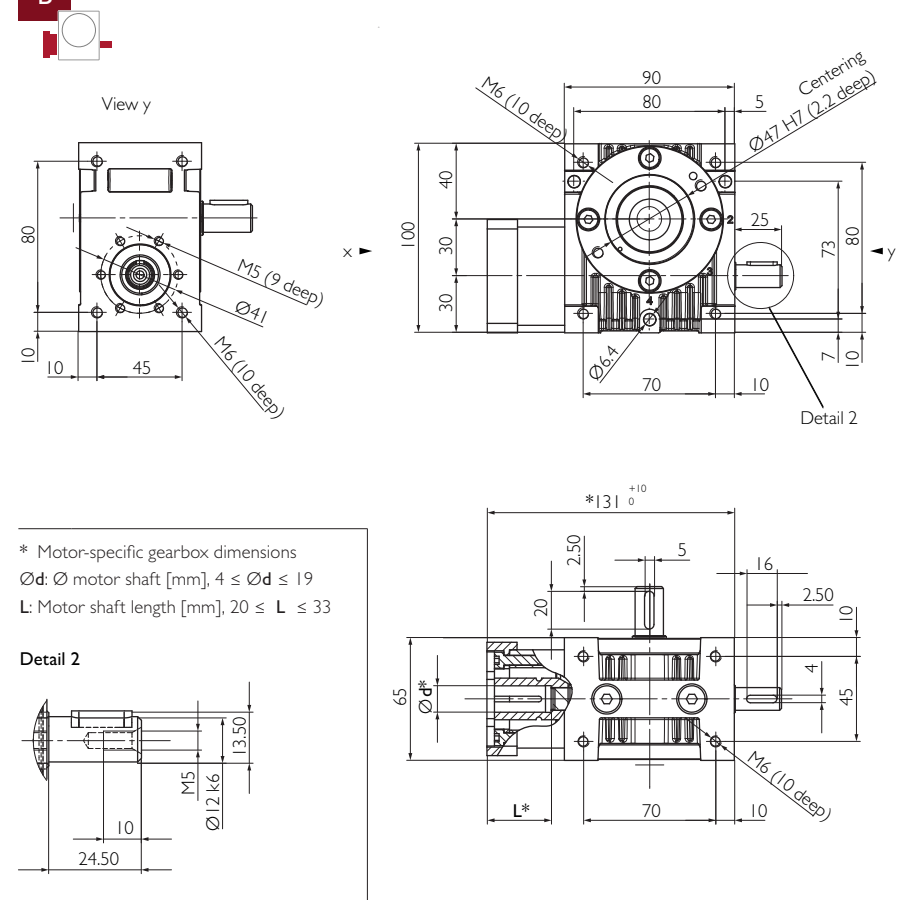
Input

A



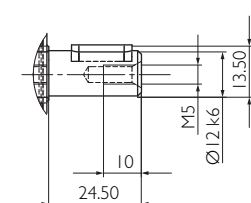
Example HPG 030 B4

B



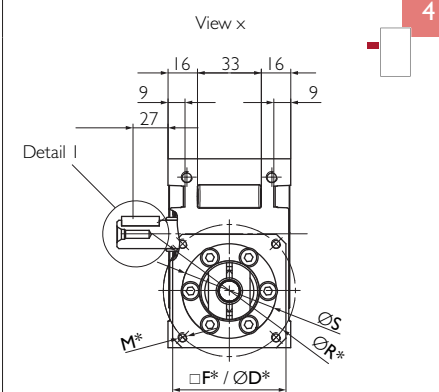
* Motor-specific gearbox dimensions
 $\varnothing d$: $\varnothing$ motor shaft [mm], $4 \leq \varnothing d \leq 19$
 L: Motor shaft length [mm], $20 \leq L \leq 33$

Detail 2

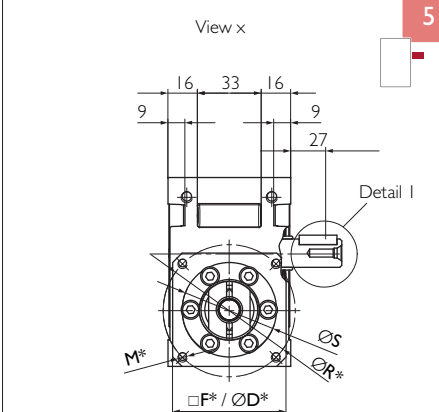


Output

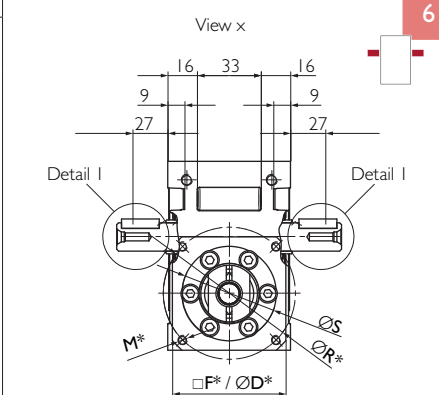
4



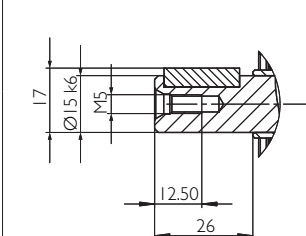
5



6



Detail 1

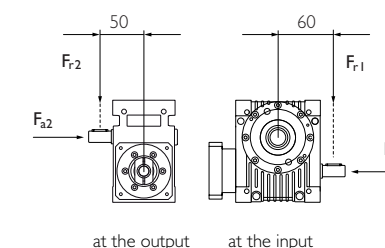


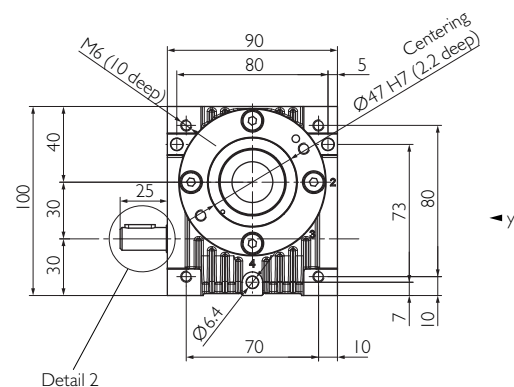
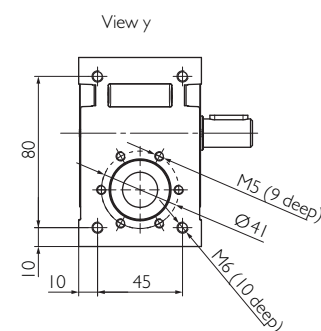
* Motor-specific gearbox dimensions
 S: min. 32 [mm], R: Pitch circle $\varnothing$ [mm], M: Bore hole $\varnothing$ or thread [mm], $\square F / \varnothing D$: Specify flange [mm]

Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60		
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	12.9 85	17.9 84	20.1 83	19.2 81	16.9 80	19.4 76	17.9 74	17.5 67	19.5 63	19.0 54	8.6 48	18.8 40	8.6 30		
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	11.3 86	16.0 86	18.3 85	17.5 83	15.5 81	17.9 77	16.6 74	16.2 68	18.1 65	17.6 55	8.6 50	17.5 44	8.6 40		
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	10.0 86	14.4 86	16.7 85	16.2 83	14.3 80	16.6 77	15.4 73	15.1 68	16.9 64	16.4 54	8.6 49	16.3 45	8.6 40		
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	7.4 84	11.2 84	13.3 83	13.1 81	11.7 77	13.7 74	12.8 71	12.6 67	14.0 62	13.7 53	8.6 48	13.6 44	8.6 40		
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	5.9 81	9.2 82	11.0 81	11.0 78	9.9 76	11.6 73	10.9 69	10.8 65	12.0 60	11.8 51	10.0 47	11.7 42	10.0 37		
	n _{1N} = 6000 rpm	T _{2N} η	[Nm] [%]	4.9 79	7.8 79	9.4 78	9.4 77	8.6 75	10.1 72	9.5 68	9.4 62	10.5 56	10.3 47	10.0 42	10.2 37	10.0 33		
	Max. acceleration torque		T _{2B}	[Nm]	13	21										10	21	10
	Emergency stop torque		T _{2Not}	[Nm]	35										20	35	20	
	Idling torque ^{a)}		T ₀₁₂	[Nm]	0.65					0.6				0.5				
	Max. input speed		n _{1Max}	[rpm]	6000													
Max. backlash ^{b)} at the output		PS	j _t	[arcmin]	<22	<18	<16	<16	<14	<12					<11			
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	0.3	0.45	0.58	0.63	0.66	0.68	0.72	0.74	0.78	0.8	0.75	0.85	0.75		
Stability at the output		C _{2K}	[Nm/arcmin]	27														
Max. axial force ^{c) d)} at the output		F _{a2max}	[N]	910	1200	1500	1800	2200	2100	2300	2500	2700	2900	3100	2900	3100		
Max. radial force ^{c) e)} at the output		F _{r2max}	[N]	640	740	850	970	1100	980	1000	1000	1100	1200	1300	1300	1300		
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	32	37	42	48	54	49	50	52	54	60	67	65	67		
Max. axial force ^{c) d)} at the input		F _{a1max}	[N]	890	740	700	780	890	820	890	910	860	880	1100	890	1100		
Max. radial force ^{c) f)} at the input		F _{r1max}	[N]	280	270	280	300	320	320	330	340	330	340	360	340	360		
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁷ kg m ²]	344	224	182	163	152	142	137	133	132	130	129	129	129		
Service life		L _h	[h]	25000														
Weight without motor components		m	[kg]	2														
Max. permissible housing temperature			[°C]	+90														
Ambient temperature			[°C]	-15 up to +50														
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)																
Painting		None																
Protection class		IP65																

- a) approximate, at $n_1 = 3000 \text{ rpm}$ and operating temperature.
 b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
 c) Bearing forces: Values valid at $n_1 = 3000 \text{ rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
 c) d) in relation to shaft center.
 c) e) at a distance of 50 mm from the middle of the casing.
 c) f) at a distance of 60 mm from the middle of the casing.
 g) in relation to the input, including coupling.
 g) h) Motor shaft diameter $\varnothing d$ from $\varnothing 4$ to $\varnothing 19$, calculated at $\varnothing 9 \text{ mm}$.

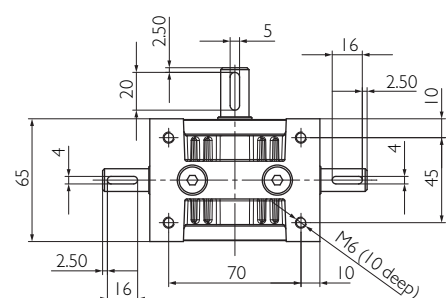
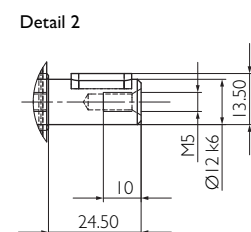
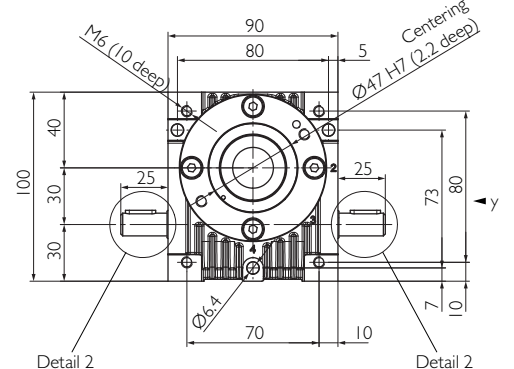
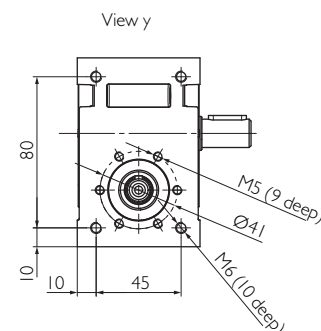
Bearing forces



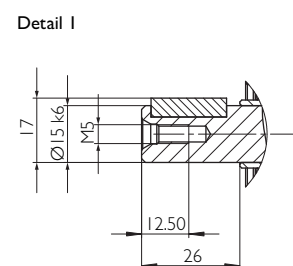
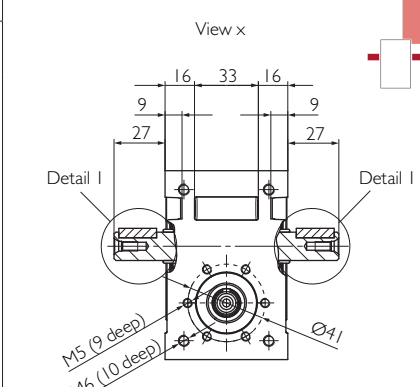
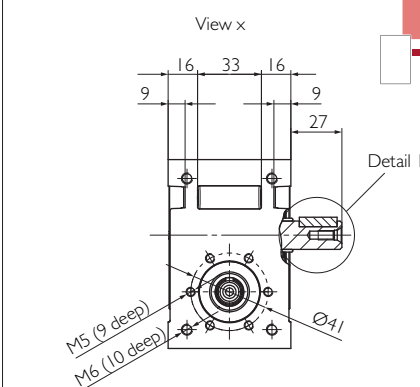
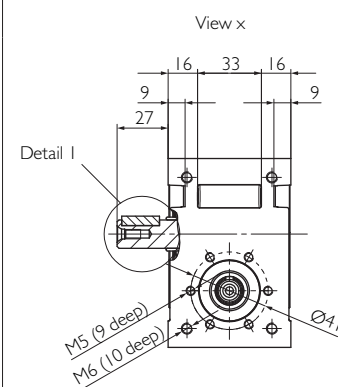


Example HPG 030 C6

D



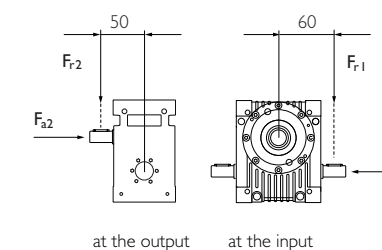
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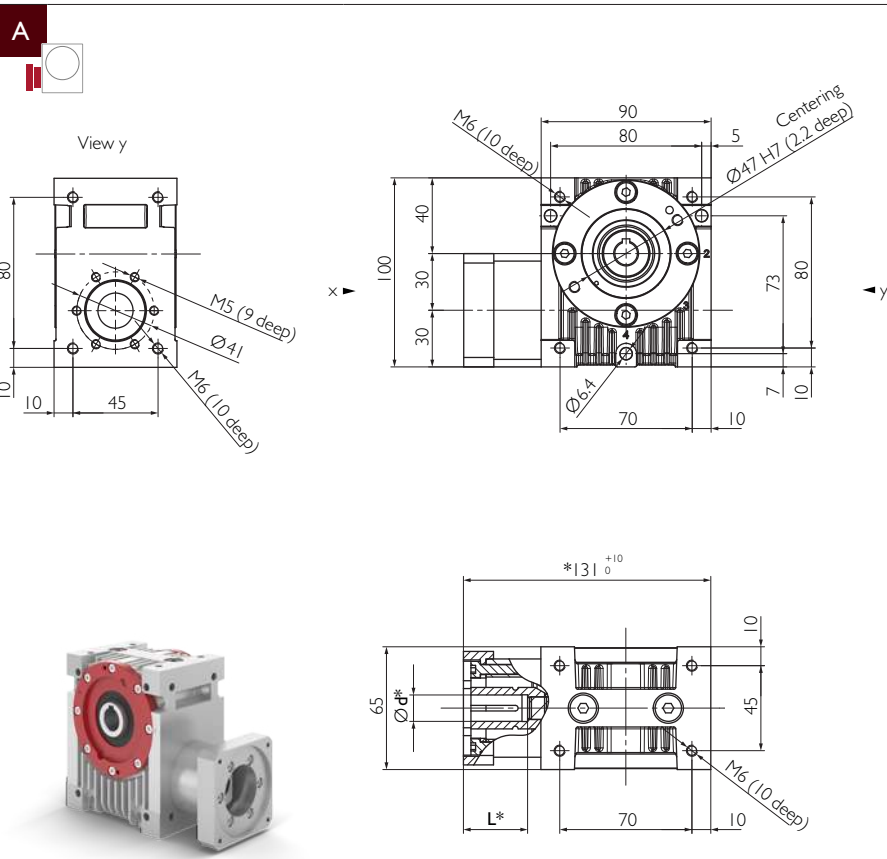
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60		
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	12.9 85	17.9 84	20.1 83	19.2 81	16.9 80	19.4 76	17.9 74	17.5 67	19.5 63	19.0 54	8.6 48	18.8 40	8.6 30		
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	11.3 86	16.0 86	18.3 85	17.5 83	15.5 81	17.9 77	16.6 74	16.2 68	18.1 65	17.6 55	8.6 50	17.5 44	8.6 40		
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	10.0 86	14.4 86	16.7 85	16.2 83	14.3 80	16.6 77	15.4 73	15.1 68	16.9 64	16.4 54	8.6 49	16.3 45	8.6 40		
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	7.4 84	11.2 84	13.3 83	13.1 81	11.7 77	13.7 74	12.8 71	12.6 67	14.0 62	13.7 53	8.6 48	13.6 44	8.6 40		
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	5.9 81	9.2 82	11.0 81	11.0 78	9.9 76	11.6 73	10.9 69	10.8 65	12.0 60	11.8 51	10.0 47	11.7 42	10.0 37		
	n _{1N} = 6000 rpm	T _{2N} η	[Nm] [%]	4.9 79	7.8 79	9.4 78	9.4 77	8.6 75	10.1 72	9.5 68	9.4 62	10.5 56	10.3 47	10.0 42	10.2 37	10.0 33		
Max. acceleration torque		T _{2B}	[Nm]	13	21									10			21	10
Emergency stop torque		T _{2Not}	[Nm]	35									20			35	20	
Idling torque ^{a)}		T ₀₁₂	[Nm]	0.65			0.6			0.5								
Max. input speed		n _{1Max}	[rpm]	6000														
Max. backlash ^{b)} at the output		PS	j _t	[arcmin]	<22	<18	<16	<16	<14	<12				<11				
Torsional rigidity vom Abtrieb zum Eintritt		C _{t21}	[Nm/arcmin]	0.3	0.45	0.58	0.63	0.66	0.68	0.72	0.74	0.78	0.8	0.75	0.85	0.75		
Stability at the output		C _{2K}	[Nm/arcmin]	27														
Max. axial force ^{c)} ^{d)} at the output		F _{a2max}	F _{a2max}	910	1200	1500	1800	2200	2100	2300	2500	2700	2900	3100	2900	3100		
Max. radial force ^{c)} ^{e)} at the output		F _{r2max}	F _{r2max}	640	740	850	970	1100	980	1000	1000	1100	1200	1300	1300	1300		
Max. overturning torque ^{c)} at the output		M _{2max}	M _{2max}	32	37	42	48	54	49	50	52	54	60	67	65	67		
Max. axial force ^{c)} ^{d)} at the input		F _{a1max}	F _{a1max}	890	740	700	780	890	820	890	910	860	880	1100	890	1100		
Max. radial force ^{c)} ^{f)} at the input		F _{r1max}	F _{r1max}	280	270	280	300	320	320	330	340	330	340	360	340	360		
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁷ kg m ²]	230	110	68	49	38	28	23	19	18	16	15	15	15		
Service life		L _h	[h]	25000														
Weight without motor components		m	[kg]	1.7														
Max. permissible housing temperature			[°C]	+90														
Ambient temperature			[°C]	-15 up to +50														
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)																
Painting		None																
Protection class		IP65																

- approximate, at $n_1 = 3000$ rpm and operating temperature.
- Precision grade PS (standard backlash) for classic mechanical engineering applications.
- Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{2}{3} T_{2N}$ and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
- d) in relation to shaft center.
- e) at a distance of 50 mm from the middle of the casing.
- f) at a distance of 60 mm from the middle of the casing.
- g) in relation to the input.

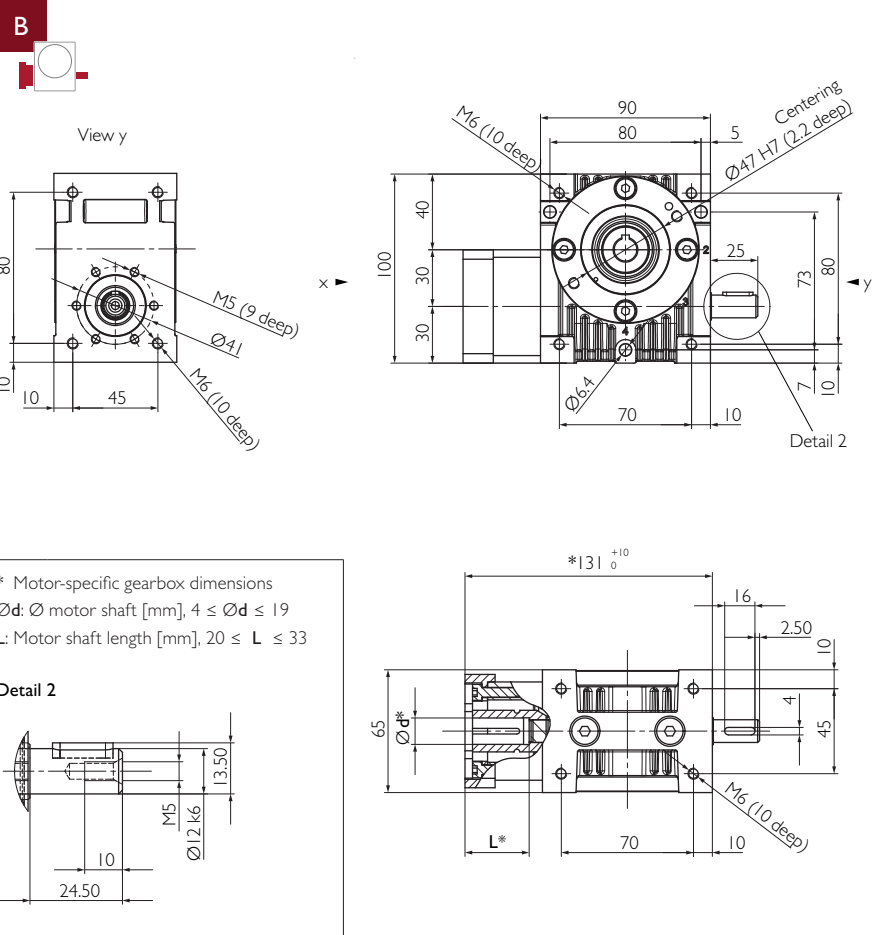
Bearing forces



Input

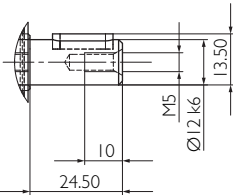


Example HPG 030 A7

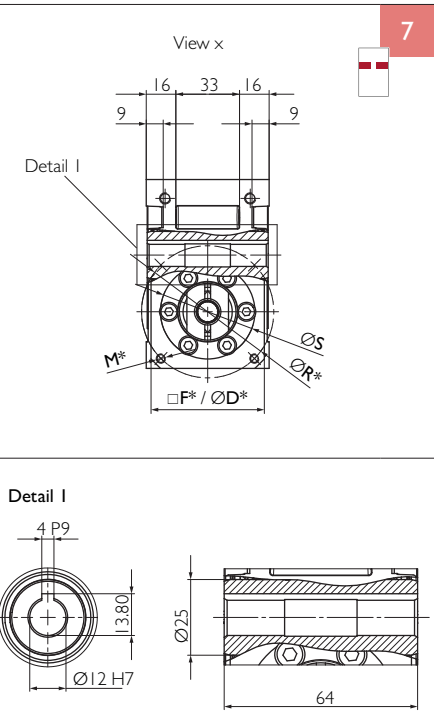


* Motor-specific gearbox dimensions
Ød: Ø motor shaft [mm], 4 ≤ Ød ≤ 19
L: Motor shaft length [mm], 20 ≤ L ≤ 33

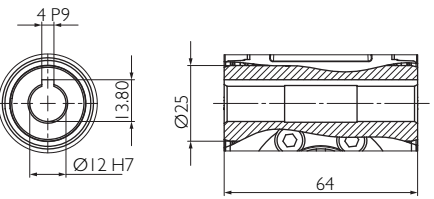
Detail 2



Output



Detail I

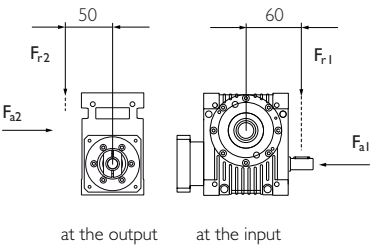


* Motor-specific gearbox dimensions
S: min. 32 [mm], R: Pitch circle Ø [mm], M: Bore hole Ø or thread [mm], □F/ØD: Specify flange [mm]

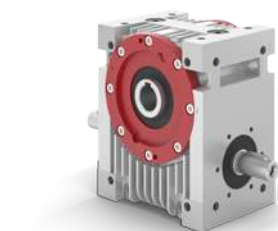
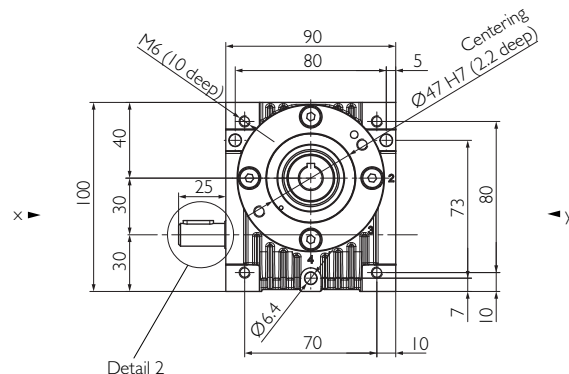
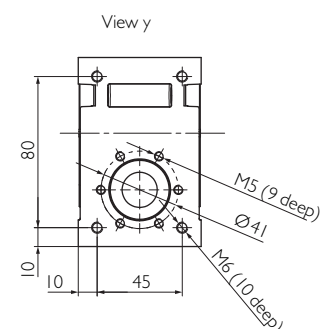
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60	
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	12.9 85	17.9 84	20.1 83	19.2 81	16.9 80	19.4 76	17.9 74	17.5 67	19.5 63	19.0 54	8.6 48	18.8 40	8.6 30	
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	11.3 86	16.0 86	18.3 85	17.5 83	15.5 81	17.9 77	16.6 74	16.2 68	18.1 65	17.6 55	8.6 50	17.5 44	8.6 40	
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	10.0 86	14.4 86	16.7 85	16.2 83	14.3 80	16.6 77	15.4 73	15.1 68	16.9 64	16.4 54	8.6 49	16.3 45	8.6 40	
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	7.4 84	11.2 84	13.3 83	13.1 81	11.7 77	13.7 74	12.8 71	12.6 67	14.0 62	13.7 53	8.6 48	13.6 44	8.6 40	
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	5.9 81	9.2 82	11.0 81	11.0 78	9.9 76	11.6 73	10.9 69	10.8 65	12.0 60	11.8 51	10.0 47	11.7 42	10.0 37	
	n _{1N} = 6000 rpm	T _{2N} η	[Nm] [%]	4.9 79	7.8 79	9.4 78	9.4 77	8.6 75	10.1 72	9.5 68	9.4 62	10.5 56	10.3 47	10.0 42	10.2 37	10.0 33	
Max. acceleration torque		T _{2B}	[Nm]	13	21									10	21	10	
Emergency stop torque		T _{2Not}	[Nm]	35										20	35	20	
Idling torque ^{a)}		T ₀₁₂	[Nm]	0.65				0.6				0.5					
Max. input speed		n _{1Max}	[rpm]	6000													
Max. backlash ^{b)} at the output		PS	j _t	[arcmin]	<22	<18	<16	<16	<14	<12					<11		
Torsional rigidity vom Abtrieb zum Eintrieb		C ₂₁	[Nm/arcmin]	0.3	0.45	0.58	0.63	0.66	0.68	0.72	0.74	0.78	0.8	0.75	0.85	0.75	
Stability at the output		C _{2K}	[Nm/arcmin]	27													
Max. axial force ^{c) d)} at the output		F _{a2max}	[N]	560	770	1000	1300	1600	1600	1700	1900	2000	2400	2700	2600	2700	
Max. radial force ^{c) e)} at the output		F _{r2max}	[N]	510	570	660	770	860	800	810	850	880	990	1100	1100	1100	
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	26	29	33	38	43	40	41	43	44	49	55	53	55	
Max. axial force ^{c) d)} at the input		F _{a1max}	[N]	890	740	700	780	890	820	890	910	860	880	1100	890	1100	
Max. radial force ^{c) f)} at the input		F _{r1max}	[N]	280	270	280	300	320	320	330	340	330	340	360	340	360	
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁷ kg m ²]	252	183	159	148	142	136	133	131	130	129	129	129	129	
Service life		L _h	[h]	25000													
Weight without motor components		m	[kg]	2													
Max. permissible housing temperature			[°C]	+90													
Ambient temperature			[°C]	-15 up to +50													
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)															
Painting		None															
Protection class		IP65															

- a) approximate, at n₁ = 3000 rpm and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
c) Bearing forces: Values valid at n₁ = 3000 rpm; ½ T_{2N} and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 50 mm from the middle of the casing.
c) f) at a distance of 60 mm from the middle of the casing.
g) in relation to the input, including coupling.
g) h) Motor shaft diameter Ød from Ø4 to Ø19, calculated at Ø9mm.

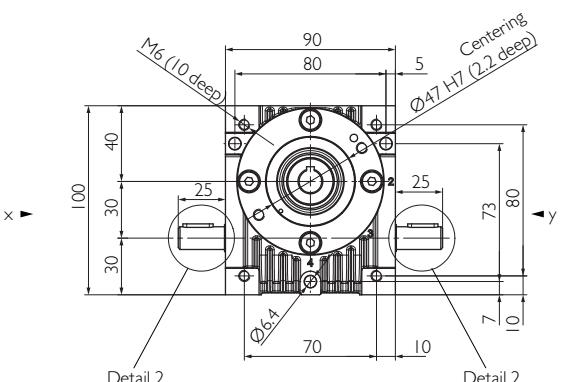
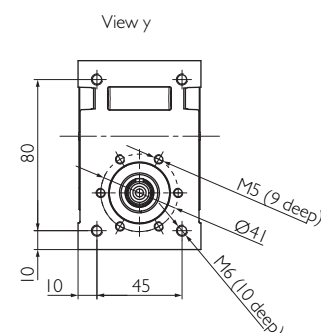
Bearing forces



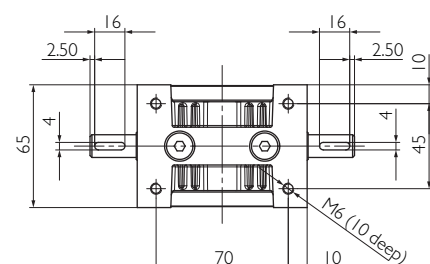
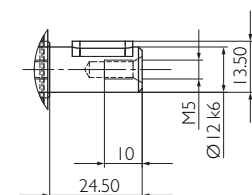
Input



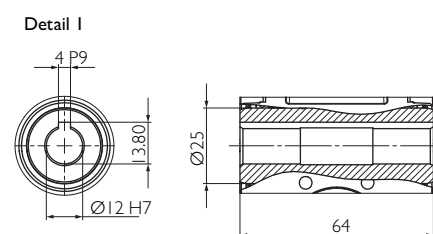
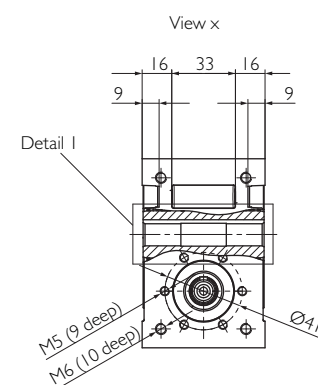
Example HPG 030 C7



Detail 2



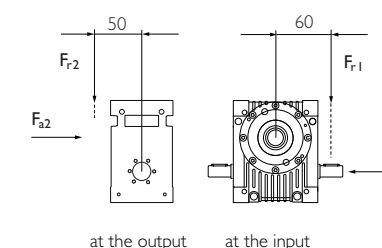
Output



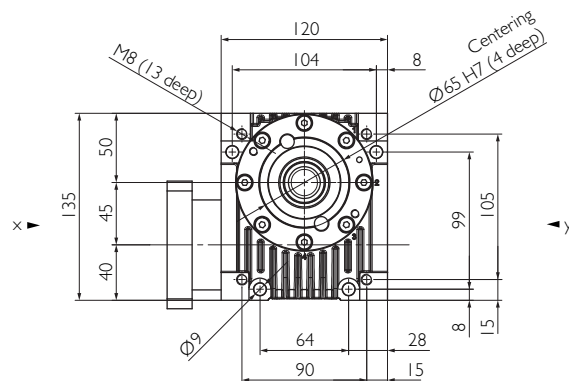
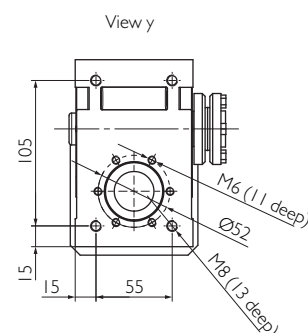
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60		
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	12.9 85	17.9 84	20.1 83	19.2 81	16.9 80	19.4 76	17.9 74	17.5 67	19.5 63	19.0 54	8.6 48	18.8 40	8.6 30		
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	11.3 86	16.0 86	18.3 85	17.5 83	15.5 81	17.9 77	16.6 74	16.2 68	18.1 65	17.6 55	8.6 50	17.5 44	8.6 40		
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	10.0 86	14.4 86	16.7 85	16.2 83	14.3 80	16.6 77	15.4 73	15.1 68	16.9 64	16.4 54	8.6 49	16.3 45	8.6 40		
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	7.4 84	11.2 84	13.3 83	13.1 81	11.7 77	13.7 74	12.8 71	12.6 67	14.0 62	13.7 53	8.6 48	13.6 44	8.6 40		
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	5.9 81	9.2 82	11.0 81	11.0 78	9.9 76	11.6 73	10.9 69	10.8 65	12.0 60	11.8 51	10.0 47	11.7 42	10.0 37		
	n _{1N} = 6000 rpm	T _{2N} η	[Nm] [%]	4.9 79	7.8 79	9.4 78	9.4 77	8.6 75	10.1 72	9.5 68	9.4 62	10.5 56	10.3 47	10.0 42	10.2 37	10.0 33		
Max. acceleration torque		T _{2B}	[Nm]	13	21									10			21	10
Emergency stop torque		T _{2Not}	[Nm]	35									20			35	20	
Idling torque ^{a)}		T ₀₁₂	[Nm]	0.65			0.6			0.5								
Max. input speed		n _{1Max}	[rpm]	6000														
Max. backlash ^{b)} at the output		PS	j _t	[arcmin]	<22	<18	<16	<16	<14	<12				<11				
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	0.3	0.45	0.58	0.63	0.66	0.68	0.72	0.74	0.78	0.8	0.75	0.85	0.75		
Stability at the output		C _{2K}	[Nm/arcmin]	27														
Max. axial force ^{c) d)} at the output		F _{a2max}	[N]	560	770	1000	1300	1600	1600	1700	1900	2000	2400	2700	2600	2700		
Max. radial force ^{c) e)} at the output		F _{r2max}	[N]	510	570	660	770	860	800	810	850	880	990	1100	1100	1100		
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	26	29	33	38	43	40	41	43	44	49	55	53	55		
Max. axial force ^{c) d)} at the input		F _{a1max}	[N]	890	740	700	780	890	820	890	910	860	880	1100	890	1100		
Max. radial force ^{c) f)} at the input		F _{r1max}	[N]	280	270	280	300	320	320	330	340	330	340	360	340	360		
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁷ kg m ²]	138	69	45	34	28	22	19	17	16	15	15	15	15		
Service life		L _h	[h]	25000														
Weight without motor components		m	[kg]	1.6														
Max. permissible housing temperature			[°C]	+90														
Ambient temperature			[°C]	-15 up to +50														
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)																
Painting		None																
Protection class		IP65																

- a) approximate, at $n_1 = 3000$ rpm and operating temperature.
- b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
- c) Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{2}{3} T_{2N}$ and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
- c) d) in relation to shaft center.
- c) e) at a distance of 50 mm from the middle of the casing.
- c) f) at a distance of 60 mm from the middle of the casing.
- g) in relation to the input.

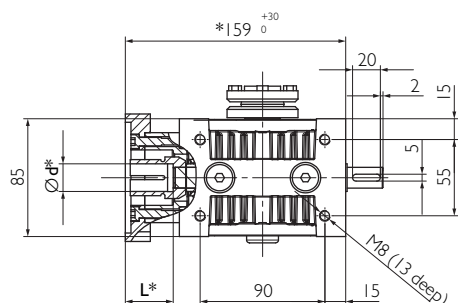
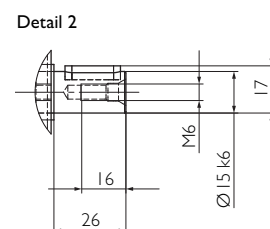
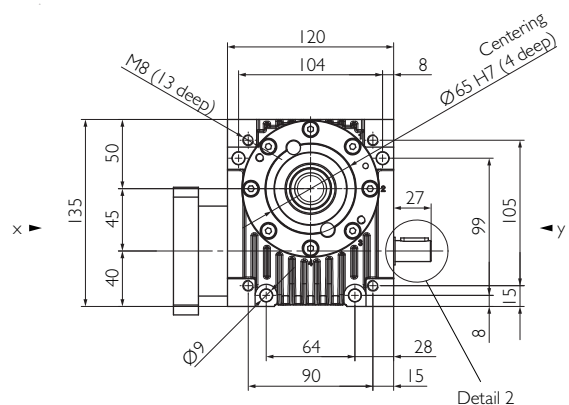
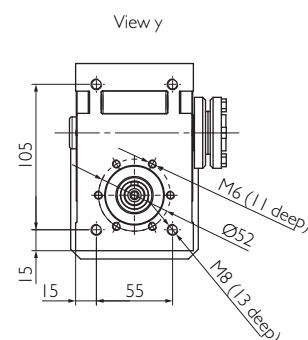
Bearing forces



Input



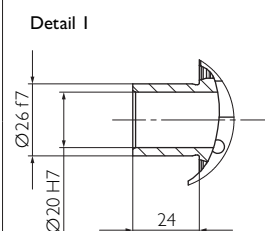
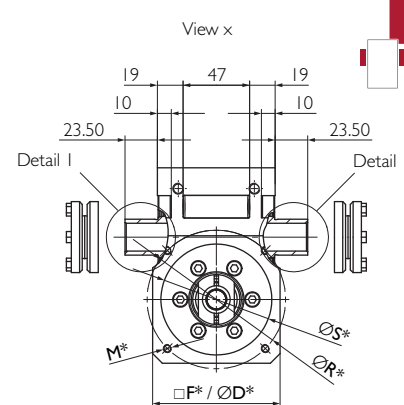
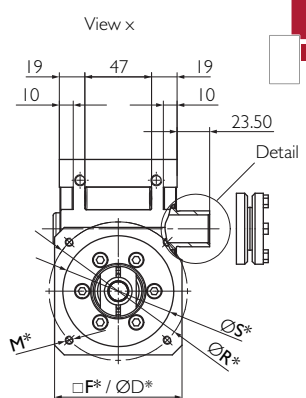
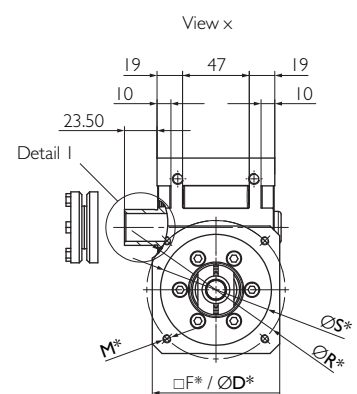
Example HPG 045 A2



* Motor-specific gearbox dimensions
 $\varnothing d$: $\varnothing$ motor shaft [mm], $6 \leq \varnothing d \leq 24$
 L : Motor shaft length [mm], $20 \leq L \leq 53$

Detail 2

Output

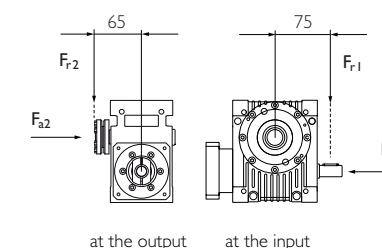


* Motor-specific gearbox dimensions
S: min. 40 [mm], **R:** Pitch circle Ø [mm], **M:** Bore hole Ø or thread [mm], **□F/ØD:** Specify flange [mm]

Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	52.7 88	73.9 88	83.9 87	80.5 86	70.8 85	81.7 82	75.5 79	73.9 75	75.0 71	77.9 63	54.5 59	79.4 50	54.5 43
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	43.8 89	63.3 89	73.1 88	71.0 87	62.9 86	72.9 84	67.7 81	66.4 77	74.0 73	72.2 65	54.5 60	71.5 53	55.5 45
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	37.4 89	55.4 89	64.8 89	63.4 88	56.5 86	65.8 84	61.3 81	60.3 77	67.2 74	65.6 66	55.5 60	65.1 53	55.5 45
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	26.0 88	40.3 89	48.3 88	48.1 87	43.4 85	51.0 83	47.8 80	47.2 75	52.7 72	51.6 64	51.8 58	51.3 52	51.8 45
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	20.0 87	31.6 87	38.5 87	38.7 85	35.2 83	41.6 81	39.2 77	38.8 73	43.3 70	42.5 62	42.7 54	42.3 50	42.7 43
	n _{1N} = 6000 rpm	T _{2N} η	[Nm] [%]	16.2 85	26.0 86	32.0 85	32.4 84	29.6 81	35.2 79	33.2 75	33.0 70	36.8 66	36.1 58	36.4 51	36.0 46	36.4 40
Max. acceleration torque		T _{2B}	[Nm]	60	90									60	90	60
Emergency stop torque		T _{2Not}	[Nm]	120									80	120	80	
Idling torque ^{a)}		T ₀₁₂	[Nm]	1.05			0.95			0.8						
Max. input speed		n _{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<15	<12	<11	<11	<9	<8					<7		
	PR	j _t	[arcmin]	<10	<8	<7	<7	<6	<5.5					<5		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	1.6	2.8	3.6	4	4.3	4.5	4.9	5.3	5.5	5.8	5.5	6	5.5
Stability at the output		C _{2K}	[Nm/arcmin]	30												
Max. axial force ^{c)d)} at the output		F _{a2max}		720	1000	1600	2200	2800	2900	3300	3700	3900	4700	4700	4800	4800
Max. radial force ^{c)e)} at the output		F _{r2max}		700	820	1200	1400	1600	1600	1600	1700	1800	2000	2100	2200	2200
Max. overturning torque ^{c)} at the output		M _{2max}		45	53	76	91	110	100	110	110	110	130	140	140	140
Max. axial force ^{c)d)} at the input		F _{a1max}		1400	980	860	1000	1300	1100	1300	1300	1200	1200	1200	1200	1200
Max. radial force ^{c)f)} at the input		F _{r1max}		510	470	430	510	590	550	610	630	580	610	600	620	600
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁶ kg m ²]	148	84	62	52	46	41	38	36	36	35	34	34	34
	Type 2 ⁱ⁾	J ₁	[10 ⁻⁶ kg m ²]	191	128	106	95	90	84	82	80	79	78	78	77	77
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	4.5												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000$ rpm and operating temperature.
- b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- c) Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{2}{3} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- c) d) in relation to shaft center.
- c) e) at a distance of 65 mm from the middle of the casing.
- c) f) at a distance of 75 mm from the middle of the casing.
- g) in relation to the input, including coupling and shrink disc at the output (output 1 & 2)
with two shrink discs (output 3) increase values by 90/10°.
- g) h) Motor shaft diameter $\varnothing d$ from $\varnothing 6$ to $\varnothing 20$, calculated at $\varnothing 11$ mm.
- g) i) Motor shaft diameter $\varnothing d$ from $\varnothing 21$ to $\varnothing 24$, calculated at $\varnothing 24$ mm.

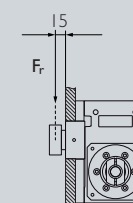
Bearing forces



Package

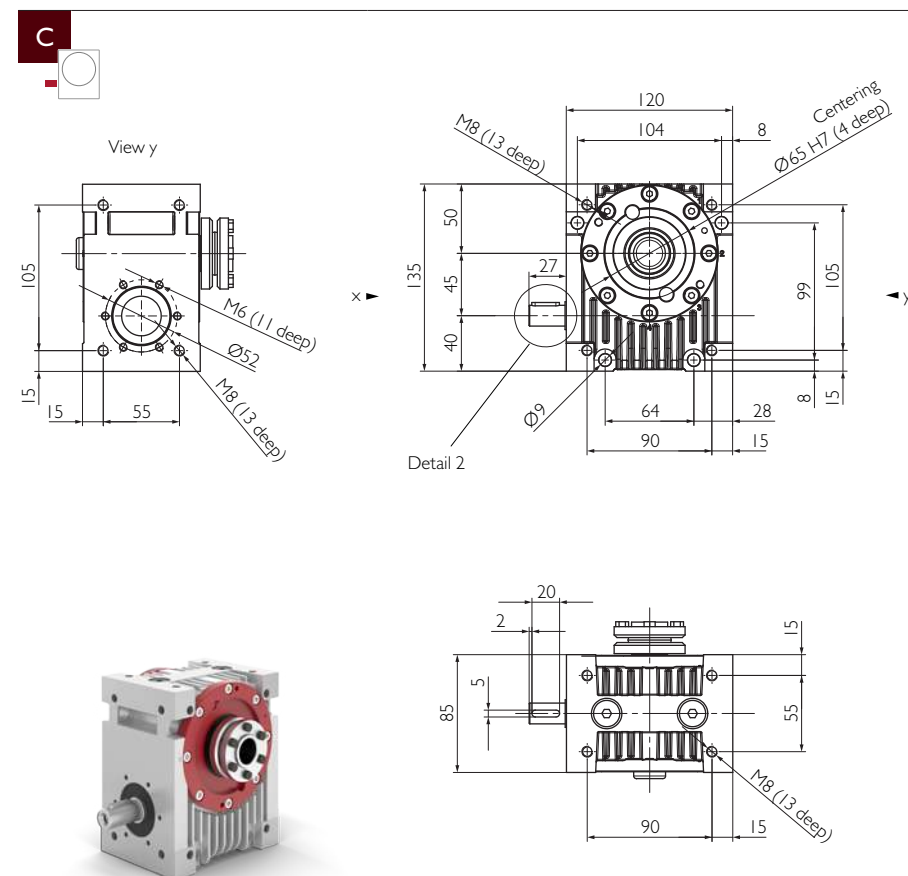
			Output Flange including Bearing & Pinion				
Radial rigidity	C ₃	[N/mm]	23000				
Speed	n _{2N}	[rpm]	1500	750	400	150	100
Max. radial force ¹⁾	F _{rmax}	[N]	1900	2400	2900	3200	3500

- j) Bearing forces: Values valid at duty cycle of 40% at a distance of 15mm from the end of the bearing.

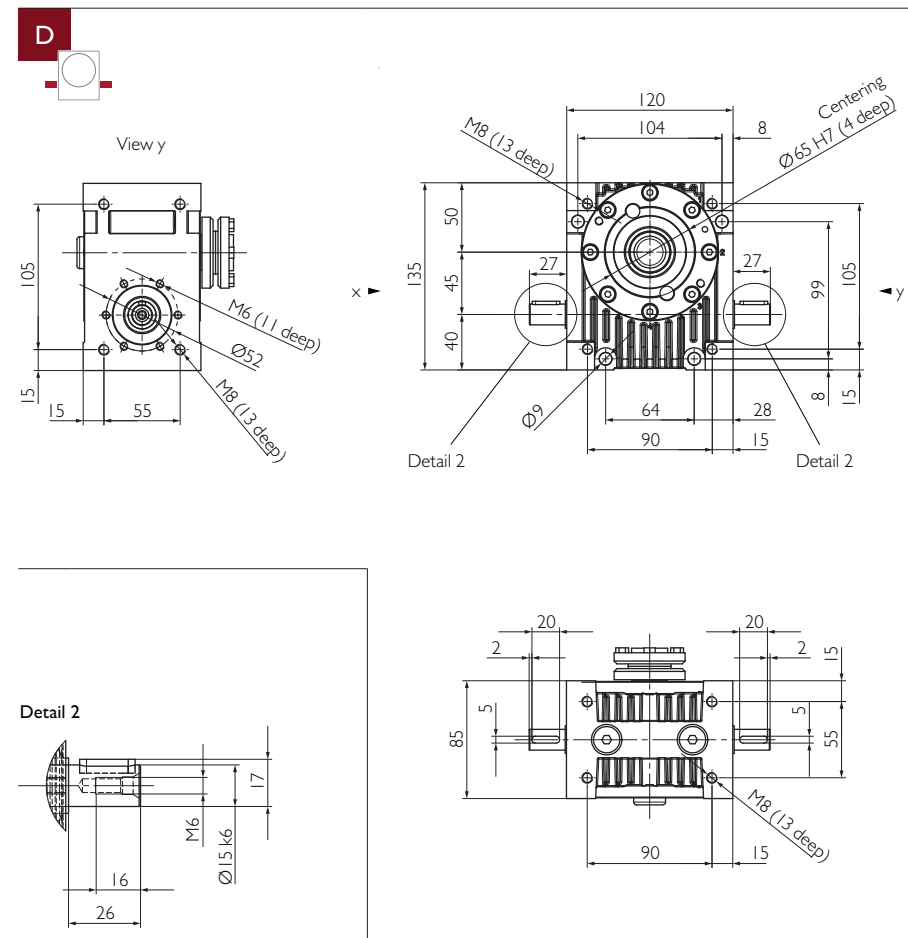


Detailed information about the **Package, Options & Accessories** on pages 46 and 47.

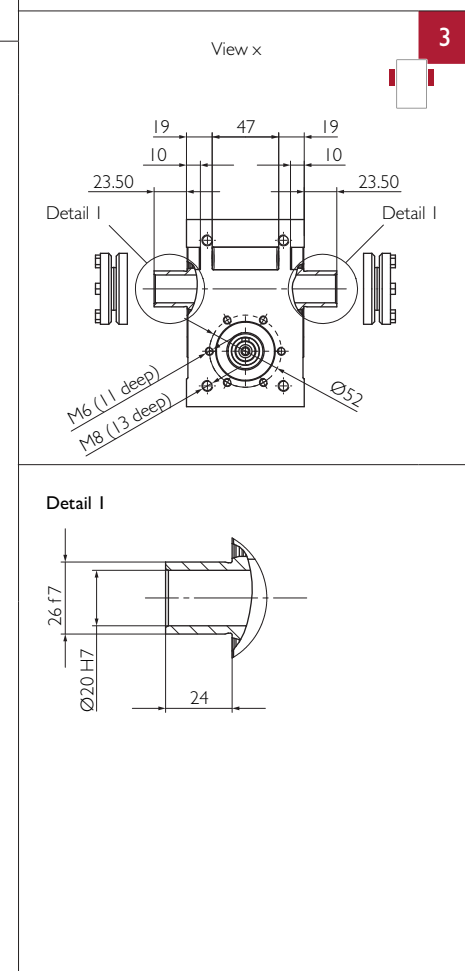
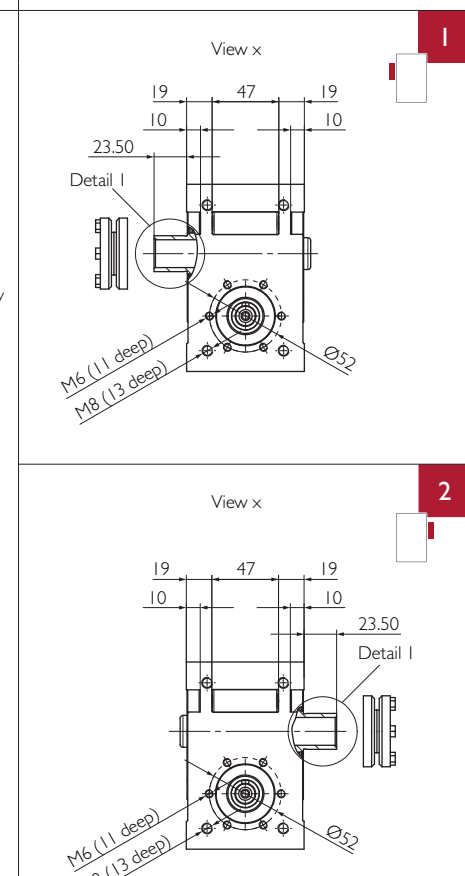
Input



Example HPG 045 C2



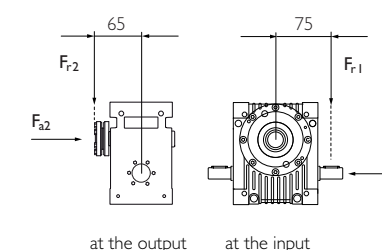
Output



Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N}	[Nm]	52.7	73.9	83.9	80.5	70.8	81.7	75.5	73.9	75.0	77.9	54.5	79.4	54.5
		η	[%]	88	88	87	86	85	82	79	75	71	63	59	50	43
	n _{1N} = 1000 rpm	T _{2N}	[Nm]	43.8	63.3	73.1	71.0	62.9	72.9	67.7	66.4	74.0	72.2	54.5	71.5	55.5
		η	[%]	89	89	88	87	86	84	81	77	73	65	60	53	45
	n _{1N} = 1500 rpm	T _{2N}	[Nm]	37.4	55.4	64.8	63.4	56.5	65.8	61.3	60.3	67.2	65.6	55.5	65.1	55.5
		η	[%]	89	89	89	88	86	84	81	77	74	66	60	53	45
	n _{1N} = 3000 rpm	T _{2N}	[Nm]	26.0	40.3	48.3	48.1	43.4	51.0	47.8	47.2	52.7	51.6	51.8	51.3	51.8
		η	[%]	88	89	88	87	85	83	80	75	72	64	58	52	45
	n _{1N} = 4500 rpm	T _{2N}	[Nm]	20.0	31.6	38.5	38.7	35.2	41.6	39.2	38.8	43.3	42.5	42.7	42.3	42.7
		η	[%]	87	87	87	85	83	81	77	73	70	62	54	50	43
	n _{1N} = 6000 rpm	T _{2N}	[Nm]	16.2	26.0	32.0	32.4	29.6	35.2	33.2	33.0	36.8	36.1	36.4	36.0	36.4
		η	[%]	85	86	85	84	81	79	75	70	66	58	51	46	40
Max. acceleration torque		T _{2B}	[Nm]	60	90									60	90	60
Emergency stop torque		T _{2Not}	[Nm]	120									80	120	80	
Idling torque ^{a)}		T ₀₁₂	[Nm]	1.05				0.95				0.8				
Max. input speed		n _{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<15	<12	<11	<11	<9	<8					<7		
	PR	j _t	[arcmin]	<10	<8	<7	<7	<6	<5.5					<5		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	1.6	2.8	3.6	4	4.3	4.5	4.9	5.3	5.5	5.8	5.5	6	5.5
Stability at the output		C _{2K}	[Nm/arcmin]	30												
Max. axial force ^{c) d)} at the output			[N]	720	1000	1600	2200	2800	2900	3300	3700	3900	4700	4700	4800	4800
Max. radial force ^{c) e)} at the output			[N]	700	820	1200	1400	1600	1600	1600	1700	1800	2000	2100	2200	2200
Max. overturning torque ^{c)} at the output			[Nm]	45	53	76	91	110	100	110	110	110	130	140	140	140
Max. axial force ^{c) d)} at the input			[N]	1400	980	860	1000	1300	1100	1300	1300	1200	1200	1200	1200	1200
Max. radial force ^{c) f)} at the input			[N]	510	470	430	510	590	550	610	630	580	610	600	620	600
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁶ kg m ²]	120	57	34	24	19	13	10	9	8	7	6	6	6
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	4												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000 \text{ rpm}$ and operating temperature.
 b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
 Precision grade PR (reduced backlash) for precise process applications.
 c) Bearing forces: Values valid at $n_1 = 3000 \text{ rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
 Consult with Güdel for composite bearing forces, axial and radial forces.
 c) d) in relation to shaft center.
 c) e) at a distance of 65 mm from the middle of the casing.
 c) f) at a distance of 75 mm from the middle of the casing.
 g) in relations to the input, including shrink disc at the output (output 1 & 2),
 with two shrink discs (output 3) increase values by 90/1°.

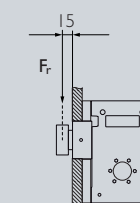
Bearing forces



Package

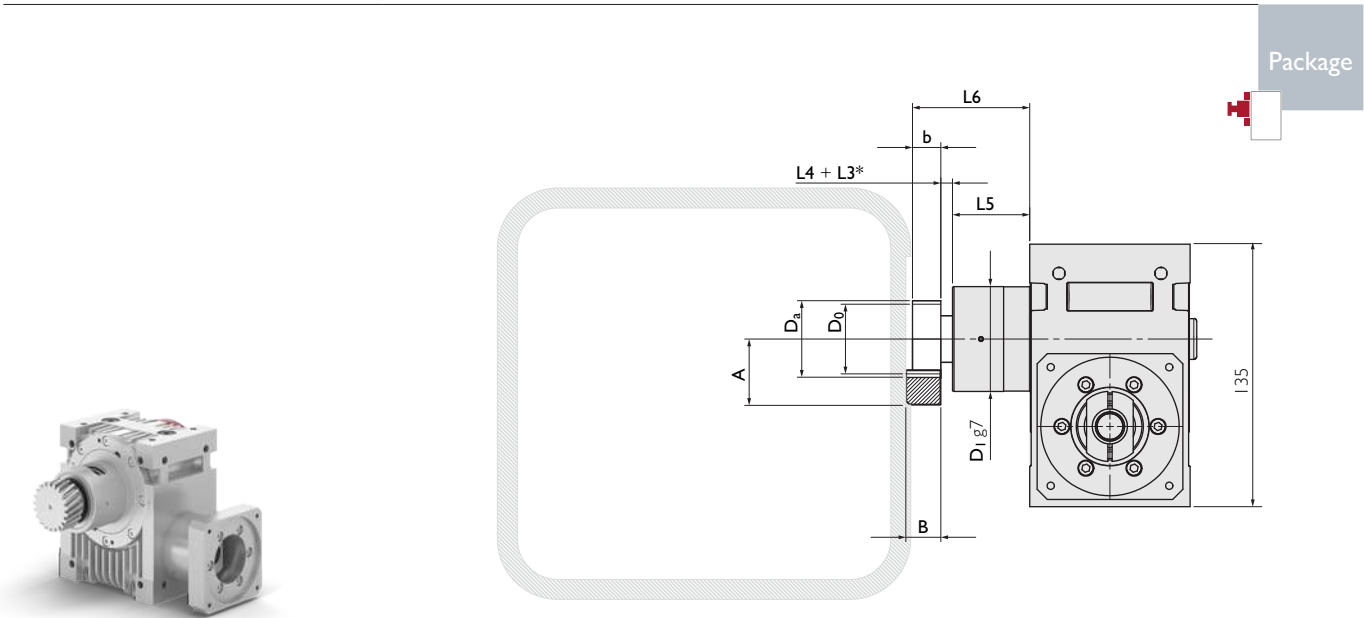
		Output Flange including Bearing & Pinion					
Radial rigidity	C ₃	[N/mm]	23000				
Speed	n _{2N}	[rpm]	1500	750	400	150	100
Max. radial force ¹⁾	F _{rmax}	[N]	1900	2400	2900	3200	3500

- j) Bearing forces: Values valid at duty cycle of 40% at a distance of 15mm from the end of the bearing.

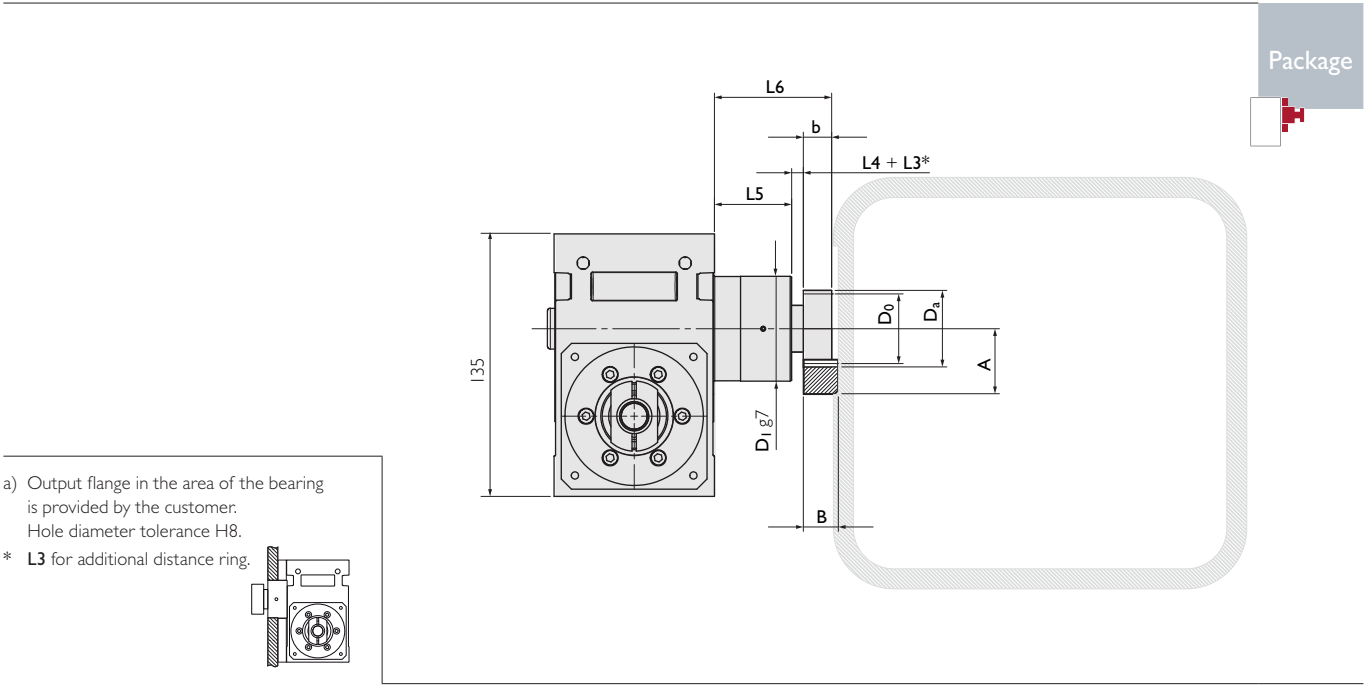


Detailed information about the Package, Options & Accessories on pages 46 and 47.

Output Flange including Bearing & Pinion^{a)}



Example HPG 045 A1 Package



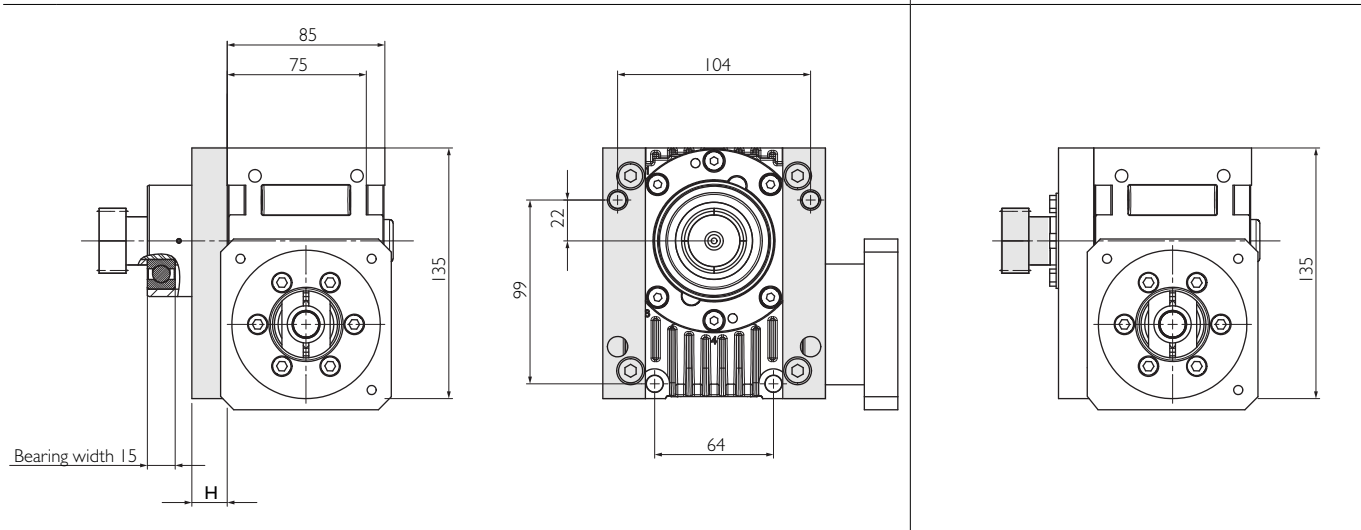
a) Output flange in the area of the bearing is provided by the customer. Hole diameter tolerance H8.
* L3 for additional distance ring.

Geometric information

Helical modular pitch	Art. Nr.	m	z	A	b	B	D _a	D ₀	D _I	L4	L5	L6
Pinion 1	211120	1.5	20	33.415	20	19	34.83	31.83	60	4.5	43	67.5
											53	77.5
Pinion 2	211216	2	16	39.575	20	24	39.15	35.15	60	8	43	71
											53	81
Straight modular pitch	Art. Nr.	m	z	A	b	B	D _a	D ₀	D _I	L4	L5	L6
Pinion 3	201120	1.5	20	32.5	20	19	33.0	30.0	60	4.5	43	67.5
											53	77.5
Pinion 4	201216	2	16	38.6	20	24	37.2	33.2	60	8	43	71
											53	81

Spacer Elements

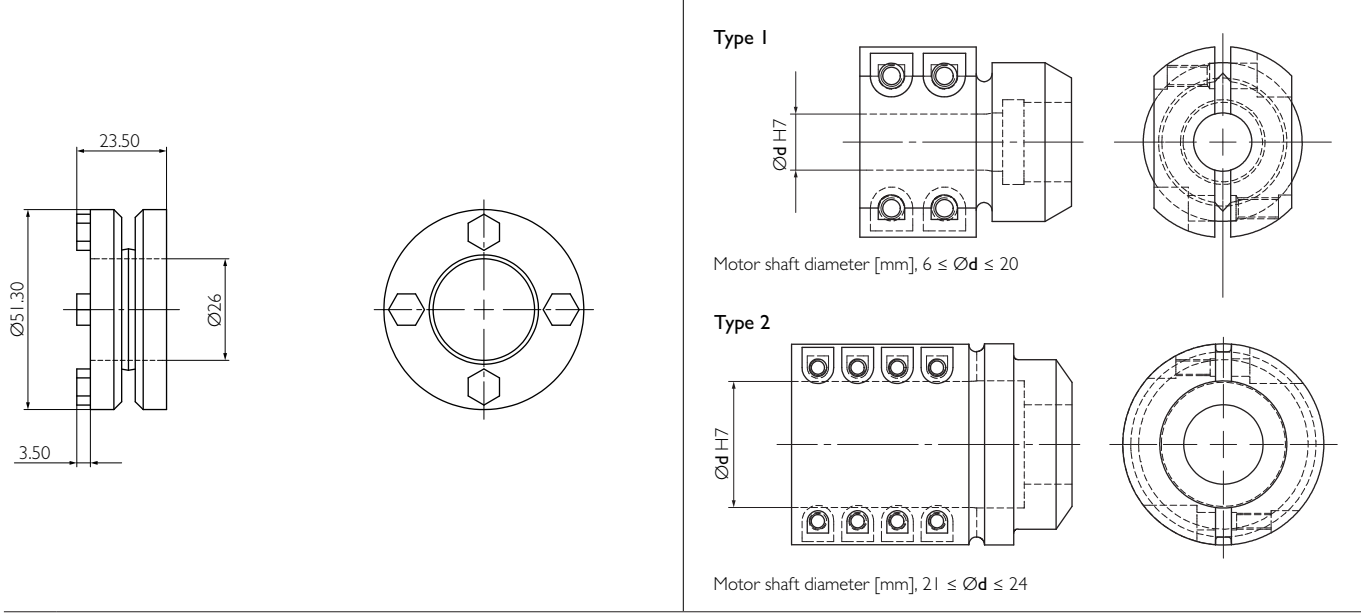
with Pinion special solutions on request



Casing can only be fastened with long screws as per the bore hole pattern. Screws M8 of length 75mm + H + thread depth, tightening torque 22Nm.

Shrink Disc

Coupling

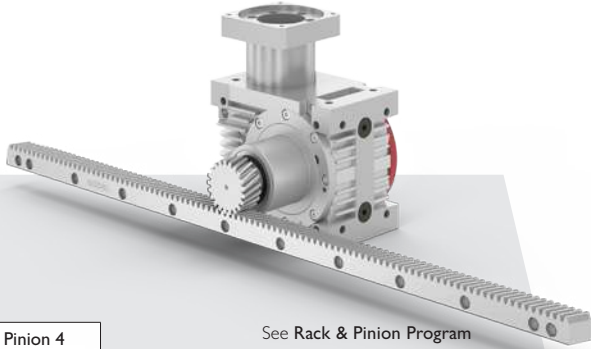


Your ideal Drive Train

Our Function Package with high-performance angle gearbox, output flange, pinion and rack by Güdel.

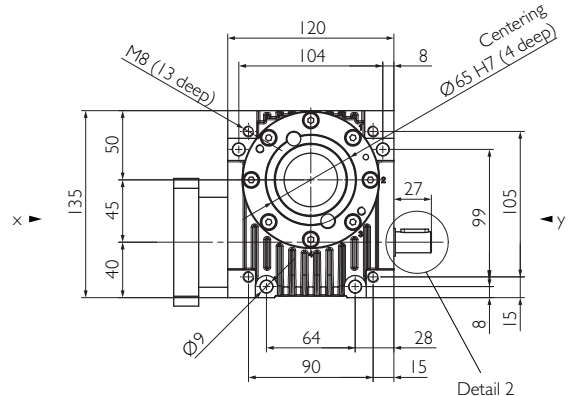
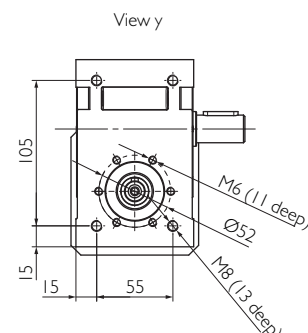
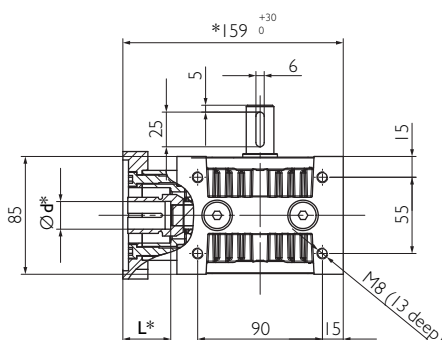
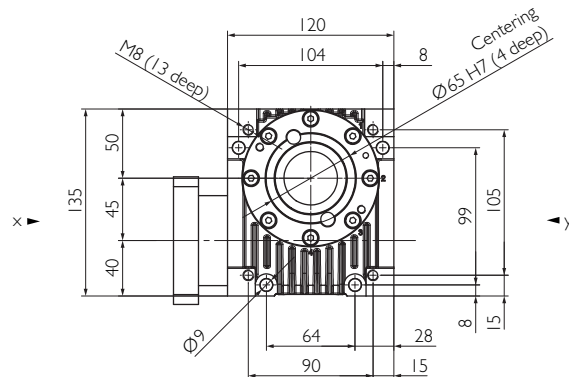
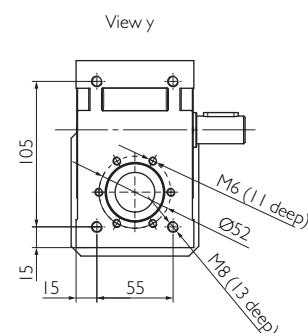
			Pinion 1	Pinion 2	Pinion 3	Pinion 4
Maximum acceleration force	F _N	[N]	4237	5417	3638	4810
Maximum acceleration torque	T _N	[Nm]	67	92	55	77

Higher value for rack and pinion taking account of the number of load cycles: 1x10⁶ for the rack; 1x10⁷ for the pinion. Both in cycle mode.

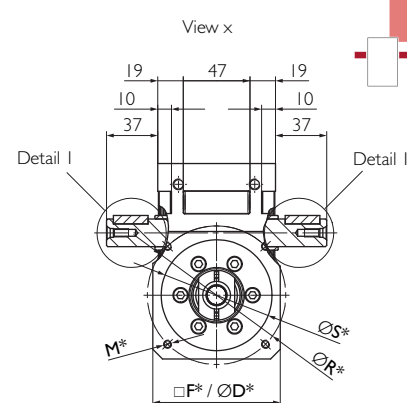
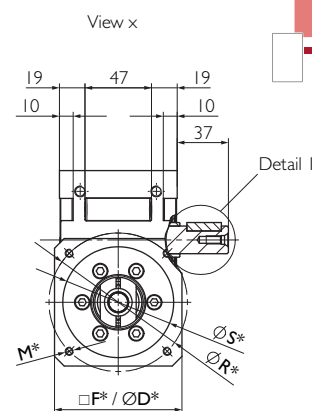
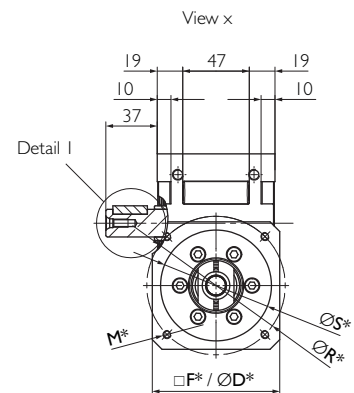
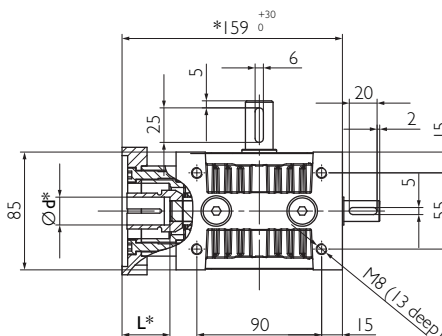
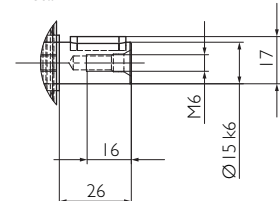


See **Rack & Pinion Program** of your ideal Drive Train on pages 104 et seq.

See **Flowcharts** to find your ideal Drive Train on pages 116 et seq.



Detail 2



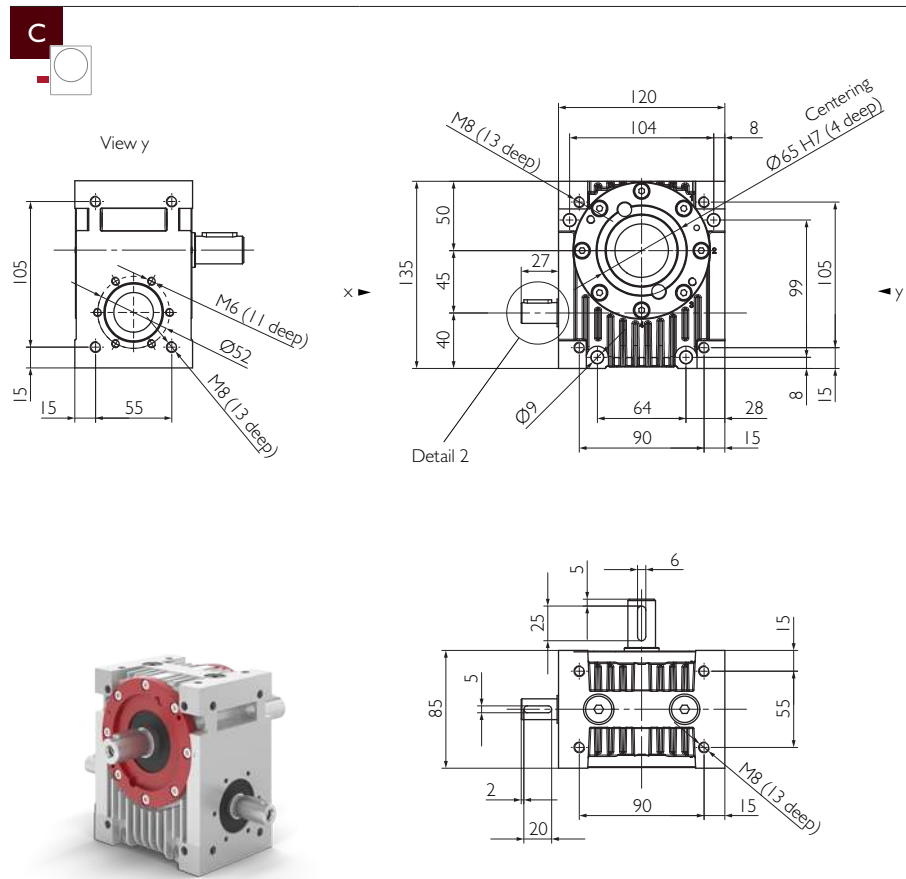
Technical drawing of a mechanical assembly showing a shaft with a key and a pulley. Dimensions include 22.50, Ø20 k6, M6, 16, and 35.

* Motor-specific gearbox dimensions
S: min. 40 [mm], R: Pitch circle Ø [mm], M: Bore hole Ø or thread [mm], □F/ØD: Specify flange [mm]

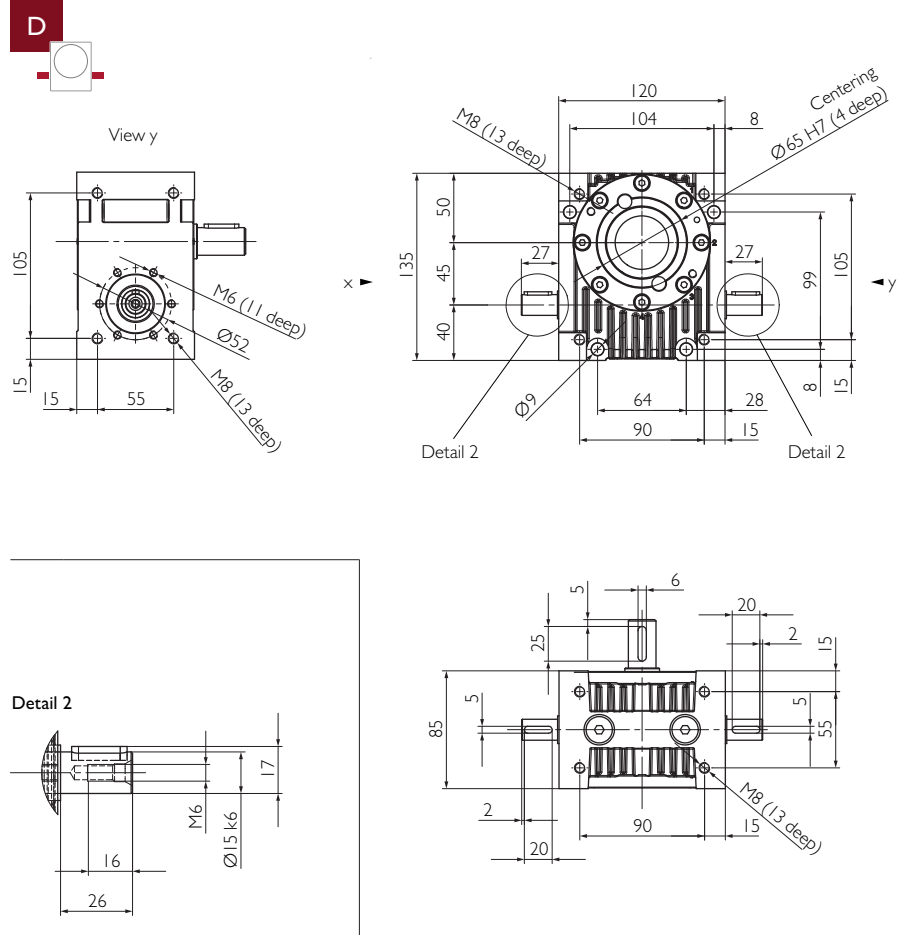
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	52.7 88	73.9 88	83.9 87	80.5 86	70.8 85	81.7 82	75.5 79	73.9 75	75.0 71	77.9 63	54.5 59	79.4 50	54.5 43
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	43.8 89	63.3 89	73.1 88	71.0 87	62.9 86	72.9 84	67.7 81	66.4 77	74.0 73	72.2 65	54.5 60	71.5 53	55.5 45
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	37.4 89	55.4 89	64.8 89	63.4 88	56.5 86	65.8 84	61.3 81	60.3 77	67.2 74	65.6 66	55.5 60	65.1 53	55.5 45
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	26.0 88	40.3 89	48.3 88	48.1 87	43.4 85	51.0 83	47.8 80	47.2 75	52.7 72	51.6 64	51.8 58	51.3 52	51.8 45
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	20.0 87	31.6 87	38.5 87	38.7 85	35.2 83	41.6 81	39.2 77	38.8 73	43.3 70	42.5 62	42.7 54	42.3 50	42.7 43
	n _{1N} = 6000 rpm	T _{2N} η	[Nm] [%]	16.2 85	26.0 86	32.0 85	32.4 84	29.6 81	35.2 79	33.2 75	33.0 70	36.8 66	36.1 58	36.4 51	36.0 46	36.4 40
Max. acceleration torque		T _{2B}	[Nm]	60	90									60	90	60
Emergency stop torque		T _{2Not}	[Nm]	120									80	120	80	
Idling torque ^{a)}		T ₀₁₂	[Nm]	1.05			0.95			0.8						
Max. input speed		n _{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<15	<12	<11	<11	<9	<8					<7		
	PR	j _t	[arcmin]	<10	<8	<7	<7	<6	<5.5					<5		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	1.6	2.8	3.6	4	4.3	4.5	4.9	5.3	5.5	5.8	5.5	6	5.5
Stability at the output		C _{2K}	[Nm/arcmin]	30												
Max. axial force ^{c)d)} at the output			[N]	720	1000	1600	2200	2800	2900	3300	3700	3900	4700	4700	4800	4800
Max. radial force ^{c)e)} at the output			[N]	700	820	1200	1400	1600	1600	1600	1700	1800	2000	2100	2200	2200
Max. overturning torque ^{c)} at the output			[Nm]	45	53	76	91	110	100	110	110	110	130	140	140	140
Max. axial force ^{c)d)} at the input			[N]	1400	980	860	1000	1300	1100	1300	1300	1200	1200	1200	1200	1200
Max. radial force ^{c)f)} at the input			[N]	510	470	430	510	590	550	610	630	580	610	600	620	600
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁶ kg m ²]	148	84	62	52	46	41	38	36	36	35	34	34	34
	Type 2 ⁱ⁾	J ₁	[10 ⁻⁶ kg m ²]	191	128	106	95	90	84	82	80	79	78	78	77	77
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	4.5												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- approximate, at $n_1 = 3000$ rpm and operating temperature.
- Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{3}{4} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- d) in relation to shaft center.
- e) at a distance of 65 mm from the middle of the casing.
- f) at a distance of 75 mm from the middle of the casing.
- g) in relation to the input, including coupling.
- h) Motor shaft diameter $\varnothing d$ from $\varnothing 6$ to $\varnothing 20$, calculated at $\varnothing 11$ mm.
- i) Motor shaft diameter $\varnothing d$ from $\varnothing 21$ to $\varnothing 24$, calculated at $\varnothing 24$ mm.

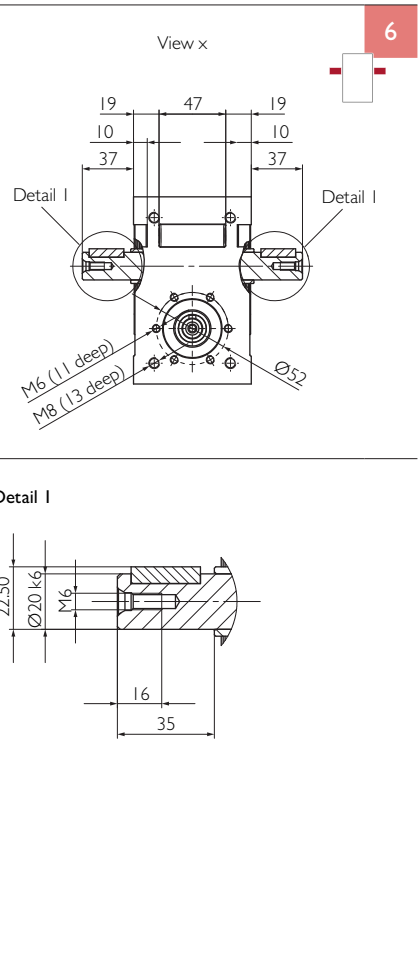
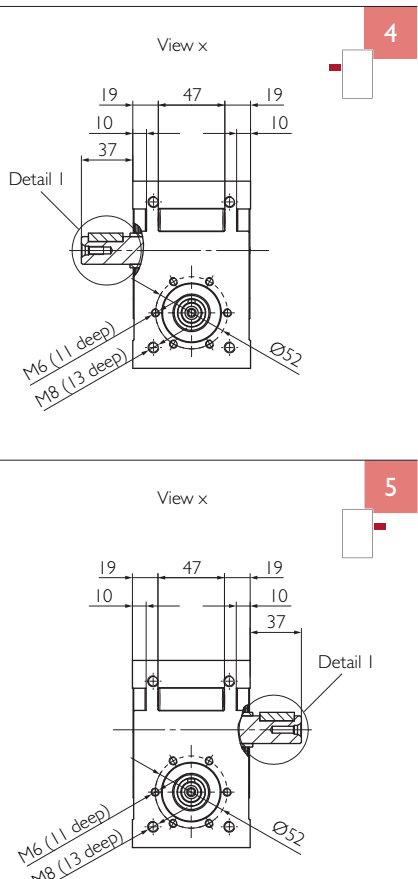
Input



Example HPG 045 D6



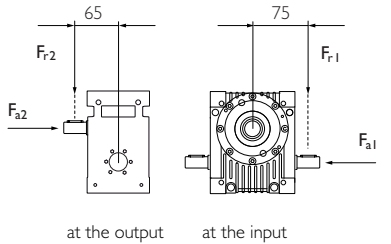
Output



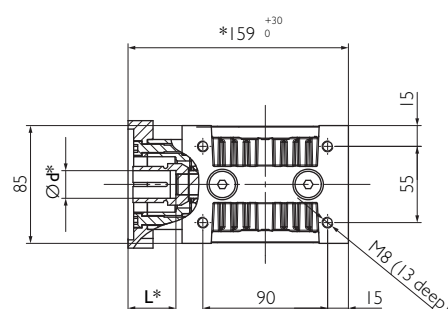
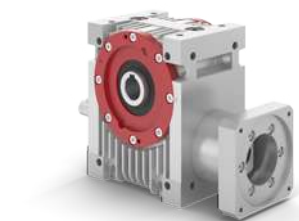
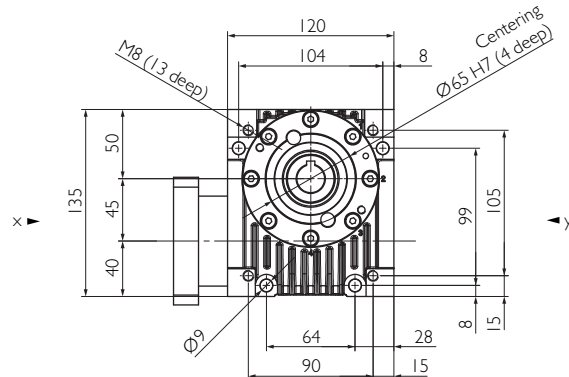
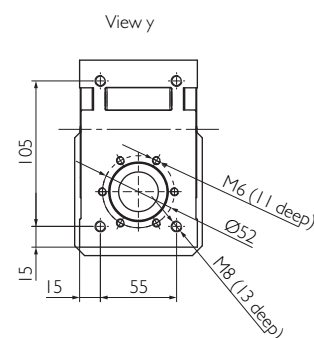
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	$n_{1N} = 500 \text{ rpm}$	T_{2N} η	[Nm] [%]	52.7 88	73.9 88	83.9 87	80.5 86	70.8 85	81.7 82	75.5 79	73.9 75	75.0 71	77.9 63	54.5 59	54.5 50	54.5 43
	$n_{1N} = 1000 \text{ rpm}$	T_{2N} η	[Nm] [%]	43.8 89	63.3 89	73.1 88	71.0 87	62.9 86	72.9 84	67.7 81	66.4 77	74.0 73	72.2 65	54.5 60	71.5 53	55.5 45
	$n_{1N} = 1500 \text{ rpm}$	T_{2N} η	[Nm] [%]	37.4 89	55.4 89	64.8 89	63.4 88	56.5 86	65.8 84	61.3 81	60.3 77	67.2 74	65.6 66	55.5 60	65.1 53	55.5 45
	$n_{1N} = 3000 \text{ rpm}$	T_{2N} η	[Nm] [%]	26.0 88	40.3 89	48.3 88	48.1 87	43.4 85	51.0 83	47.8 80	47.2 75	52.7 72	51.6 64	51.8 58	51.3 52	51.8 45
	$n_{1N} = 4500 \text{ rpm}$	T_{2N} η	[Nm] [%]	20.0 87	31.6 87	38.5 87	38.7 85	35.2 83	41.6 81	39.2 77	38.8 73	43.3 70	42.5 62	42.7 54	42.3 50	42.7 43
	$n_{1N} = 6000 \text{ rpm}$	T_{2N} η	[Nm] [%]	16.2 85	26.0 86	32.0 85	32.4 84	29.6 81	35.2 79	33.2 75	33.0 70	36.8 66	36.1 58	36.4 51	36.0 46	36.4 40
Max. acceleration torque		T_{2B}	[Nm]	60	90									60	90	60
Emergency stop torque		T_{2Not}	[Nm]	120										80	120	80
Idling torque ^{a)}		T_{012}	[Nm]	1.05			0.95				0.8					
Max. input speed		n_{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output	PS	j_k	[arcmin]	<15	<12	<11	<11	<9	<8					<7		
	PR	j_k	[arcmin]	<10	<8	<7	<7	<6	<5.5					<5		
Torsional rigidity vom Abtrieb zum Eintrieb		C_{21}	[Nm/arcmin]	1.6	2.8	3.6	4	4.3	4.5	4.9	5.3	5.5	5.8	5.5	6	5.5
Stability at the output		C_{2K}	[Nm/arcmin]	30												
Max. axial force ^{c) d)} at the output			[N]	720	1000	1600	2200	2800	2900	3300	3700	3900	4700	4700	4800	4800
Max. radial force ^{c) e)} at the output			[N]	700	820	1200	1400	1600	1600	1600	1700	1800	2000	2100	2200	2200
Max. overturning torque ^{c)} at the output			[Nm]	45	53	76	91	110	100	110	110	110	130	140	140	140
Max. axial force ^{c) d)} at the input			[N]	1400	980	860	1000	1300	1100	1300	1300	1200	1200	1200	1200	1200
Max. radial force ^{c) f)} at the input			[N]	510	470	430	510	590	550	610	630	580	610	600	620	600
Mass moment of inertia ^{g)}		J_1	[10 ⁻⁶ kg m ²]	120	57	34	24	19	13	10	9	8	7	6	6	6
Service life		L_h	[h]	25000												
Weight without motor components		m	[kg]	4												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000 \text{ rpm}$ and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
c) Bearing forces: Values valid at $n_1 = 3000 \text{ rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 65 mm from the middle of the casing.
c) f) at a distance of 75 mm from the middle of the casing.
g) in relation to the input.

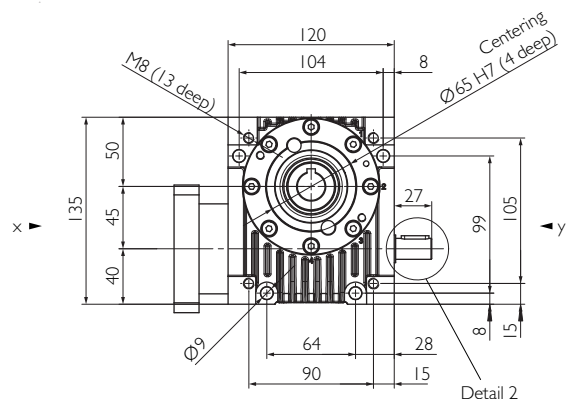
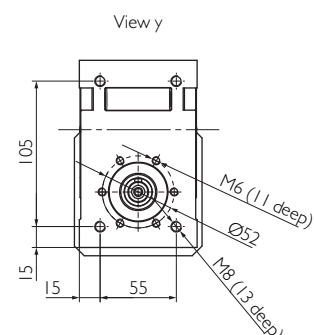
Bearing forces



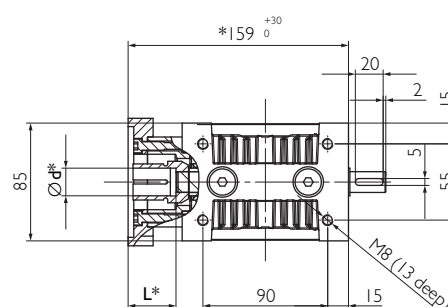
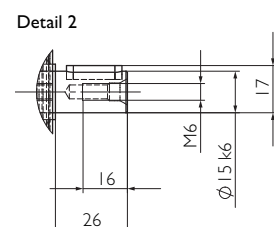
Input



Example HPG 045 B7

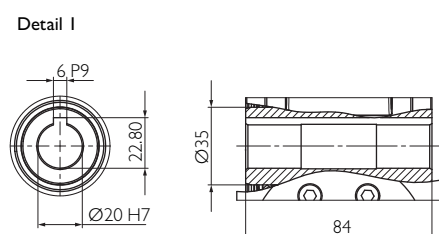
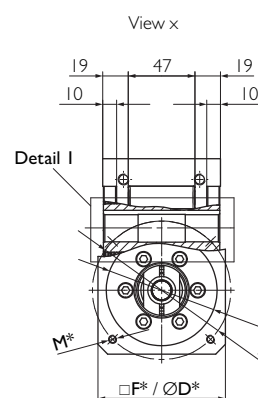


* Motor-specific gearbox dimensions
 $\varnothing d$: $\varnothing$ motor shaft [mm], $6 \leq \varnothing d \leq 24$
 L : Motor shaft length [mm], $20 \leq L \leq 53$



* Motor-specific gearbox dimensions
S: min. 40 [mm], **R:** Pitch circle Ø [mm], **M:** Bore hole Ø or thread [mm], **□F/ØD:** Specify flange [mm]

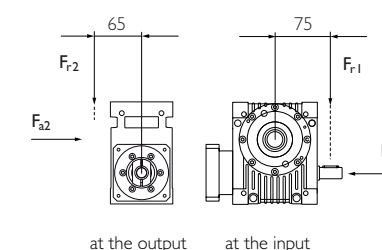
Output



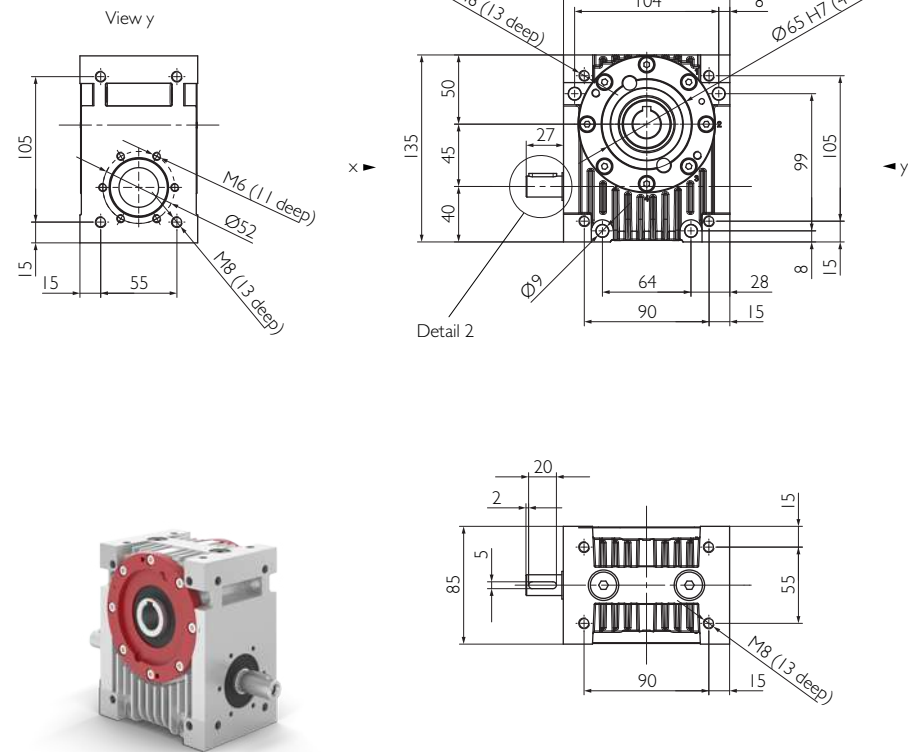
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N}	[Nm]	52.7	73.9	83.9	80.5	70.8	81.7	75.5	73.9	75.0	77.9	54.5	79.4	54.5
		η	[%]	88	88	87	86	85	82	79	75	71	63	59	50	43
	n _{1N} = 1000 rpm	T _{2N}	[Nm]	43.8	63.3	73.1	71.0	62.9	72.9	67.7	66.4	74.0	72.2	54.5	71.5	55.5
		η	[%]	89	89	88	87	86	84	81	77	73	65	60	53	45
	n _{1N} = 1500 rpm	T _{2N}	[Nm]	37.4	55.4	64.8	63.4	56.5	65.8	61.3	60.3	67.2	65.6	55.5	65.1	55.5
		η	[%]	89	89	89	88	86	84	81	77	74	66	60	53	45
	n _{1N} = 3000 rpm	T _{2N}	[Nm]	26.0	40.3	48.3	48.1	43.4	51.0	47.8	47.2	52.7	51.6	51.8	51.3	51.8
		η	[%]	88	89	88	87	85	83	80	75	72	64	58	52	45
	n _{1N} = 4500 rpm	T _{2N}	[Nm]	20.0	31.6	38.5	38.7	35.2	41.6	39.2	38.8	43.3	42.5	42.7	42.3	42.7
		η	[%]	87	87	87	85	83	81	77	73	70	62	54	50	43
	n _{1N} = 6000 rpm	T _{2N}	[Nm]	16.2	26.0	32.0	32.4	29.6	35.2	33.2	33.0	36.8	36.1	36.4	36.0	36.4
		η	[%]	85	86	85	84	81	79	75	70	66	58	51	46	40
Max. acceleration torque		T _{2B}	[Nm]	60	90									60	90	60
Emergency stop torque		T _{2Not}	[Nm]	120									80	120	80	
Idling torque ^{a)}		T ₀₁₂	[Nm]	1.05			0.95			0.8						
Max. input speed		n _{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output	PS	j _k	[arcmin]	<15	<12	<11	<11	<9	<8					<7		
	PR	j _k	[arcmin]	<10	<8	<7	<7	<6	<5.5					<5		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	1.6	2.8	3.6	4	4.3	4.5	4.9	5.3	5.5	5.8	5.5	6	5.5
Stability at the output		C _{2K}	[Nm/arcmin]	30												
Max. axial force ^{c)} ^{d)} at the output			[N]	360	600	1100	1600	2200	2400	2700	3100	3200	4000	4300	4400	4400
Max. radial force ^{c)} ^{e)} at the output			[N]	370	580	780	1200	1400	1400	1400	1500	1500	1700	1900	1900	1900
Max. overturning torque ^{c)} at the output			[Nm]	24	38	51	75	89	88	91	96	98	110	120	120	120
Max. axial force ^{c)} ^{d)} at the input			[N]	1400	980	860	1000	1300	1100	1300	1300	1200	1200	1200	1200	1200
Max. radial force ^{c)} ^{f)} at the input			[N]	510	470	430	510	590	550	610	630	580	610	600	620	600
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁶ kg m ²]	125	74	57	48	44	39	37	36	35	34	34	34	34
	Type 2 ⁱ⁾	J ₁	[10 ⁻⁶ kg m ²]	168	118	100	92	87	83	81	79	79	78	78	77	77
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	4.5												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000$ rpm and operating temperature.
- b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- c) Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{2}{3} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- c) d) in relation to shaft center.
- c) e) at a distance of 65 mm from the middle of the casing.
- c) f) at a distance of 75 mm from the middle of the casing.
- g) in relation to the input, including coupling.
- g) h) Motor shaft diameter $\varnothing d$ from $\varnothing 6$ to $\varnothing 20$, calculated at $\varnothing 11$ mm.
- g) i) Motor shaft diameter $\varnothing d$ from $\varnothing 21$ to $\varnothing 24$, calculated at $\varnothing 24$ mm.

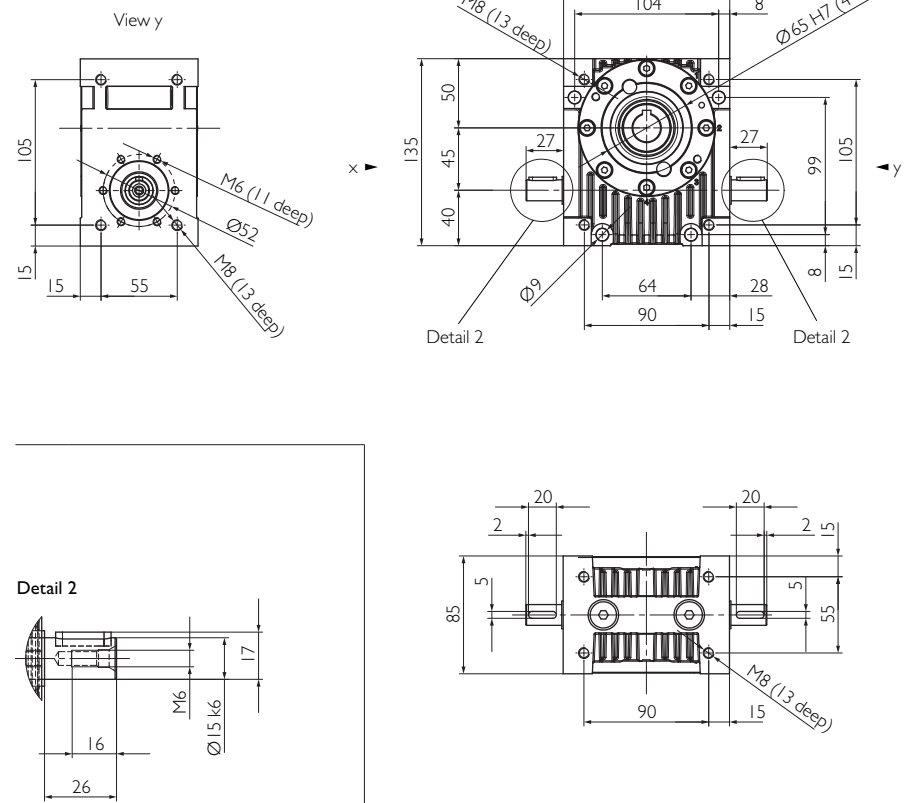
Bearing forces



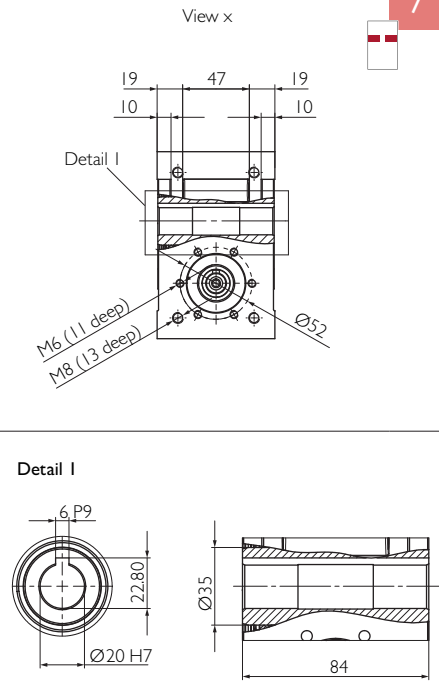
Input



Example HPG 045 D7



Output



HPG | 045 C7 D7

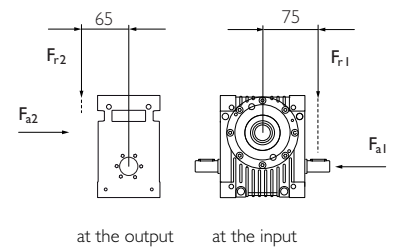
High Performance Angle Gearboxes

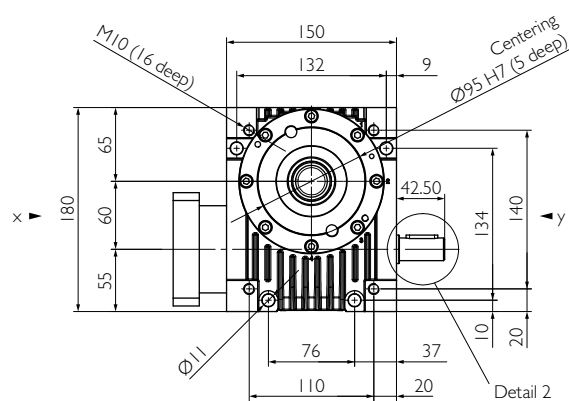
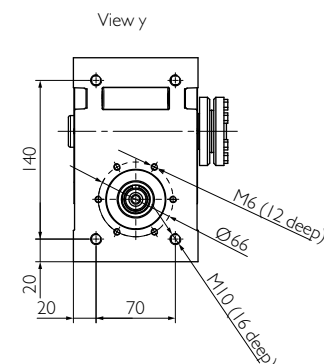
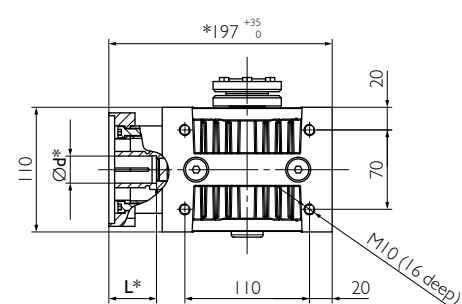
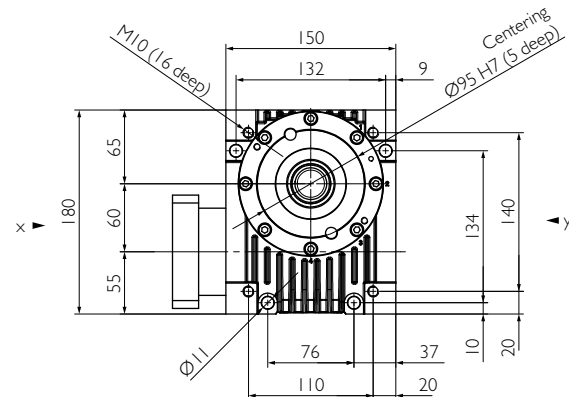
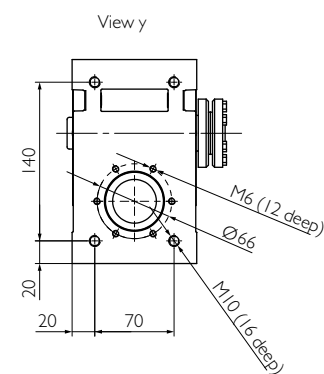
Performance

Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	52.7 88	73.9 88	83.9 87	80.5 86	70.8 85	81.7 82	75.5 79	73.9 75	75.0 71	77.9 63	54.5 59	79.4 50	54.5 43
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	43.8 89	63.3 89	73.1 88	71.0 87	62.9 86	72.9 84	67.7 81	66.4 77	74.0 73	72.2 65	54.5 60	71.5 53	55.5 45
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	37.4 89	55.4 89	64.8 89	63.4 88	56.5 86	65.8 84	61.3 81	60.3 77	67.2 74	65.6 66	55.5 60	65.1 53	55.5 45
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	26.0 88	40.3 89	48.3 88	48.1 87	43.4 85	51.0 83	47.8 80	47.2 75	52.7 72	51.6 64	51.8 58	51.3 52	51.8 45
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	20.0 87	31.6 87	38.5 87	38.7 85	35.2 83	41.6 81	39.2 77	38.8 73	43.3 70	42.5 62	42.7 54	42.3 50	42.7 43
	n _{1N} = 6000 rpm	T _{2N} η	[Nm] [%]	16.2 85	26.0 86	32.0 85	32.4 84	29.6 81	35.2 79	33.2 75	33.0 70	36.8 66	36.1 58	36.4 51	36.0 46	36.4 40
Max. acceleration torque		T _{2B}	[Nm]	60	90									60	90	60
Emergency stop torque		T _{2Not}	[Nm]	120									80	120	80	
Idling torque ^{a)}		T ₀₁₂	[Nm]	1.05			0.95			0.8						
Max. input speed		n _{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output.	PS	j _t	[arcmin]	<15	<12	<11	<11	<9	<8					<7		
	PR	j _t	[arcmin]	<10	<8	<7	<7	<6	<5.5					<5		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	1.6	2.8	3.6	4	4.3	4.5	4.9	5.3	5.5	5.8	5.5	6	5.5
Stability at the output		C _{2K}	[Nm/arcmin]	30												
Max. axial force ^{c)d)} at the output			[N]	360	600	1100	1600	2200	2400	2700	3100	3200	4000	4300	4400	4400
Max. radial force ^{e)f)} at the output			[N]	370	580	780	1200	1400	1400	1400	1500	1500	1700	1900	1900	1900
Max. overturning torque ^{c)} at the output			[Nm]	24	38	51	75	89	88	91	96	98	110	120	120	120
Max. axial force ^{c)d)} at the input			[N]	1400	980	860	1000	1300	1100	1300	1300	1200	1200	1200	1200	1200
Max. radial force ^{c)f)} at the input			[N]	510	470	430	510	590	550	610	630	580	610	600	620	600
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁶ kg m ²]	97	47	29	21	16	12	10	8	7	7	6	6	6
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	4												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

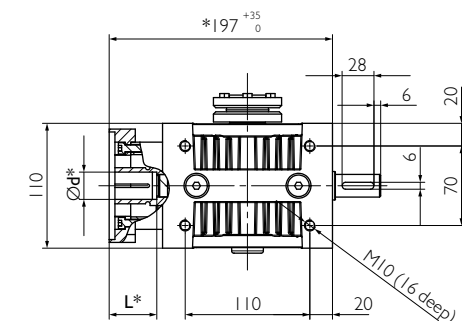
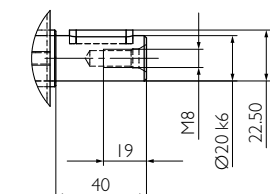
- approximate, at $n_1 = 3000$ rpm and operating temperature.
- Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- d) in relation to shaft center.
- e) at a distance of 65 mm from the middle of the casing.
- f) at a distance of 75 mm from the middle of the casing.
- g) in relation to the input.

Bearing forces



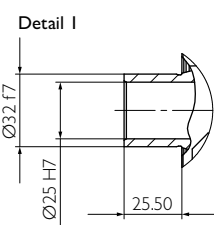
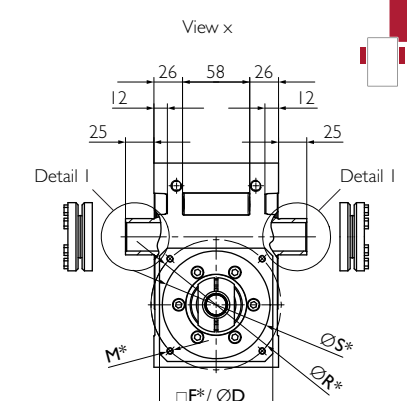
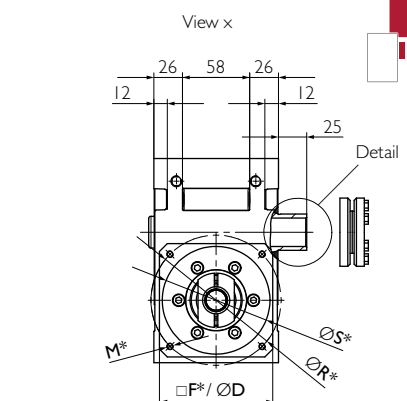
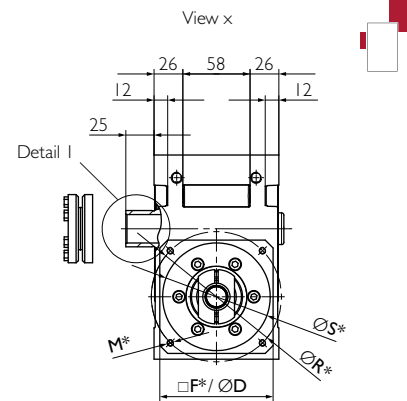


Detail 2



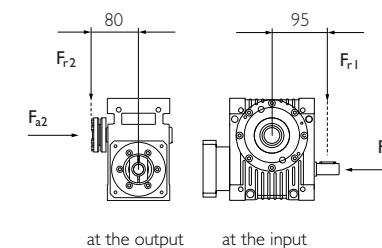
* Motor-specific gearbox dimensions

S: min. 54 [mm], R: Pitch circle Ø [mm], M: Bore hole Ø or thread [mm], □F/ØD: Specify flange [mm]



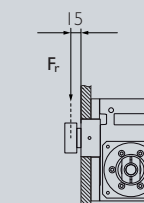
- a) approximate, at $n_1 = 3000$ rpm and operating temperature.
- b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- c) Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{3}{4} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
 - c) d) in relation to shaft center.
 - c) e) at a distance of 80 mm from the middle of the casing.
 - c) f) at a distance of 95 mm from the middle of the casing.
- g) in relation to the input, including coupling and shrink disc at the output (output 1 & 2) with two shrink discs (output 3) increase values by 200/i².
 - g) h) Motor shaft diameter $\varnothing d$ from $\varnothing 8$ to $\varnothing 24$, calculated at $\varnothing 19$ mm.
 - g) i) Motor shaft diameter $\varnothing d$ from $\varnothing 25$ to $\varnothing 35$, calculated at $\varnothing 28$ mm.

Bearing forces



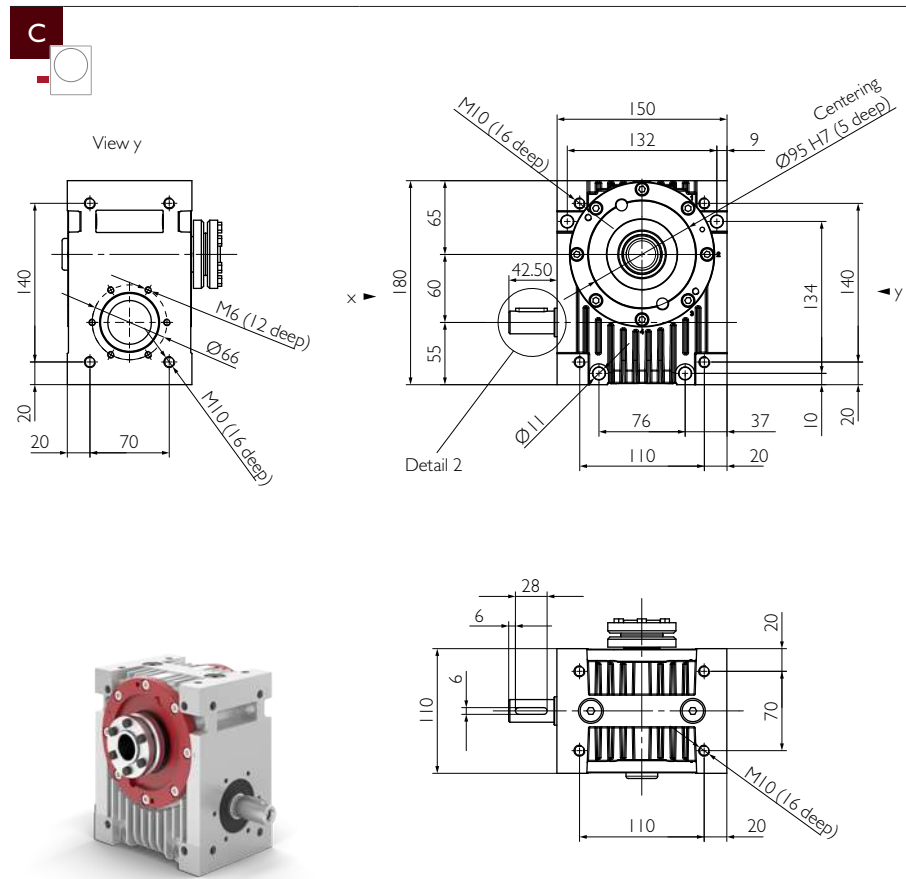
			Output Flange including Bearing & Pinion				
Radial rigidity	C ₃	[N/mm]	24000				
Speed	n _{2N}	[rpm]	1500	750	400	150	100
Max. radial force ¹⁾	F _{rmax}	[N]	2500	3200	4000	4500	5000

j) Bearing forces: Values valid at duty cycle of 40% at a distance of 15 mm from the end of the bearing.

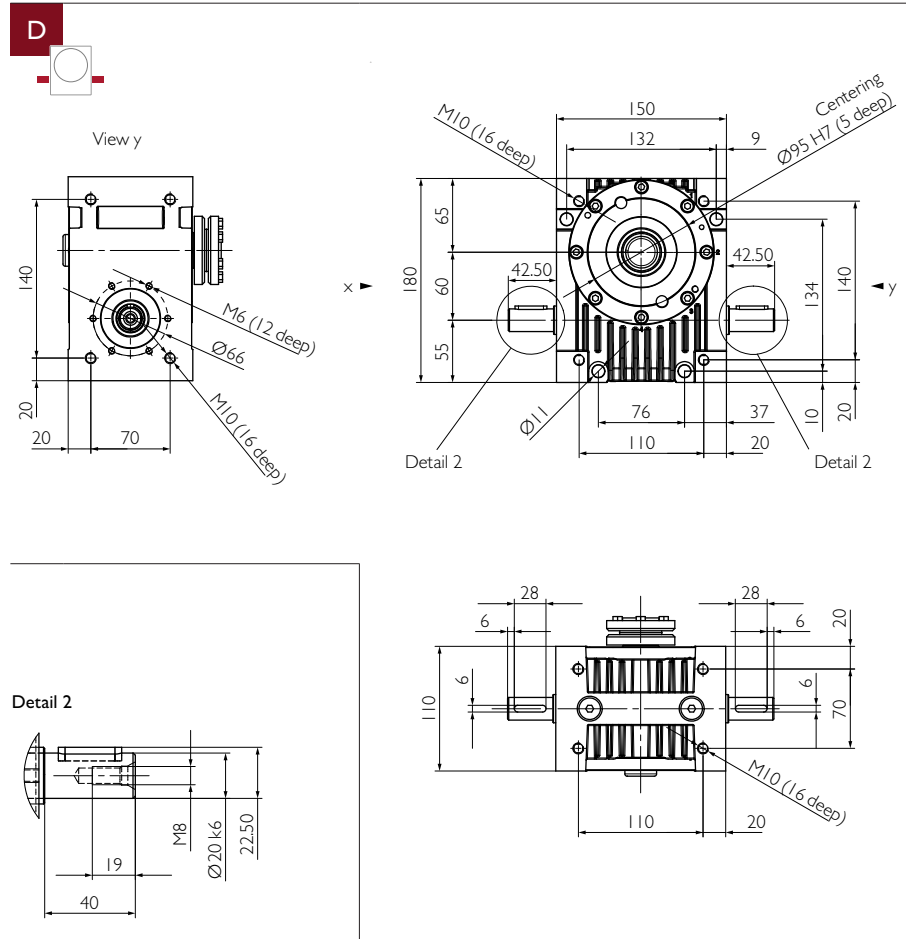


Detailed information about the **Package, Options & Accessories** on pages 60 and 61.

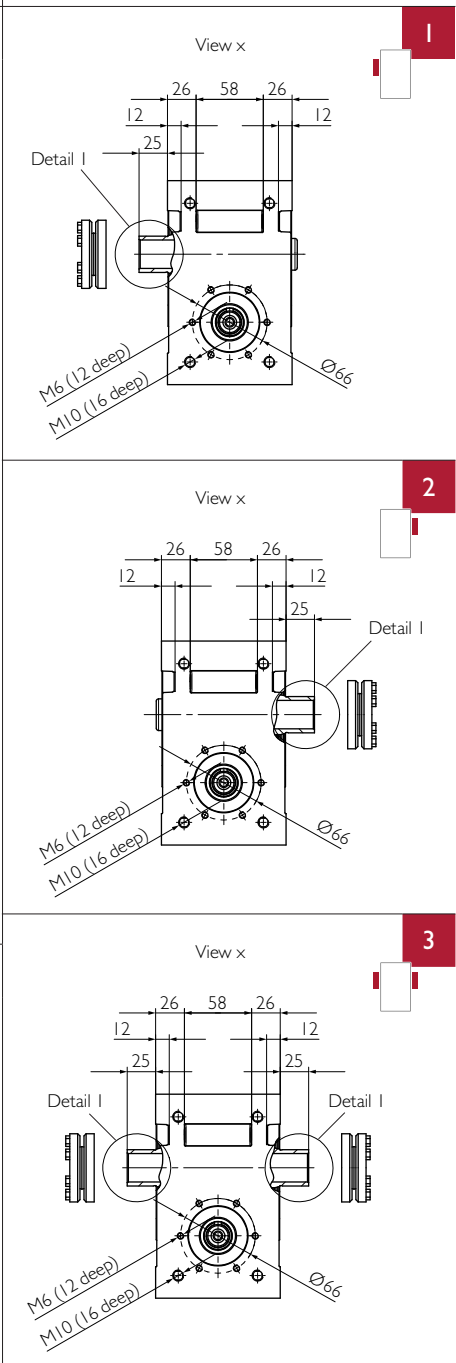
Input



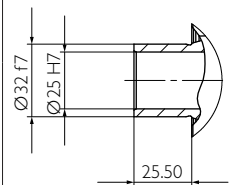
Example HPG 060 C1



Output



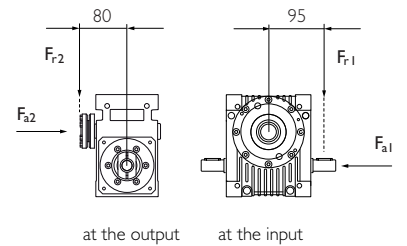
Detail 1



Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	$n_{1N} = 500 \text{ rpm}$	T_{2N} η	[Nm] [%]	135 89	192 89	219 88	211 88	186 87	215 84	199 82	195 78	195 74	202 67	144 64	209 54	144 50
	$n_{1N} = 1000 \text{ rpm}$	T_{2N} η	[Nm] [%]	107 90	158 90	184 90	180 89	160 88	186 86	173 84	170 81	190 77	185 70	144 65	184 56	144 53
	$n_{1N} = 1500 \text{ rpm}$	T_{2N} η	[Nm] [%]	89 90	135 91	159 90	157 89	140 89	164 86	153 84	151 81	168 78	165 70	144 65	163 56	144 52
	$n_{1N} = 3000 \text{ rpm}$	T_{2N} η	[Nm] [%]	59 90	93 90	113 90	113 89	103 88	121 86	114 83	113 80	126 77	124 69	126 64	123 55	126 50
	$n_{1N} = 4500 \text{ rpm}$	T_{2N} η	[Nm] [%]	44 89	71 89	88 89	89 88	81 87	96 84	91 82	90 78	101 75	99 67	101 61	98 52	101 47
	$n_{1N} = 6000 \text{ rpm}$	T_{2N} η	[Nm] [%]	35 88	58 88	71 88	73 87	67 85	80 83	75 80	75 75	84 72	82 64	84 58	82 48	84 44
Max. acceleration torque		T_{2B}	[Nm]	140	220									150	220	150
Emergency stop torque		T_{2Not}	[Nm]	300									200	300	200	
Idling torque ^{a)}		T_{012}	[Nm]	1.45			1.3			1.1						
Max. input speed		n_{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output	PS	j_k	[arcmin]	<13	<10	<9	<9	<8	<7					<6		
	PR	j_k	[arcmin]	<9	<7	<6	<6	<5	<4.5					<4		
Torsional rigidity vom Abtrieb zum Eintrieb		C_{21}	[Nm/arcmin]	2.5	4.8	7.6	8.6	10	11	12.1	13.3	14.5	15.4	15	16	15
Stability at the output		C_{2K}	[Nm/arcmin]	42												
Max. axial force ^{c)d)} at the output		F_{a2max}	[N]	1300	1700	2600	3600	4400	4100	4500	5100	5300	6500	7300	7500	7500
Max. radial force ^{c)e)} at the output		F_{r2max}	[N]	1300	1500	2100	2500	2800	2400	2500	2600	2700	3100	3300	3300	3300
Max. overturning torque ^{c)} at the output		M_{2max}	[Nm]	110	120	170	200	220	190	200	210	220	250	270	270	270
Max. axial force ^{c)d)} at the input		F_{a1max}	[N]	1700	990	750	1000	1400	1100	1400	1600	1200	1400	1300	1500	1300
Max. radial force ^{c)f)} at the input		F_{r1max}	[N]	690	510	390	520	720	560	710	760	610	650	620	690	630
Mass moment of inertia ^{g)}		J_1	[10 ⁻⁶ kg m ²]	467	221	135	95	74	52	42	34	31	27	26	25	25
Service life		L_h	[h]	25000												
Weight without motor components		m	[kg]	9												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000 \text{ rpm}$ and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
c) Bearing forces: Values valid at $n_1 = 3000 \text{ rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 80 mm from the middle of the casing.
c) f) at a distance of 95 mm from the middle of the casing.
g) in relation to the input, including shrink disc at the output (output 1 & 2), with two shrink discs (output 3) increase values by 200/i².

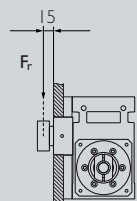
Bearing forces



Package

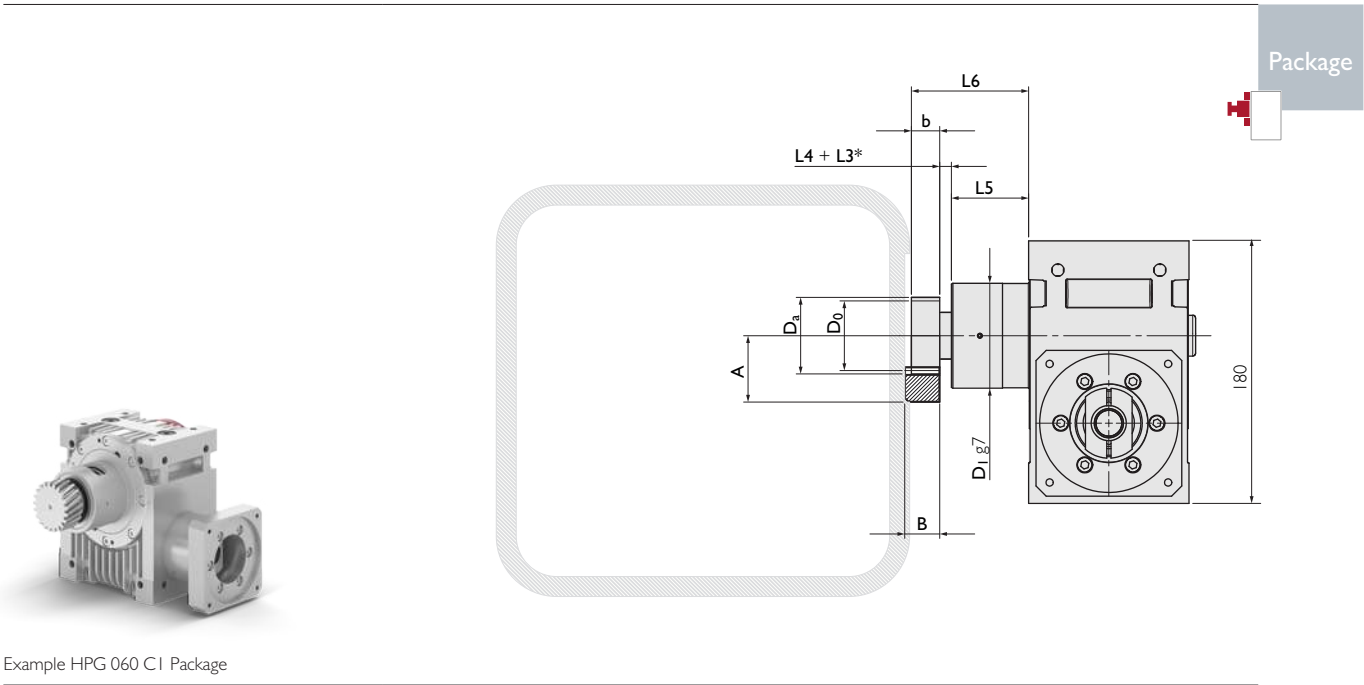
			Output Flange including Bearing & Pinion				
Radial rigidity	C ₃	[N/mm]	24000				
Speed	n _{2N}	[rpm]	1500	750	400	150	100
Max. radial force ¹⁾	F _{rmax}	[N]	2500	3200	4000	4500	5000

- j) Bearing forces: Values valid at duty cycle of 40% at a distance of 15mm from the end of the bearing.

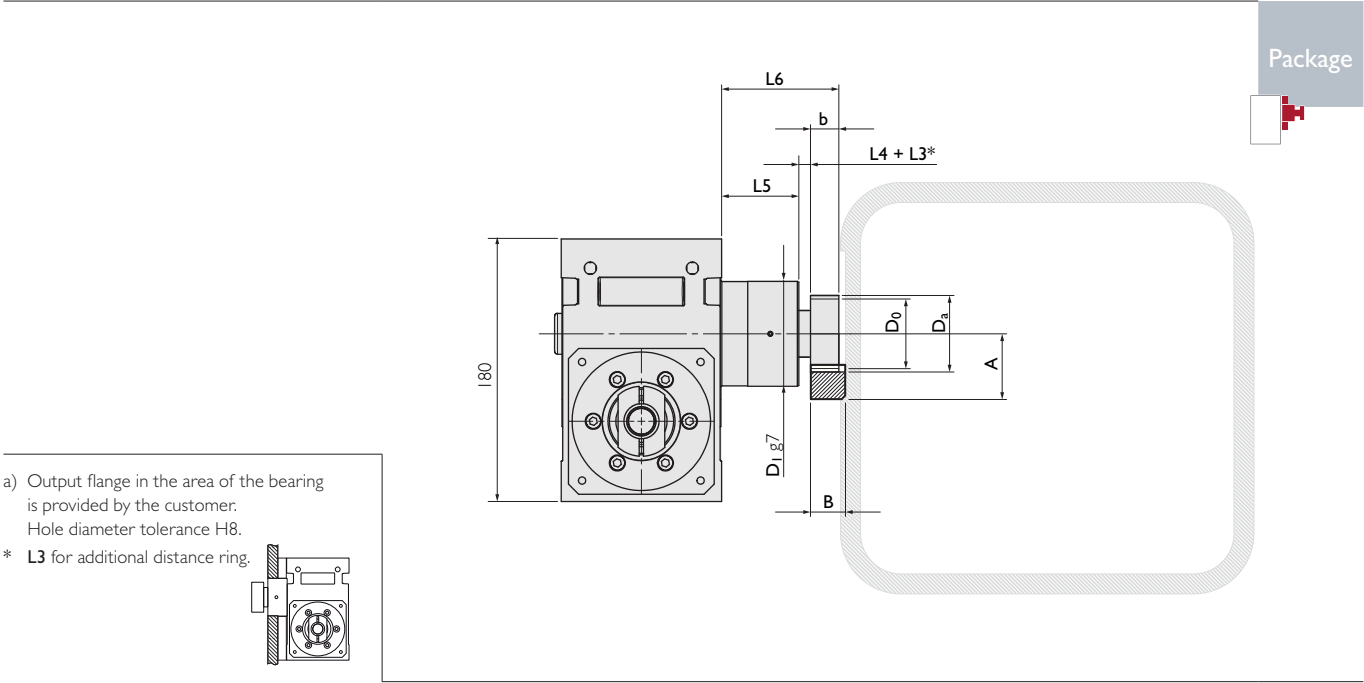


Detailed information about the Package, Options & Accessories on pages 60 and 61.

Output Flange including Bearing & Pinion^{a)}



Example HPG 060 C1 Package

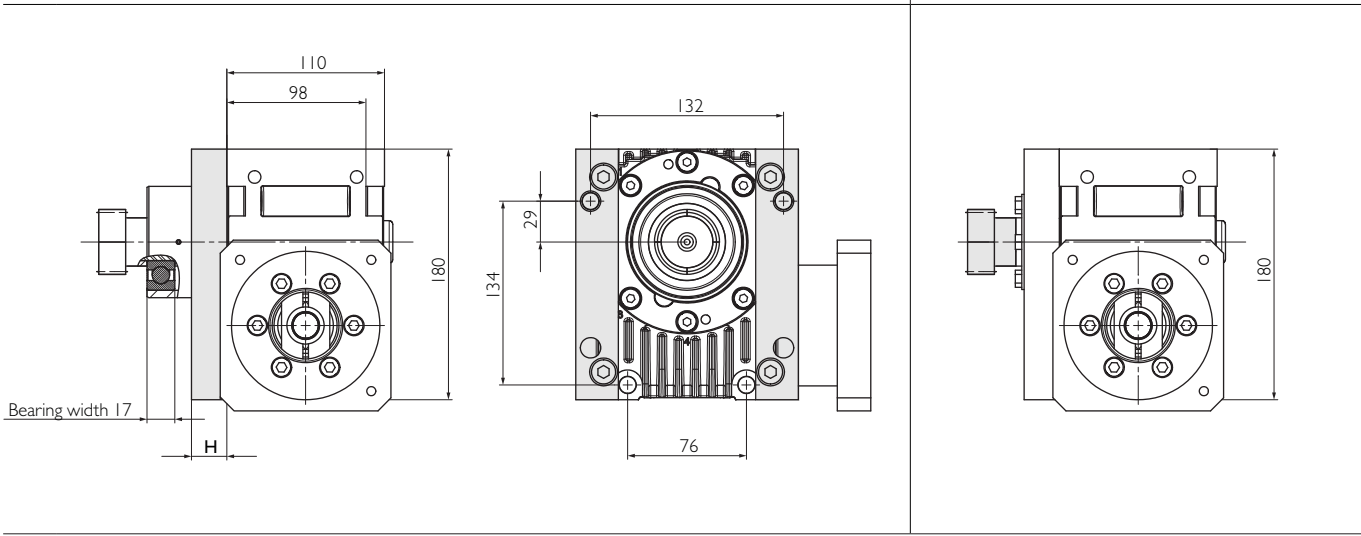


a) Output flange in the area of the bearing is provided by the customer. Hole diameter tolerance H8.
* L3 for additional distance ring.

Helical modular pitch	Art. Nr.	m	z	A	b	B	Da	D0	D1	L4	L5	L6
Pinion 1	211220	2	20	43.22	20	24	46.44	42.44	72	8	53	81
											58	86
											83	111
Pinion 2	211320	2.5	20	48.025	25	24	58.05	53.05	72	8	53	86
											58	91
											83	116
Pinion 3	211416	3	16	52.365	30	29	58.73	52.73	52.73	8	53	91
											58	96
											83	121
Straight modular pitch	Art. Nr.	m	z	A	b	B	Da	D0	D1	L4	L5	L6
Pinion 4	201220	2	20	42.0	20	24	44.0	40.0	72	8	53	81
											58	86
											83	111
Pinion 5	201320	2.5	20	46.5	25	24	55.0	50.0	72	8	53	86
											58	91
											83	116
Pinion 6	201416	3	16	50.9	30	29	55.8	49.8	72	8	53	91
											58	96
											83	121

Spacer Elements

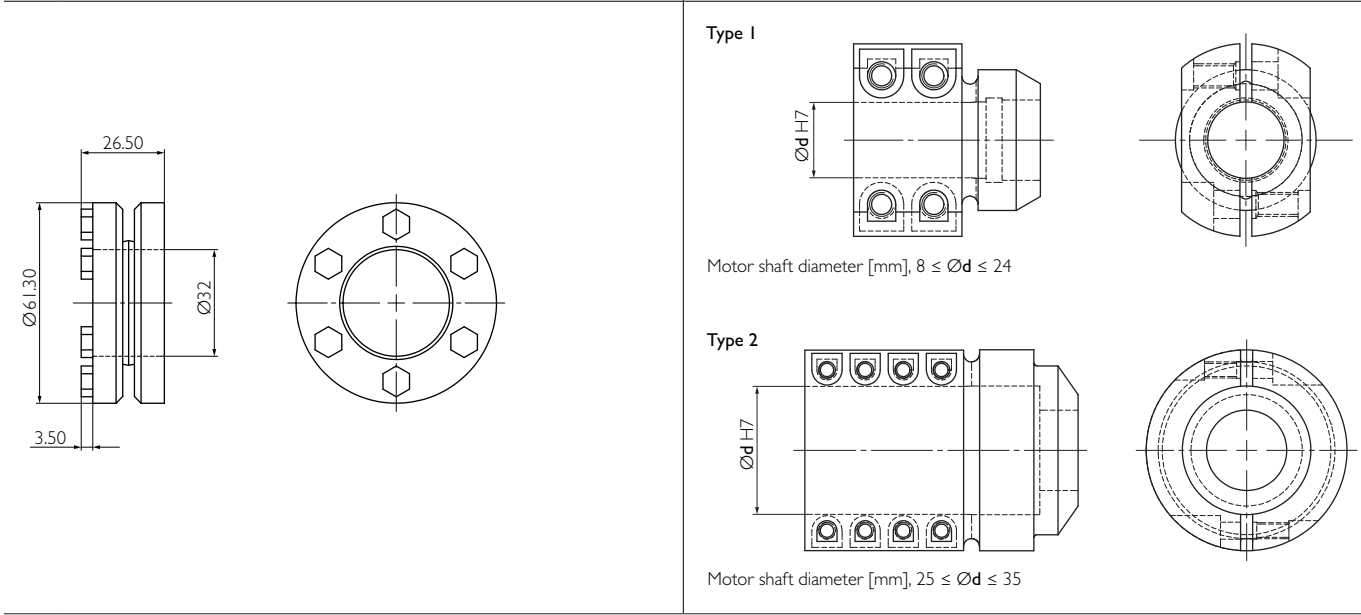
with Pinion special solutions on request



Casing can only be fastened with long screws as per the bore hole pattern. Screws M10 of length 98mm + H + thread depth, tightening torque 42Nm.

Shrink Disc

Coupling



Your ideal Drive Train

Our Function Package with high-performance angle gearbox, output flange, pinion and rack by Güdel.

			Pinion 1	Pinion 2	Pinion 3	Pinion 4	Pinion 5	Pinion 6
Maximum acceleration force	F_N	[N]	7480	10363	13589	5958	9004	12597
Maximum acceleration torque	T_N	[Nm]	159	275	346	119	225	302

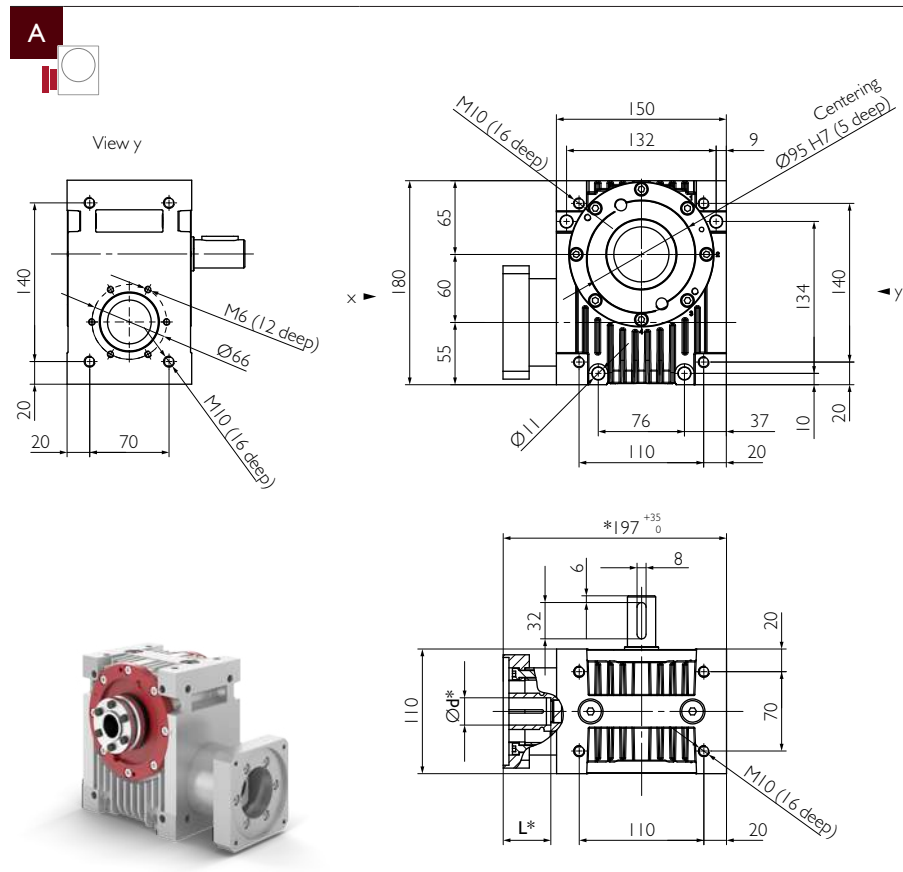
Higher value for rack and pinion taking account of the number of load cycles: 1×10^6 for the rack; 1×10^7 for the pinion. Both in cycle mode.



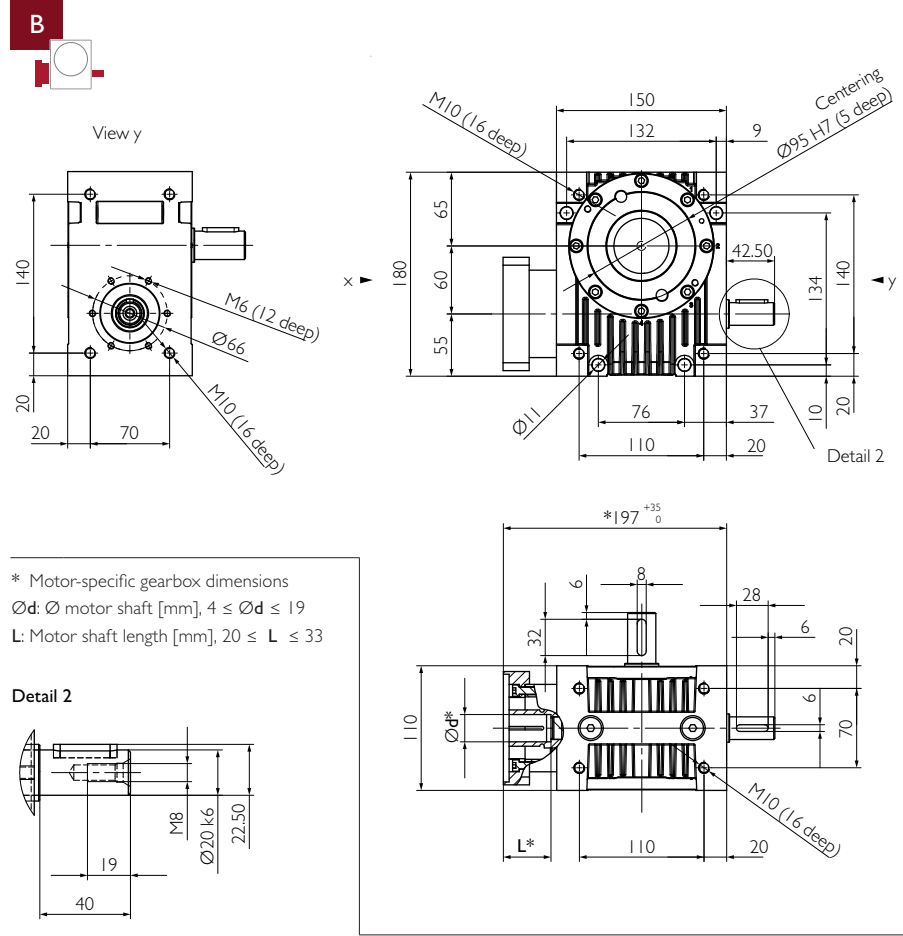
See Rack & Pinion Program of your ideal Drive Train on pages 104 et seq.

See Flowcharts to find your ideal Drive Train on pages 116 et seq.

Input

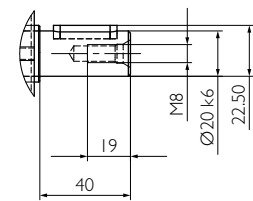


Example HPG 060 A6

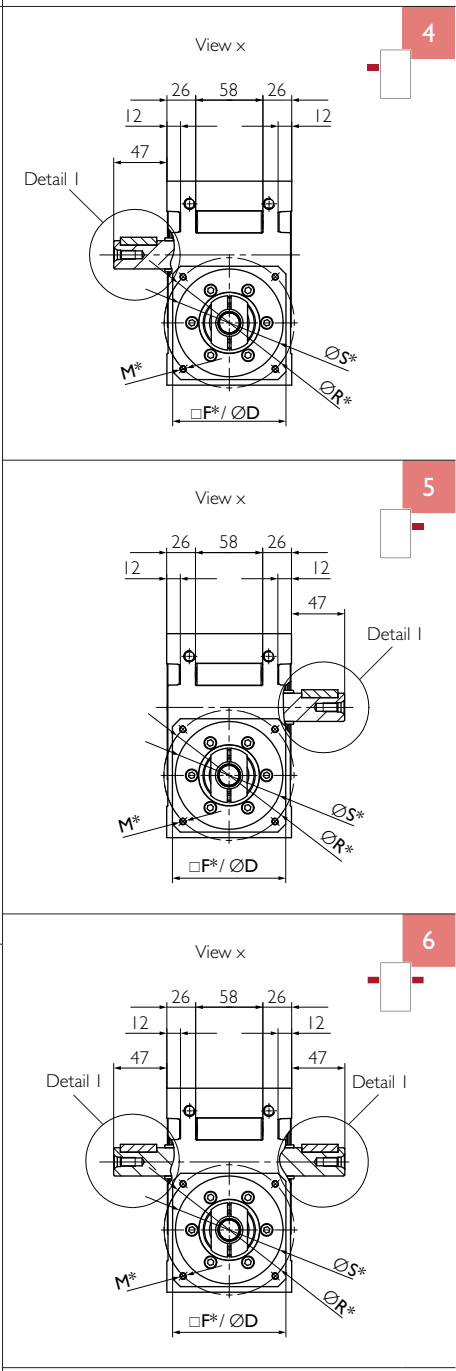


* Motor-specific gearbox dimensions
Ød: Ø motor shaft [mm], 4 ≤ Ød ≤ 19
L: Motor shaft length [mm], 20 ≤ L ≤ 33

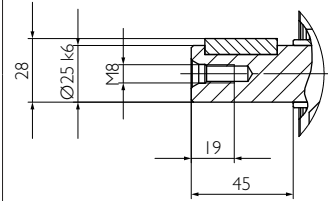
Detail 2



Output



Detail I

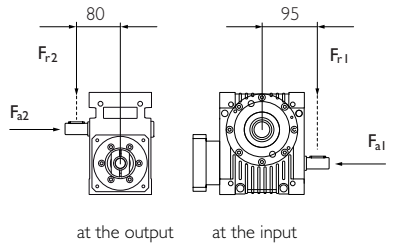


* Motor-specific gearbox dimensions
S: min. 32 [mm], R: Pitch circle Ø [mm], M: Bore hole Ø or thread [mm], □F/ØD: Specify flange [mm]

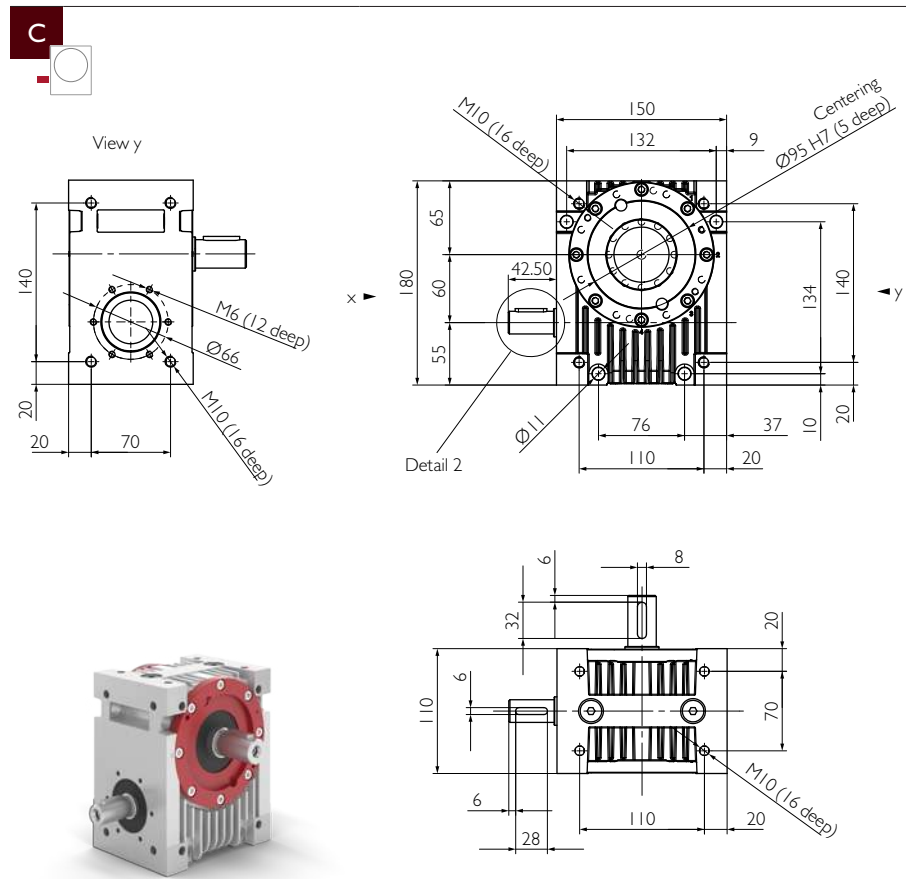
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	135 89	192 89	219 88	211 88	186 87	215 84	199 82	195 78	195 74	202 67	144 64	209 54	144 50
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	107 90	158 90	184 90	180 89	160 88	186 86	173 84	170 81	190 77	185 70	144 65	184 56	144 53
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	89 90	135 91	159 90	157 89	140 89	164 86	153 84	151 81	168 78	165 70	144 65	163 56	144 52
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	59 90	93 90	113 90	113 89	103 88	121 86	114 83	113 80	126 77	124 69	126 64	123 55	126 50
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	44 89	71 89	88 89	89 88	81 87	96 84	91 82	90 78	101 75	99 67	101 61	98 52	101 47
	n _{1N} = 6000 rpm	T _{2N} η	[Nm] [%]	35 88	58 88	71 88	73 87	67 85	80 83	75 80	75 75	84 72	82 64	84 58	82 48	84 44
Max. acceleration torque		T _{2B}	[Nm]	140	220									150	220	150
Emergency stop torque		T _{2Not}	[Nm]	300										200	300	200
Idling torque ^{a)}		T ₀₁₂	[Nm]	1.45			1.3				1.1					
Max. input speed		n _{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output	PS	j _k	[arcmin]	<13	<10	<9	<9	<8	<7					<6		
	PR	j _k	[arcmin]	<9	<7	<6	<6	<5	<4.5					<4		
Torsional rigidity vom Abtrieb zum Eintrieb		C ₂₁	[Nm/arcmin]	2.5	4.8	7.6	8.6	10	11	12.1	13.3	14.5	15.4	15	16	15
Stability at the output		C _{2K}	[Nm/arcmin]	42												
Max. axial force ^{c) d)} at the output		F _{a2max}	[N]	1300	1700	2600	3600	4400	4100	4500	5100	5300	6500	7300	7500	7500
Max. radial force ^{c) e)} at the output		F _{r2max}	[N]	1300	1500	2100	2500	2800	2400	2500	2600	2700	3100	3300	3300	3300
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	110	120	170	200	220	190	200	210	220	250	270	270	270
Max. axial force ^{c) d)} at the input		F _{a1max}	[N]	1700	990	750	1000	1400	1100	1400	1600	1200	1400	1300	1500	1300
Max. radial force ^{c) f)} at the input		F _{r1max}	[N]	690	510	390	520	720	560	710	760	610	650	620	690	630
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁶ kg m ²]	550	304	218	178	157	135	125	117	114	110	109	108	108
	Type 2 ⁱ⁾	J ₁	[10 ⁻⁶ kg m ²]	760	515	428	389	367	345	335	328	325	321	320	319	318
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	9												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at n₁ = 3000 rpm and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
c) Bearing forces: Values valid at n₁ = 3000 rpm; ½ T_{2N} and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 80 mm from the middle of the casing.
c) f) at a distance of 95 mm from the middle of the casing.
g) in relation to the input, including coupling.
g) h) Motor shaft diameter Ød from Ø8 to Ø24, calculated at Ø19mm.
g) i) Motor shaft diameter Ød from Ø25 to Ø35, calculated at Ø28mm.

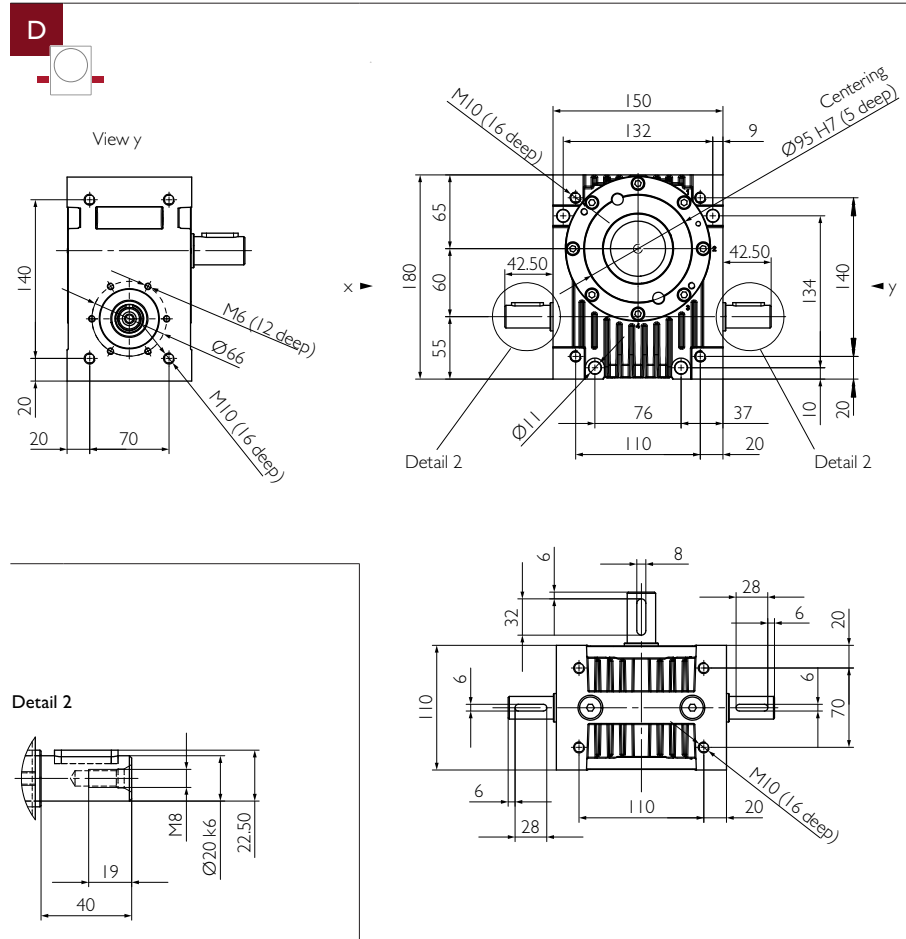
Bearing forces



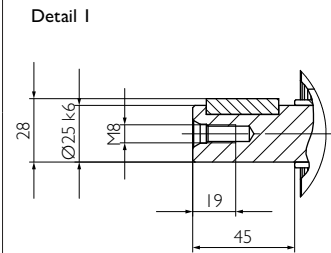
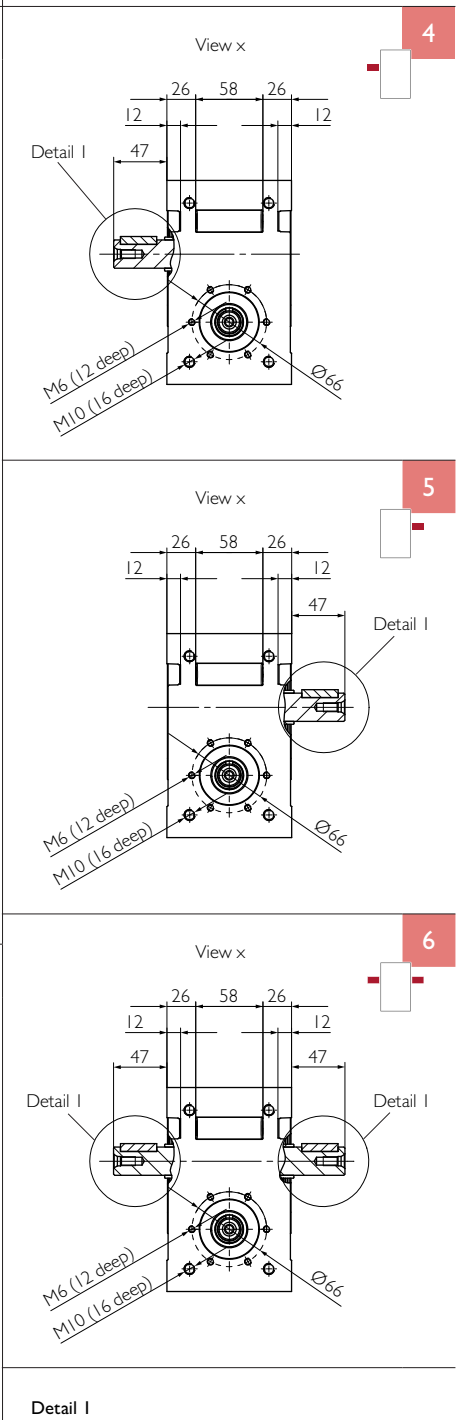
Input



Example HPG 060 C5



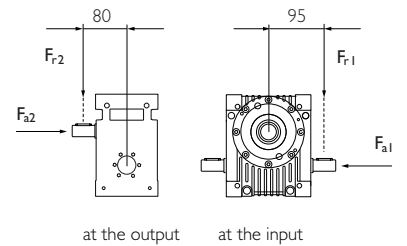
Output



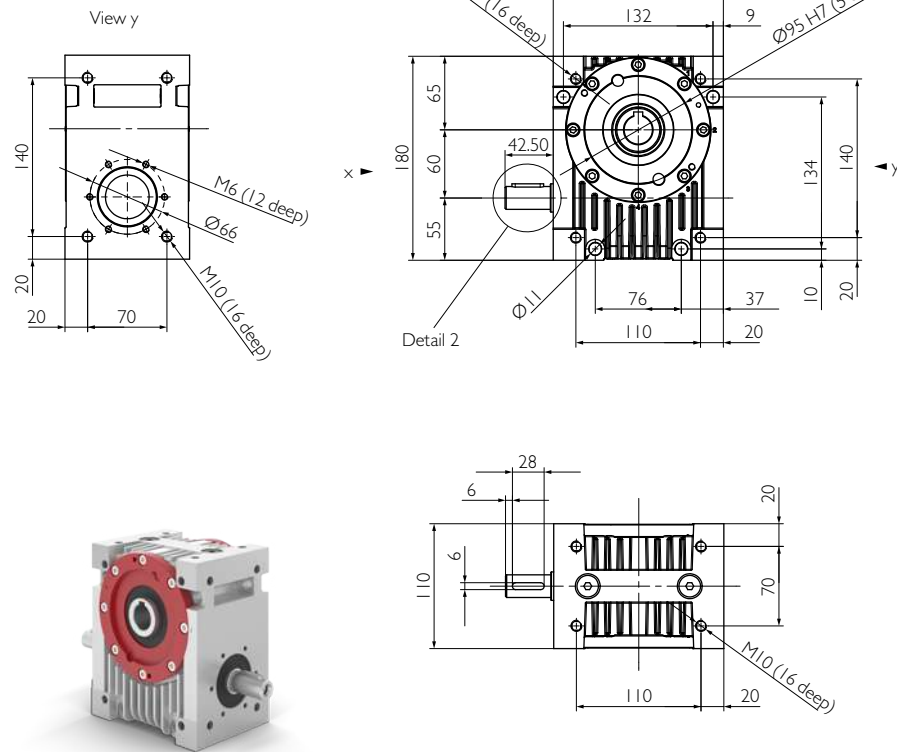
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	$n_{1N} = 500 \text{ rpm}$	T_{2N} η	[Nm] [%]	135 89	192 89	219 88	211 88	186 87	215 84	199 82	195 78	195 74	202 67	144 64	209 54	144 50
	$n_{1N} = 1000 \text{ rpm}$	T_{2N} η	[Nm] [%]	107 90	158 90	184 90	180 89	160 88	186 86	173 84	170 81	190 77	185 70	144 65	184 56	144 53
	$n_{1N} = 1500 \text{ rpm}$	T_{2N} η	[Nm] [%]	89 90	135 91	159 90	157 89	140 89	164 86	153 84	151 81	168 78	165 70	144 65	163 56	144 52
	$n_{1N} = 3000 \text{ rpm}$	T_{2N} η	[Nm] [%]	59 90	93 90	113 90	113 89	103 88	121 86	114 83	113 80	126 77	124 69	126 64	123 55	126 50
	$n_{1N} = 4500 \text{ rpm}$	T_{2N} η	[Nm] [%]	44 89	71 89	88 89	89 88	81 87	96 84	91 82	90 78	101 75	99 67	101 61	98 52	101 47
	$n_{1N} = 6000 \text{ rpm}$	T_{2N} η	[Nm] [%]	35 88	58 88	71 88	73 87	67 85	80 83	75 80	75 75	84 72	82 64	84 58	82 48	84 44
Max. acceleration torque		T_{2B}	[Nm]	140	220									150	220	150
Emergency stop torque		T_{2Not}	[Nm]	300									200	300	200	
Idling torque ^{a)}		T_{012}	[Nm]	1.45			1.3			1.1						
Max. input speed		n_{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output	PS	j_k	[arcmin]	<13	<10	<9	<9	<8	<7					<6		
	PR	j_k	[arcmin]	<9	<7	<6	<6	<5	<4.5					<4		
Torsional rigidity vom Abtrieb zum Eintrieb		C_{t21}	[Nm/arcmin]	2.5	4.8	7.6	8.6	10	11	12.1	13.3	14.5	15.4	15	16	15
Stability at the output		C_{2K}	[Nm/arcmin]	42												
Max. axial force ^{c)d)} at the output		F_{a2max}	[N]	1300	1700	2600	3600	4400	4100	4500	5100	5300	6500	7300	7500	7500
Max. radial force ^{c)e)} at the output		F_{r2max}	[N]	1300	1500	2100	2500	2800	2400	2500	2600	2700	3100	3300	3300	3300
Max. overturning torque ^{c)} at the output		M_{2max}	[Nm]	110	120	170	200	220	190	200	210	220	250	270	270	270
Max. axial force ^{c)d)} at the input		F_{a1max}	[N]	1700	990	750	1000	1400	1100	1400	1600	1200	1400	1300	1500	1300
Max. radial force ^{c)f)} at the input		F_{r1max}	[N]	690	510	390	520	720	560	710	760	610	650	620	690	630
Mass moment of inertia ^{g)}		J_1	[10 ⁻⁶ kg m ²]	467	221	135	95	74	52	42	34	31	27	26	25	25
Service life		L_h	[h]	25000												
Weight without motor components		m	[kg]	9												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000 \text{ rpm}$ and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
c) Bearing forces: Values valid at $n_1 = 3000 \text{ rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 80 mm from the middle of the casing.
c) f) at a distance of 95 mm from the middle of the casing.
g) in relation to the input.

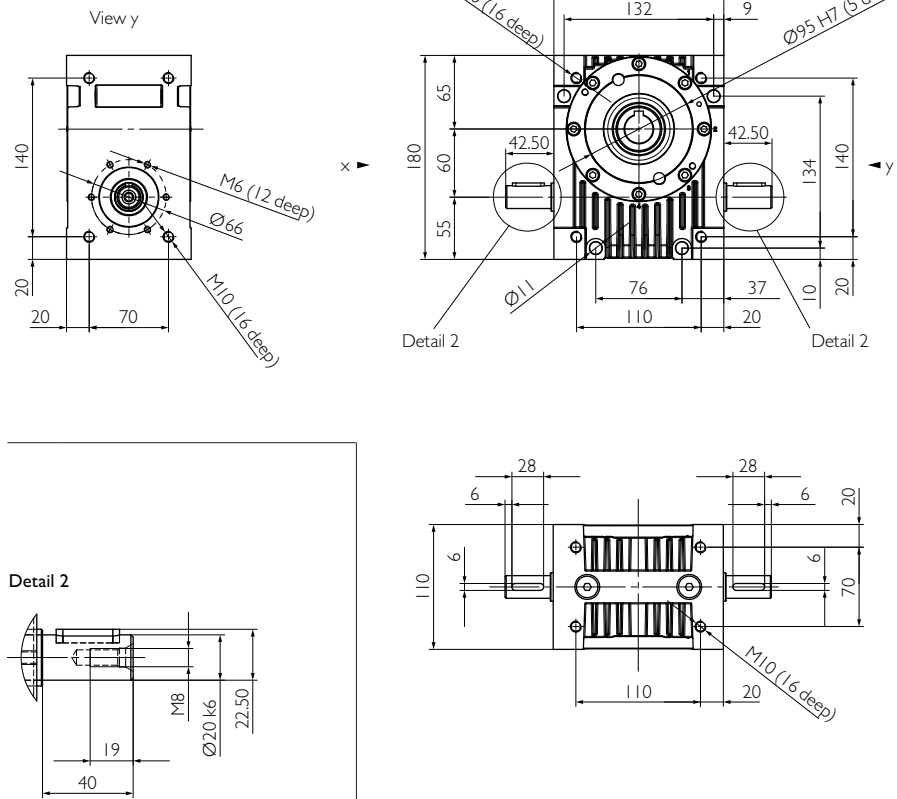
Bearing forces



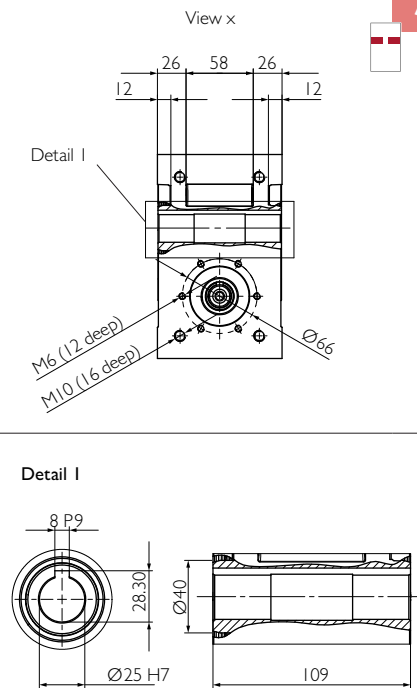
Input



Example HPG 060 D7



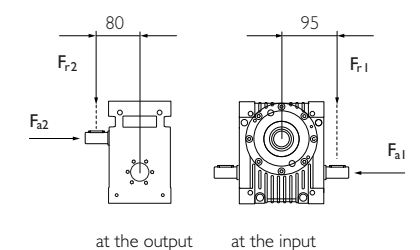
Output



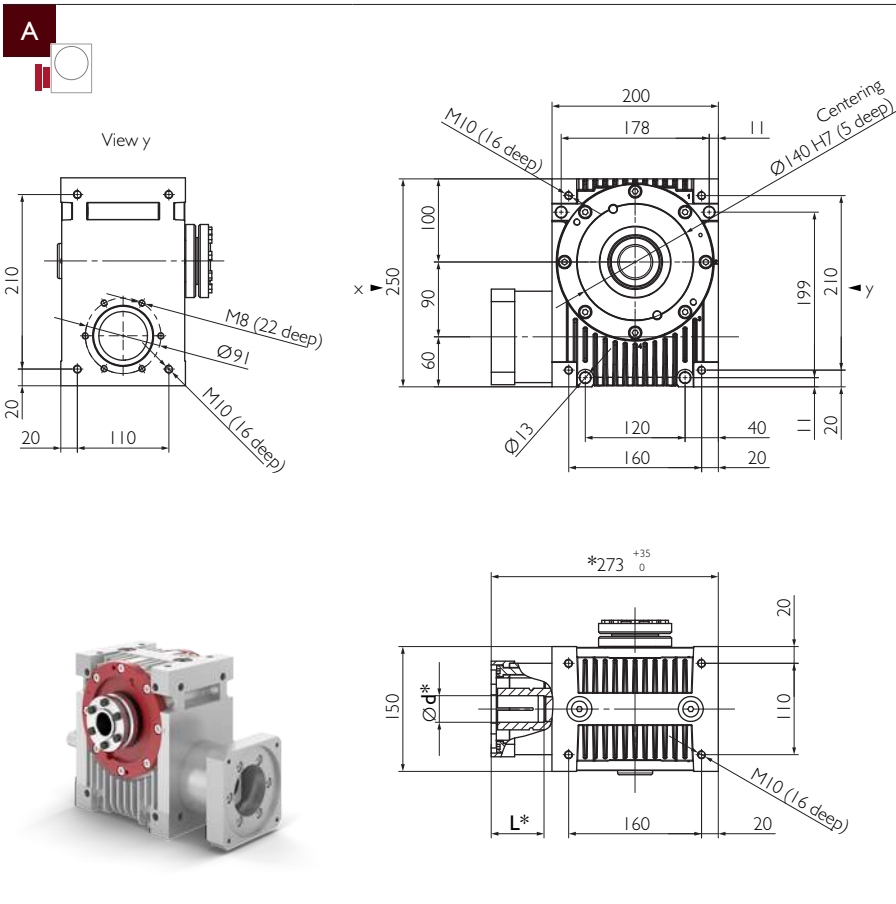
Ratio	i		2	3	4	5	6	8	10	13.33	16	24	30	47	60	
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	135 89	192 89	219 88	211 88	186 87	215 84	199 82	195 78	195 74	202 67	144 64	209 54	144 50
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	107 90	158 90	184 90	180 89	160 88	186 86	173 84	170 81	190 77	185 70	144 65	184 56	144 53
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	89 90	135 91	159 90	157 89	140 89	164 86	153 84	151 81	168 78	165 70	144 65	163 56	144 52
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	59 90	93 90	113 90	113 89	103 88	121 86	114 83	113 80	126 77	124 69	126 64	123 55	126 50
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	44 89	71 89	88 89	89 88	81 87	96 84	91 82	90 78	101 75	99 67	101 61	98 52	101 47
	n _{1N} = 6000 rpm	T _{2N} η	[Nm] [%]	35 88	58 88	71 88	73 87	67 85	80 83	75 80	75 75	84 72	82 64	84 58	82 48	84 44
Max. acceleration torque		T _{2B}	[Nm]	140	220								150	220	150	
Emergency stop torque		T _{2Not}	[Nm]	300								200	300	200		
Idling torque ^{a)}		T ₀₁₂	[Nm]	1.45			1.3			1.1						
Max. input speed		n _{1Max}	[rpm]	6000												
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<13	<10	<9	<9	<8	<7					<6		
	PR	j _t	[arcmin]	<9	<7	<6	<6	<5	<4.5					<4		
Torsional rigidity vom Abrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	2.5	4.8	7.6	8.6	10	11	12.1	13.3	14.5	15.4	15	16	15
Stability at the output		C _{2K}	[Nm/arcmin]	42												
Max. axial force ^{c)d)} at the output		F _{a2max}	[N]	780	1100	1900	2800	3600	3300	3800	4300	4500	5600	6300	6400	6400
Max. radial force ^{c)e)} at the output		F _{r2max}	[N]	840	1200	1500	2200	2400	2000	2100	2300	2300	2700	2900	2900	2900
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	67	95	120	170	190	160	170	180	190	220	230	240	230
Max. axial force ^{c)d)} at the input		F _{a1max}	[N]	1700	990	750	1000	1400	1100	1400	1600	1200	1400	1300	1500	1300
Max. radial force ^{c)f)} at the input		F _{r1max}	[N]	690	510	390	520	720	560	710	760	610	650	620	690	630
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁶ kg m ²]	416	199	122	87	68	49	40	33	30	27	26	25	25
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	8												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- approximate, at $n_1 = 3000$ rpm and operating temperature.
- Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- Bearing forces: Values valid at $n_1 = 3000$ rpm; $\frac{2}{3} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- d) in relation to shaft center.
- e) at a distance of 80 mm from the middle of the casing.
- f) at a distance of 95 mm from the middle of the casing.
- g) in relation to the input.

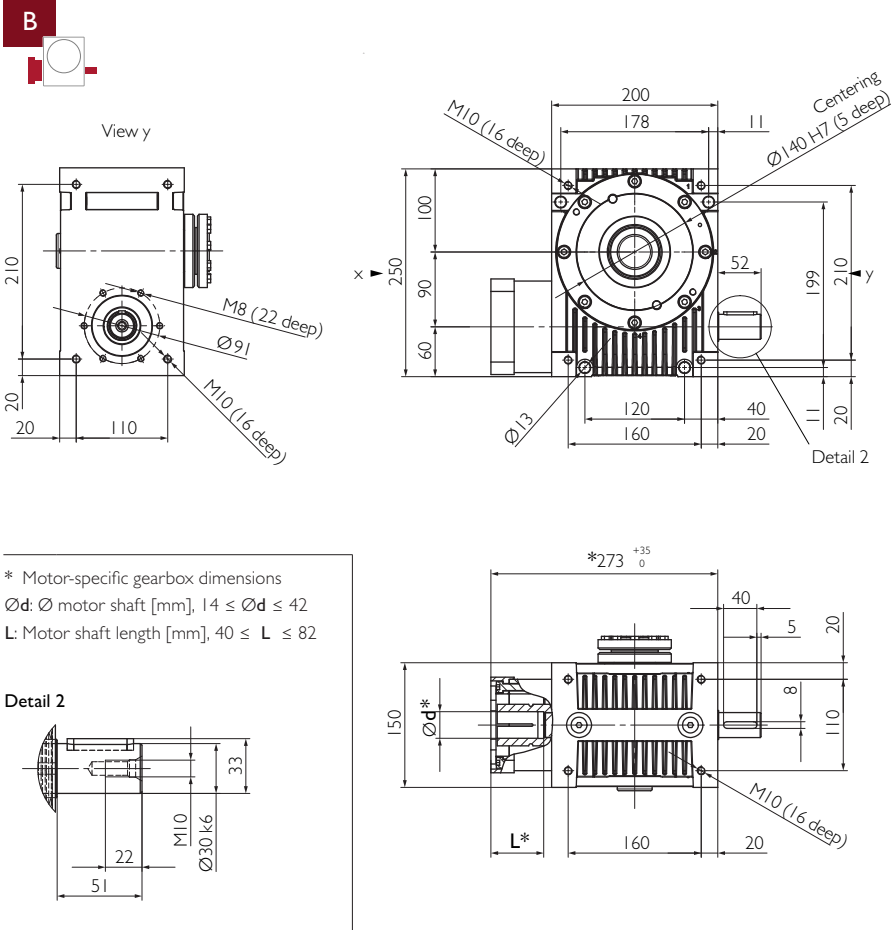
Bearing forces



Input

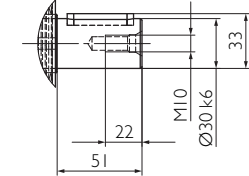


Example HPG 090 B1

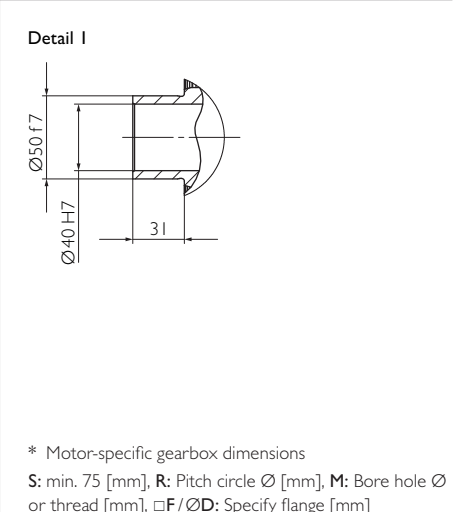
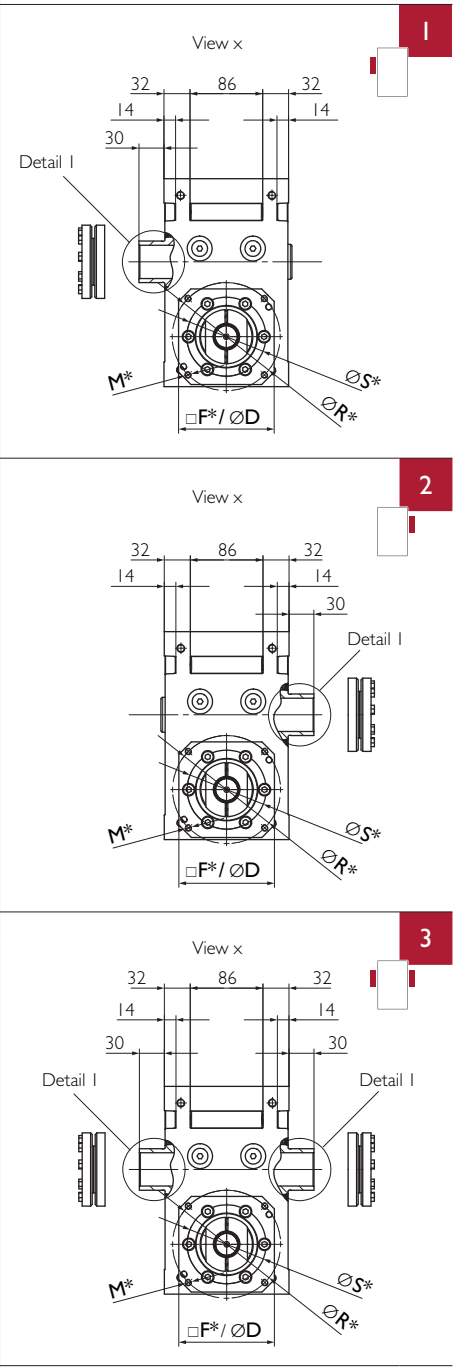


* Motor-specific gearbox dimensions
Ød: Ø motor shaft [mm], 14 ≤ Ød ≤ 42
L: Motor shaft length [mm], 40 ≤ L ≤ 82

Detail 2



Output

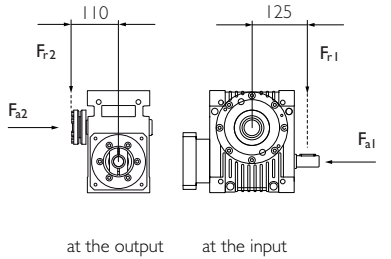


* Motor-specific gearbox dimensions
S: min. 75 [mm], R: Pitch circle Ø [mm], M: Bore hole Ø or thread [mm], □F/ØD: Specify flange [mm]

Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	469 92	679 92	784 91	761 91	674 90	782 88	726 87	712 84	700 80	727 74	527 71	527 61	527 50
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	350 92	528 92	624 92	615 92	551 91	644 89	601 88	592 85	660 82	645 76	527 72	640 63	527 57
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	279 92	432 93	518 92	516 92	466 91	547 90	513 88	507 85	565 83	553 77	527 72	550 64	527 57
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	174 92	279 92	343 92	348 92	318 91	377 89	356 88	354 85	395 82	388 76	396 70	386 62	396 55
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	126 91	206 92	257 92	262 91	241 90	288 88	273 86	272 83	303 81	298 74	305 68	297 60	305 53
Max. acceleration torque		T _{2B}	[Nm]	470	790									530	790	530
Emergency stop torque		T _{2Not}	[Nm]	900										700	900	700
Idling torque ^{a)}		T ₀₁₂	[Nm]	2.8			2.5			2						
Max. input speed		n _{1Max}	[rpm]	4500												
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<10	<8	<7	<7	<6	<6					<5		
	PR	j _t	[arcmin]	<6.5	<5	<4.5	<4	<4	<3.5					<3		
Torsional rigidity vom Abtrieb zum Eintrieb		C ₂₁	[Nm/arcmin]	5.5	10.8	15.9	18.3	20.8	23.3	25.8	28.3	31.3	33.2	32	35	32
Stability at the output		C _{2K}	[Nm/arcmin]	95												
Max. axial force ^{c)d)} at the output		F _{a2max}	[N]	6200	8200	7800	9200	11000	12000	14000	17000	18000	18000	18000	19000	19000
Max. radial force ^{c)e)} at the output		F _{r2max}	[N]	5300	6400	5500	5800	6500	6800	7500	8400	8600	8700	8800	8800	8800
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	590	700	600	640	710	750	830	920	940	960	970	970	970
Max. axial force ^{c)d)} at the input		F _{a1max}	[N]	3100	1600	1100	1700	2800	2000	2700	2900	2300	2500	2700	2600	2800
Max. radial force ^{c)f)} at the input		F _{r1max}	[N]	1500	910	640	990	1600	1200	1500	1700	1300	1400	1600	1500	1600
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁵ kg m ²]	383	206	144	116	100	85	78	72	70	67	67	66	65
	Type 2 ⁱ⁾	J ₁	[10 ⁻⁵ kg m ²]	453	276	214	186	170	155	148	142	140	137	136	136	135
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	25												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000 \text{ rpm}$ and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
c) Bearing forces: Values valid at $n_1 = 1500 \text{ rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 110 mm from the middle of the casing.
c) f) at a distance of 125 mm from the middle of the casing.
g) in relation to the input, including coupling and shrink disc at the output (output 1 & 2), with two shrink discs (output 3) increase values by 115/i².
c) h) Motor shaft diameter Ød from Ø14 to Ø35, calculated at Ø24mm.
c) i) Motor shaft diameter Ød from Ø36 to Ø42, calculated at Ø38mm.

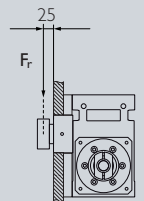
Bearing forces



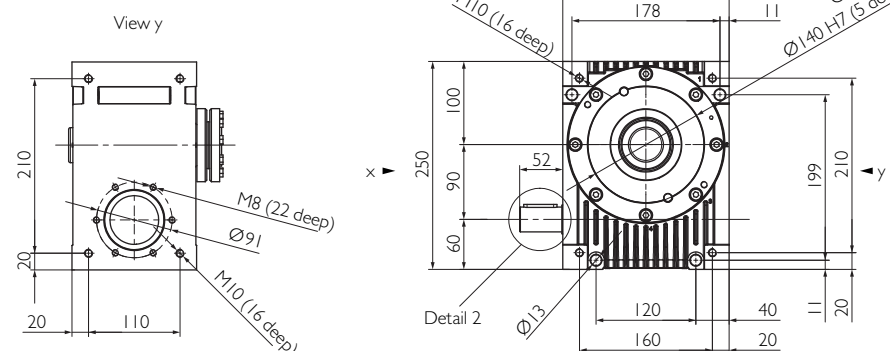
Package

Radial rigidity	C_3	[N/mm]	Output Flange including Bearing & Pinion				
			1500	750	400	150	100
Speed	n_{2N}	[rpm]	1500	750	400	150	100
Max. radial force ^{j)}	F_{rmax}	[N]	4800	5900	7200	8800	9700

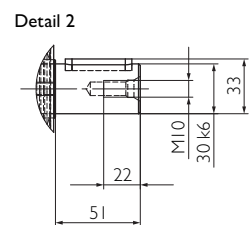
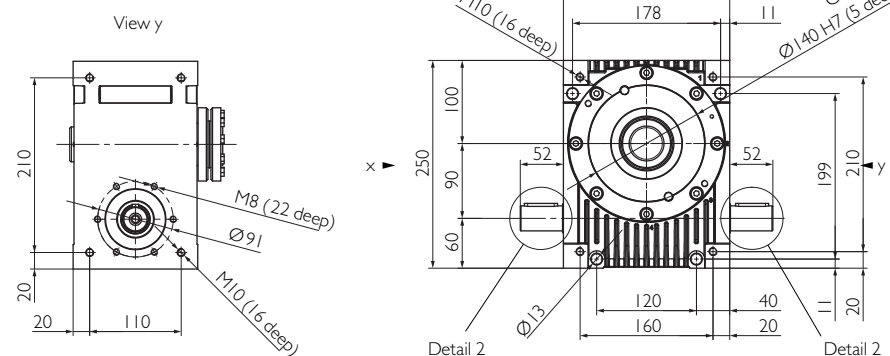
j) Bearing forces: Values valid at duty cycle of 40% at a distance of 25 mm from the end of the bearing.



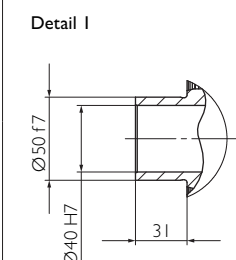
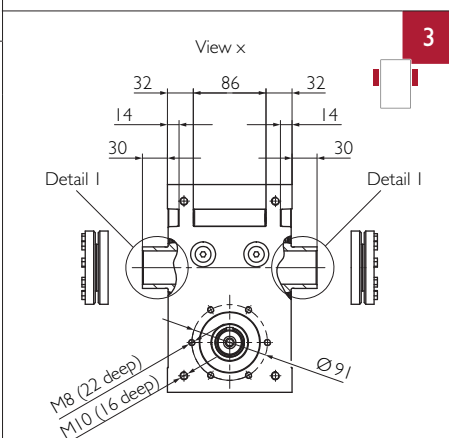
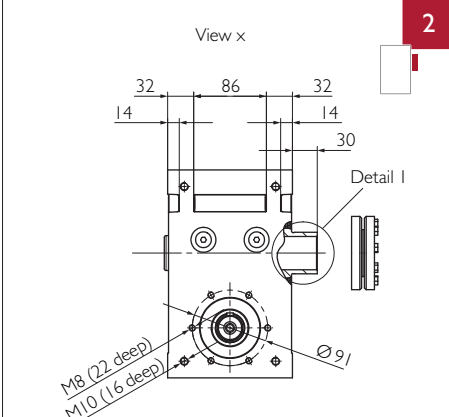
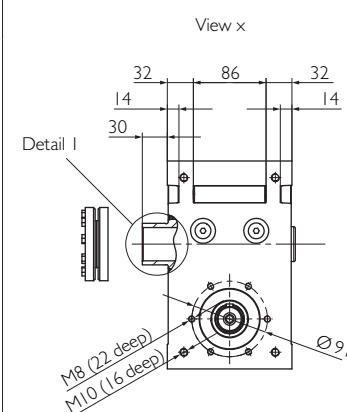
Input



Example HPG 090 C2



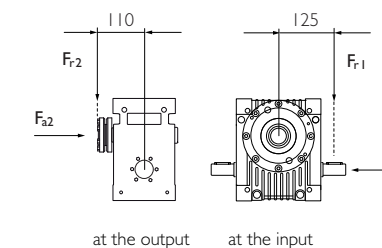
Output



Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	469 92	679 92	784 91	761 91	674 90	782 88	726 87	712 84	700 80	727 74	527 71	752 61	527 50
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	350 92	528 92	624 92	615 92	551 91	644 89	601 88	592 85	660 82	645 76	527 72	640 63	527 57
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	279 92	432 93	518 92	516 92	466 91	547 90	513 88	507 85	565 83	553 77	527 72	550 64	527 57
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	174 92	279 92	343 92	348 92	318 91	377 89	356 88	354 85	395 82	388 76	396 70	386 62	396 55
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	126 91	206 92	257 92	262 91	241 90	288 88	273 86	272 83	303 81	298 74	305 68	297 60	305 53
Max. acceleration torque		T _{2B}	[Nm]	470	790									530	790	530
Emergency stop torque		T _{2not}	[Nm]	900									700	900	700	
Idling torque ^{a)}		T ₀₁₂	[Nm]	2.8			2.5			2						
Max. input speed		n _{1Max}	[rpm]	4500												
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<10	<8	<7	<7	<6	<6					<5		
	PR	j _t	[arcmin]	<6.5	<5	<4.5	<4	<4	<3.5					<3		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	5.5	10.8	15.9	18.3	20.8	23.3	25.8	28.3	31.3	33.2	32	35	32
Stability at the output		C _{2K}	[Nm/arcmin]	95												
Max. axial force ^{c)d)} at the output		F _{a2max}	[N]	6200	8200	7800	9200	11000	12000	14000	17000	18000	18000	18000	19000	19000
Max. radial force ^{c)e)} at the output		F _{r2max}	[N]	5300	6400	5500	5800	6500	6800	7500	8400	8600	8700	8800	8800	8800
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	590	700	600	640	710	750	830	920	940	960	970	970	970
Max. axial force ^{c)d)} at the input		F _{a1max}	[N]	3100	1600	1100	1700	2800	2000	2700	2900	2300	2500	2700	2600	2800
Max. radial force ^{c)f)} at the input		F _{r1max}	[N]	1500	910	640	990	1600	1200	1500	1700	1300	1400	1600	1500	1600
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁵ kg m ²]	336	160	98	70	54	39	32	26	24	21	20	19	19
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	23												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000$ rpm and operating temperature.
- b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- c) Bearing forces: Values valid at $n_1 = 1500$ rpm; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- c) d) in relation to shaft center.
- c) e) at a distance of 110 mm from the middle of the casing.
- c) f) at a distance of 125 mm from the middle of the casing.
- g) in relation to the input, including shrink disc at the output (output 1 & 2),
with two shrink discs (output 3) increase values by $115/\sqrt{2}$.

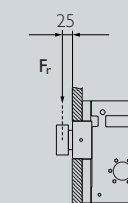
Bearing forces



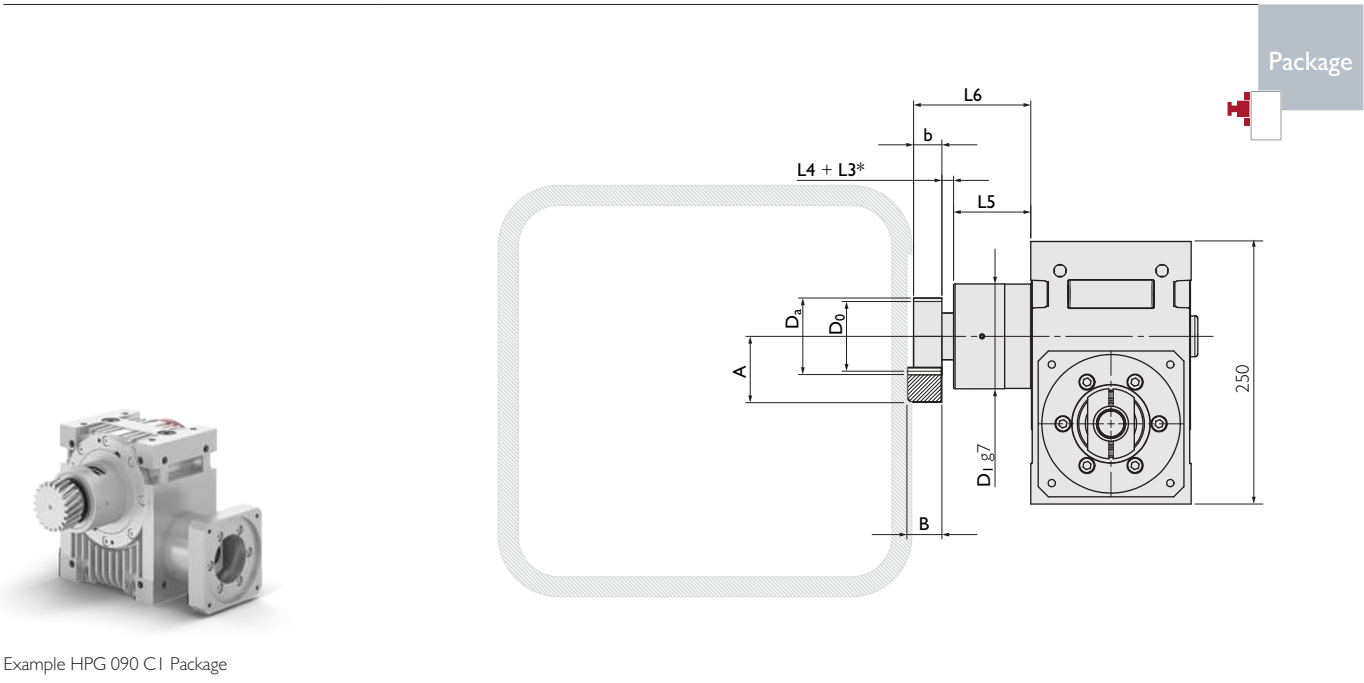
Package

		Output Flange including Bearing & Pinion					
Radial rigidity	C ₃	[N/mm]	45000				
Speed	n _{2N}	[rpm]	1500	750	400	150	100
Max. radial force ¹⁾	F _{rmax}	[N]	4800	5900	7200	8800	9700

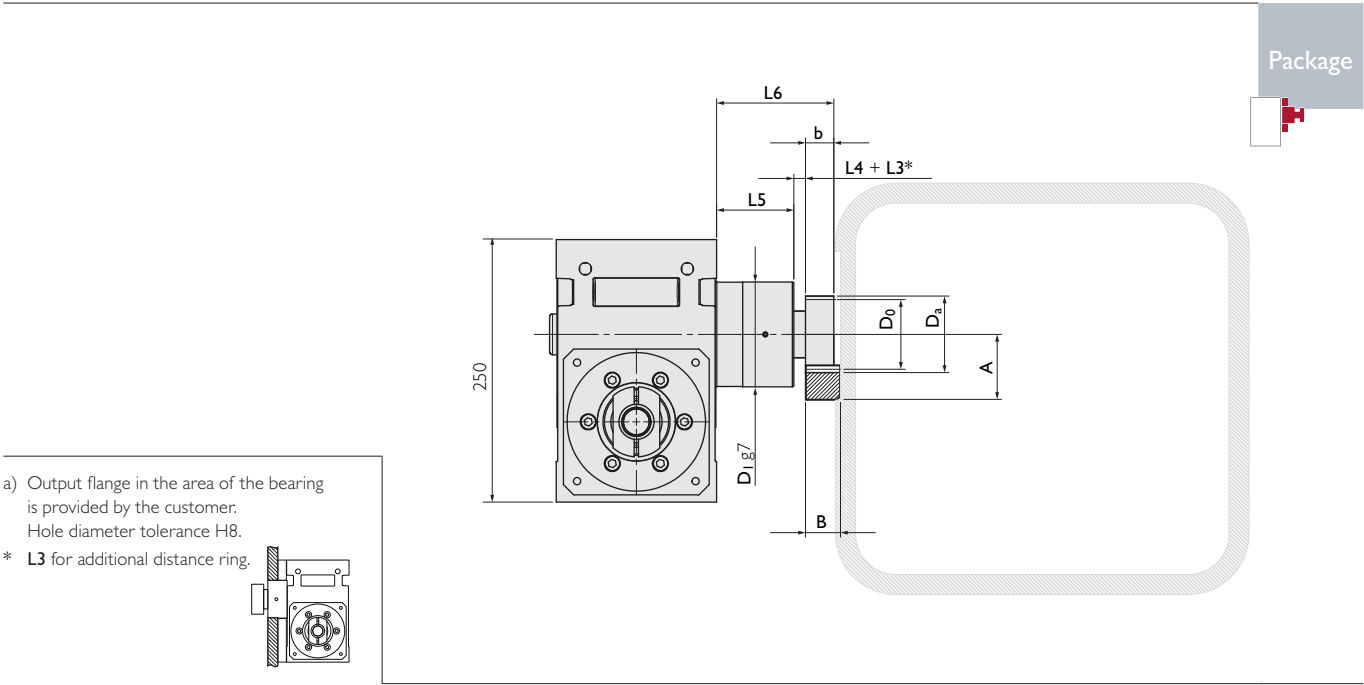
- j) Bearing forces: Values valid at duty cycle of 40% at a distance of 25mm from the end of the bearing.



Output Flange including Bearing & Pinion^{a)}



Example HPG 090 C1 Package



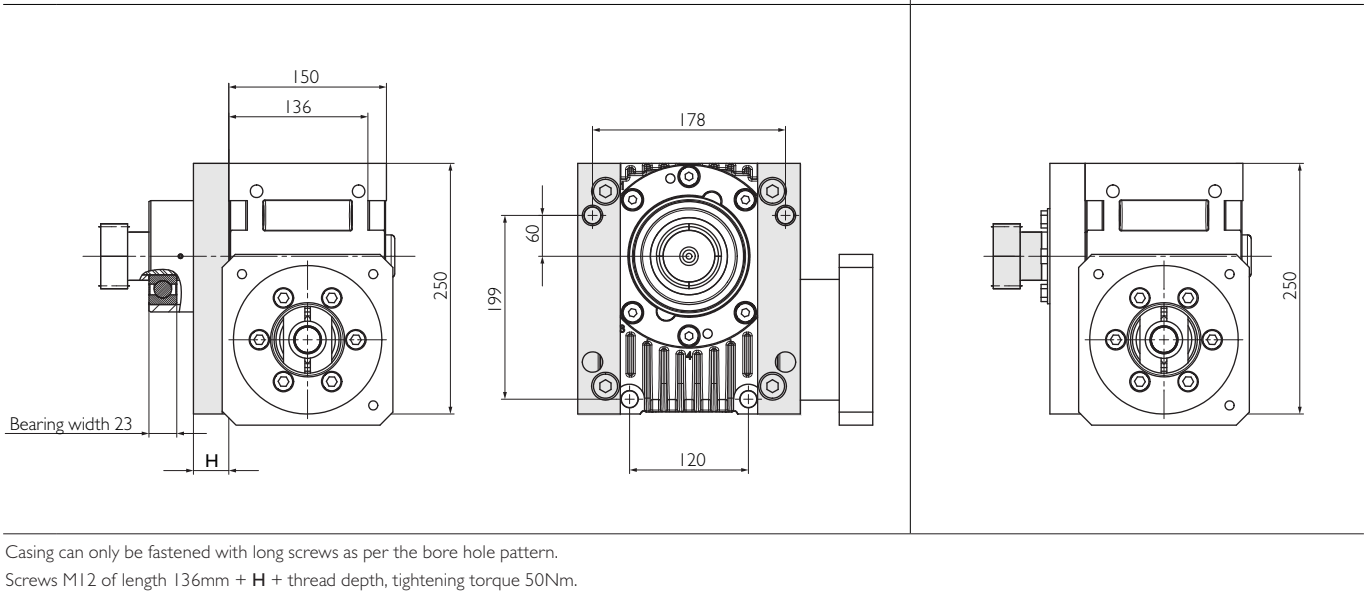
a) Output flange in the area of the bearing is provided by the customer. Hole diameter tolerance H8.
* L3 for additional distance ring.

Geometric information

Helical modular pitch	Art. Nr.	m	z	A	b	B	Da	D0	D1	L4	L5	L6
Pinion 1	211420	3	20	57.83	30	29	69.66	63.66	98	12.5	63	105.5
											104.5	147
Pinion 2	211520	4	20	77.44	40	39	92.88	84.88	98	18	63	121
											104.5	162.5
Straight modular pitch	Art. Nr.	m	z	A	b	B	Da	D0	D1	L4	L5	L6
Pinion 3	201420	3	20	56.0	30	29	66.0	60.0	98	12.5	63	105.5
											104.5	147
Pinion 4	201520	4	20	75.0	40	39	88.0	80.0	98	18	63	121
											104.5	162.5

Spacer Elements

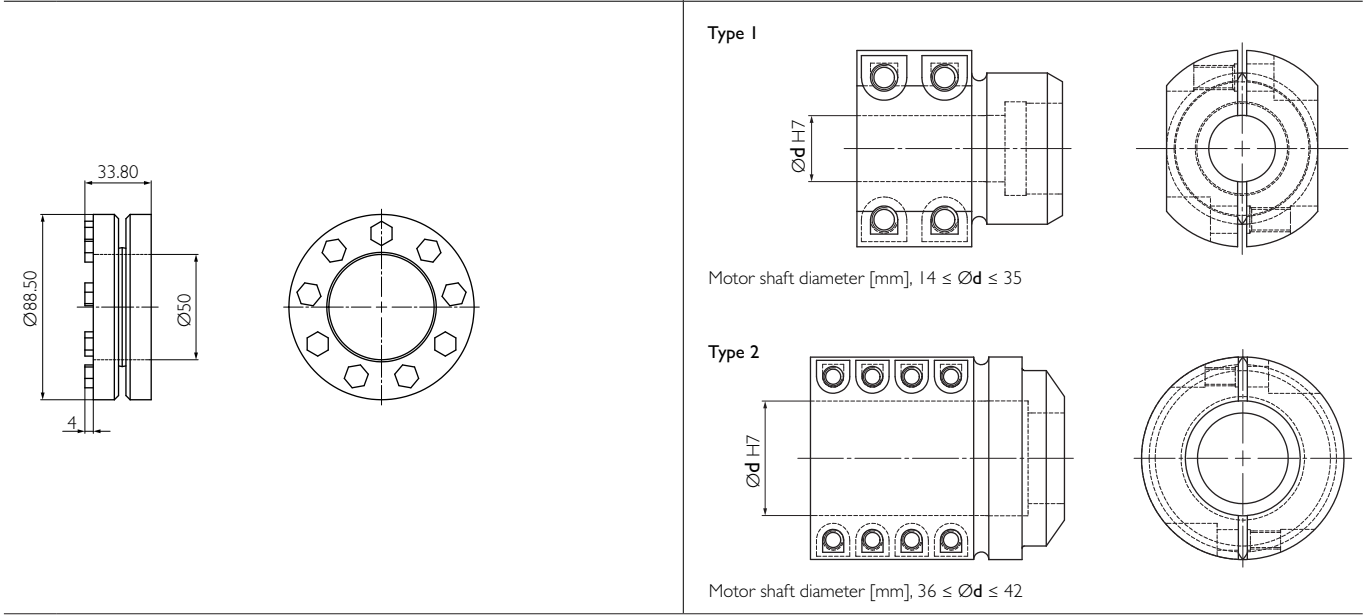
with Pinion special solutions on request



Casing can only be fastened with long screws as per the bore hole pattern. Screws M12 of length 136mm + H + thread depth, tightening torque 50Nm.

Shrink Disc

Coupling

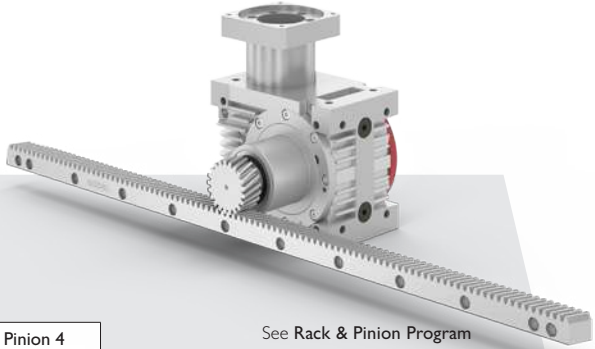


Your ideal Drive Train

Our Function Package with high-performance angle gearbox, output flange, pinion and rack by Güdel.

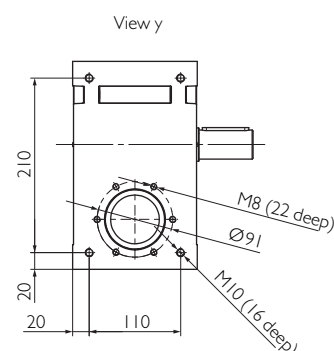
			Pinion 1	Pinion 2	Pinion 3	Pinion 4
Maximum acceleration force	F_N	[N]	13700	25420	13697	24068
Maximum acceleration torque	T_N	[Nm]	436	1079	411	963

Higher value for rack and pinion taking account of the number of load cycles: 1×10^6 for the rack; 1×10^7 for the pinion. Both in cycle mode.

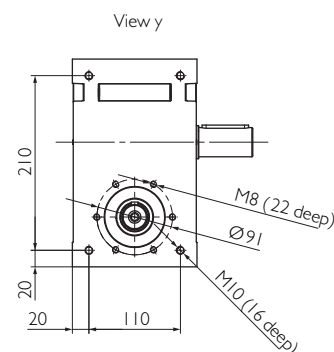


See Rack & Pinion Program of your ideal Drive Train on pages 104 et seq.

See Flowcharts to find your ideal Drive Train on pages 116 et seq.

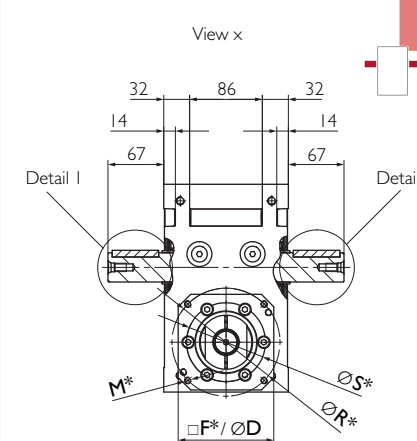
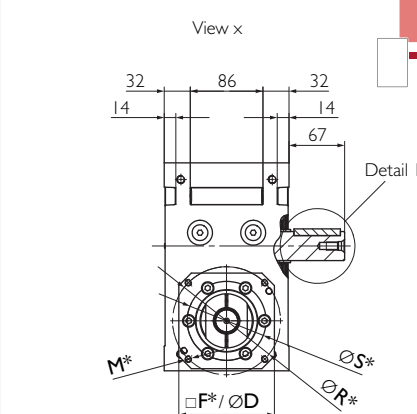
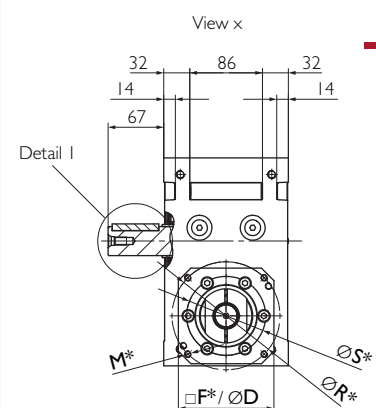
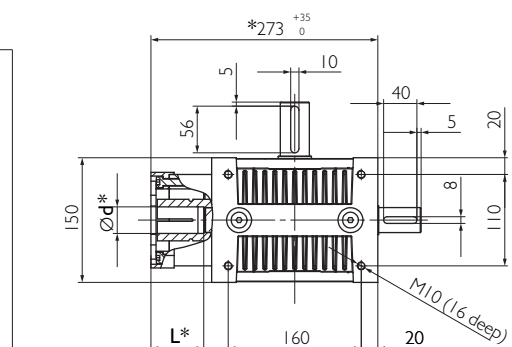
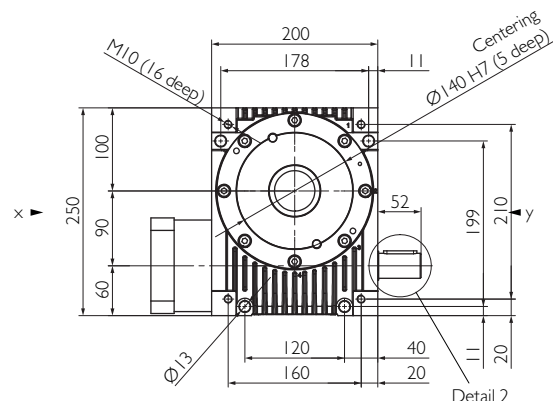
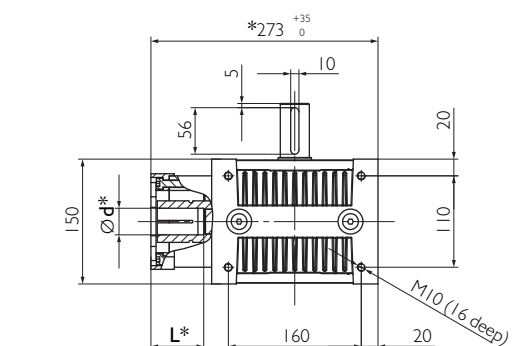
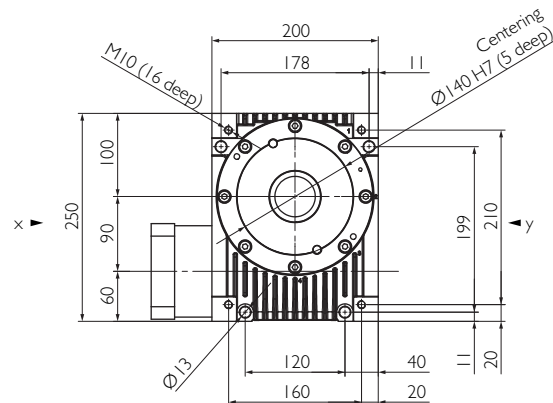
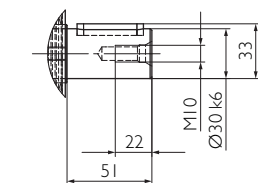


Example HPG 090 B4

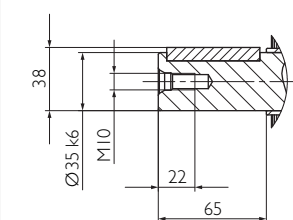


* Motor-specific gearbox dimensions
 $\varnothing d$: $\varnothing$ motor shaft [mm], $14 \leq \varnothing d \leq 42$
 L: Motor shaft length [mm], $40 \leq L \leq 82$

Detail 2



Detail 1



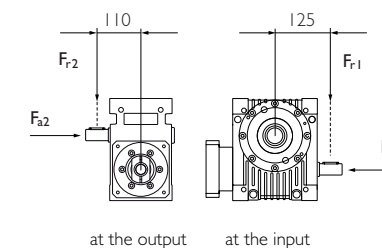
* Motor-specific gearbox dimensions
S: min. 75 [mm], **R:** Pitch circle Ø [mm], **M:** Bore hole Ø or thread [mm], **□F/ØD:** Specify flange [mm]

Performance

Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	469 92	679 92	784 91	761 91	674 90	782 88	726 87	712 84	700 80	727 74	527 71	752 61	527 50
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	350 92	528 92	624 92	615 92	551 91	644 89	601 88	592 85	660 82	645 76	527 72	640 63	527 57
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	279 92	432 93	518 92	516 92	466 91	547 90	513 88	507 85	565 83	553 77	527 72	550 64	527 57
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	174 92	279 92	343 92	348 92	318 91	377 89	356 88	354 85	395 82	388 76	396 70	386 62	396 55
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	126 91	206 92	257 92	262 91	241 90	288 88	273 86	272 83	303 81	298 74	305 68	297 60	305 53
Max. acceleration torque		T _{2B}	[Nm]	470	790									530	790	530
Emergency stop torque		T _{2Not}	[Nm]	900									700	900	700	
Idling torque ^{a)}		T ₀₁₂	[Nm]	2.8			2.5			2						
Max. input speed		n _{1Max}	[rpm]	4500												
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<10	<8	<7	<7	<6	<6					<5		
	PR	j _t	[arcmin]	<6.5	<5	<4.5	<4	<4	<3.5					<3		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	5.5	10.8	15.9	18.3	20.8	23.3	25.8	28.3	31.3	33.2	32	35	32
Stability at the output		C _{2K}	[Nm/arcmin]	73												
Max. axial force ^{c)d)} at the output		F _{a2max}	[N]	820	1400	1400	2800	4400	5000	6600	8300	8100	8700	9100	9200	9400
Max. radial force ^{c)e)} at the output		F _{r2max}	[N]	800	930	1000	1400	3000	3100	3700	4200	4300	4400	4500	4500	4600
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	88	100	110	160	330	350	400	460	470	490	500	500	500
Max. axial force ^{c)d)} at the input		F _{a1max}	[N]	3100	1600	1100	1700	2800	2000	2700	2900	2300	2500	2700	2600	2800
Max. radial force ^{c)f)} at the input		F _{r1max}	[N]	1500	910	640	990	1600	1200	1500	1700	1300	1400	1600	1500	1600
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁵ kg m ²]	383	206	144	116	100	85	78	72	70	67	67	66	65
	Type 2 ⁱ⁾	J ₁	[10 ⁻⁵ kg m ²]	453	276	214	186	170	155	148	142	140	137	136	136	135
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	25												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

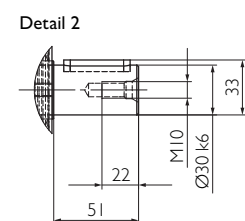
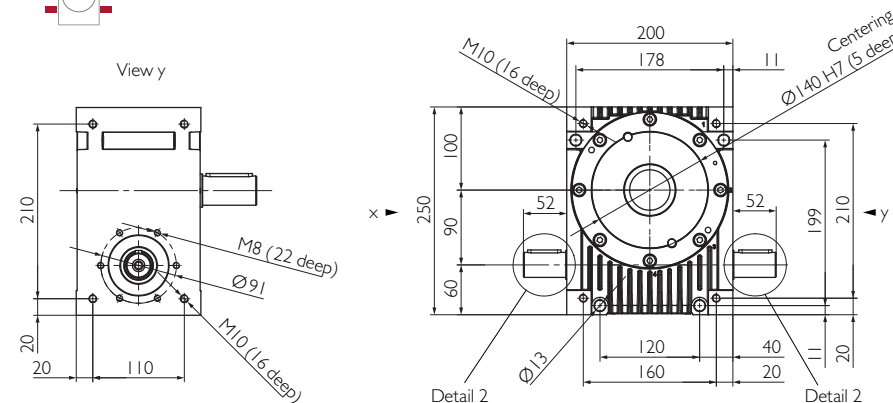
- a) approximate, at $n_1 = 3000$ rpm and operating temperature.
- b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- c) Bearing forces: Values valid at $n_1 = 1500$ rpm; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- c) d) in relation to shaft center.
- c) e) at a distance of 110 mm from the middle of the casing.
- c) f) at a distance of 125 mm from the middle of the casing.
- g) in relation to the input, including coupling.
- g) h) Motor shaft diameter $\varnothing$ d from $\varnothing 14$ to $\varnothing 35$, calculated at $\varnothing 24$ mm.
- g) i) Motor shaft diameter $\varnothing$ d from $\varnothing 36$ to $\varnothing 42$, calculated at $\varnothing 38$ mm.

Bearing forces

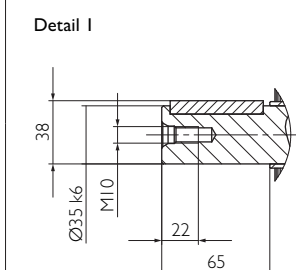
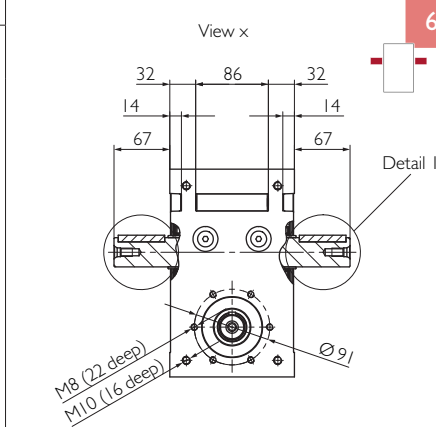
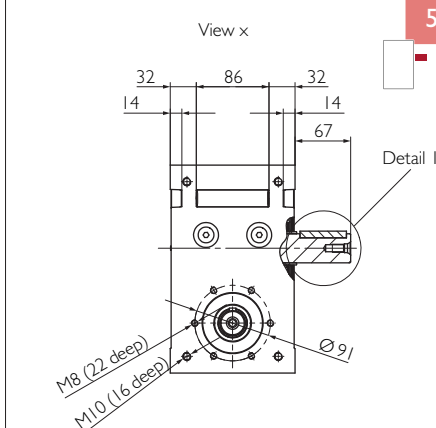
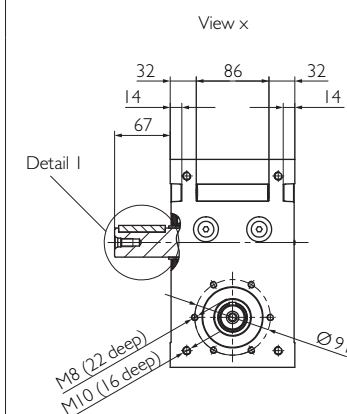




Example HPG 090 C4



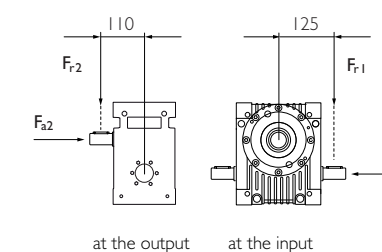
4



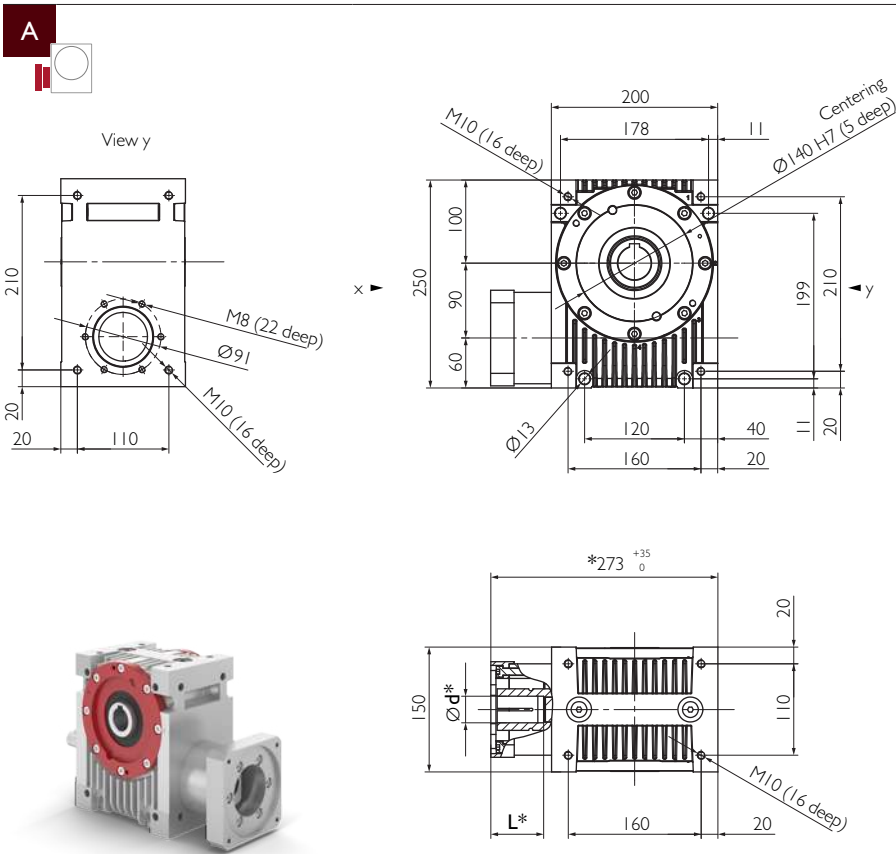
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	469 92	679 92	784 91	761 91	674 90	782 88	726 87	712 84	700 80	727 74	527 71	752 61	527 50
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	350 92	528 92	624 92	615 92	551 91	644 89	601 88	592 85	660 82	645 76	527 72	640 63	527 57
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	279 92	432 93	518 92	516 92	466 91	547 90	513 88	507 85	565 83	553 77	527 72	550 64	527 57
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	174 92	279 92	343 92	348 92	318 91	377 89	356 88	354 85	395 82	388 76	396 70	386 62	396 55
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	126 91	206 92	257 92	262 91	241 90	288 88	273 86	272 83	303 81	298 74	305 68	297 60	305 53
Max. acceleration torque		T _{2B}	[Nm]	470	790									530	790	530
Emergency stop torque		T _{2Not}	[Nm]	900									700	900	700	
Idling torque ^{a)}		T ₀₁₂	[Nm]	2.8			2.5			2						
Max. input speed		n _{1Max}	[rpm]	4500												
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<10	<8	<7	<7	<6	<6					<5		
	PR	j _t	[arcmin]	<6.5	<5	<4.5	<4	<4	<3.5					<3		
Torsional rigidity vom Abrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	5.5	10.8	15.9	18.3	20.8	23.3	25.8	28.3	31.3	33.2	32	35	32
Stability at the output		C _{2K}	[Nm/arcmin]	73												
Max. axial force ^{c)d)} at the output		F _{a2max}	[N]	820	1400	1400	2800	4400	5000	6600	8300	8100	8700	9100	9200	9400
Max. radial force ^{c)e)} at the output		F _{r2max}	[N]	800	930	1000	1400	3000	3100	3700	4200	4300	4400	4500	4500	4600
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	88	100	110	160	330	350	400	460	470	490	500	500	500
Max. axial force ^{c)d)} at the input		F _{a1max}	[N]	3100	1600	1100	1700	2800	2000	2700	2900	2300	2500	2700	2600	2800
Max. radial force ^{c)f)} at the input		F _{r1max}	[N]	1500	910	640	990	1600	1200	1500	1700	1300	1400	1600	1500	1600
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁵ kg m ²]	336	160	98	70	54	39	32	26	24	21	20	19	19
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	22												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- approximate, at $n_1 = 3000$ rpm and operating temperature.
- Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- Bearing forces: Values valid at $n_1 = 1500$ rpm; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- d) in relation to shaft center.
- e) at a distance of 110 mm from the middle of the casing.
- f) at a distance of 125 mm from the middle of the casing.
- g) in relation to the input.

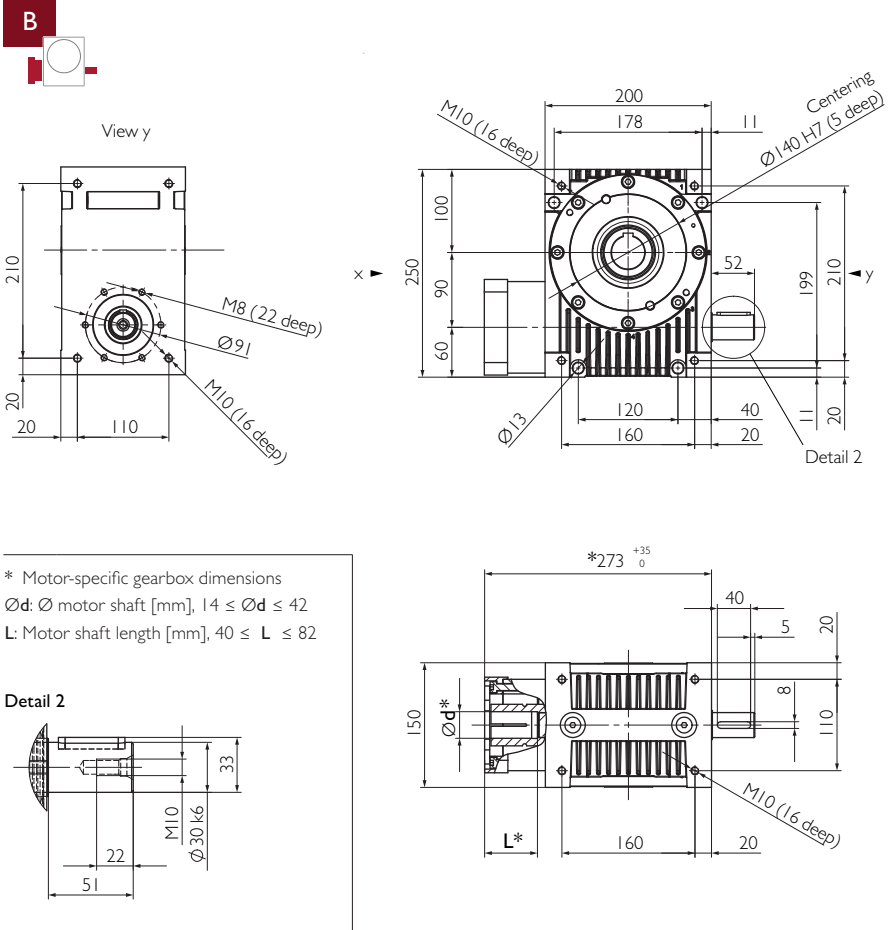
Bearing forces



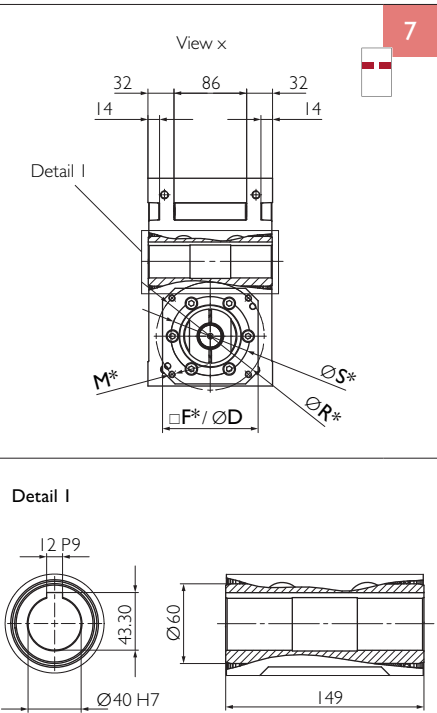
Input



Example HPG 090 B7



Output

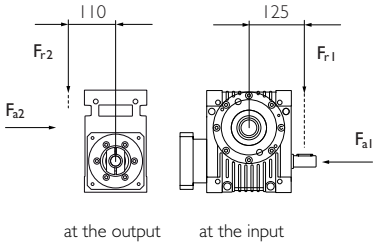


* Motor-specific gearbox dimensions
S: min. 75 [mm], R: Pitch circle Ø [mm], M: Bore hole Ø or thread [mm], □F/ØD: Specify flange [mm]

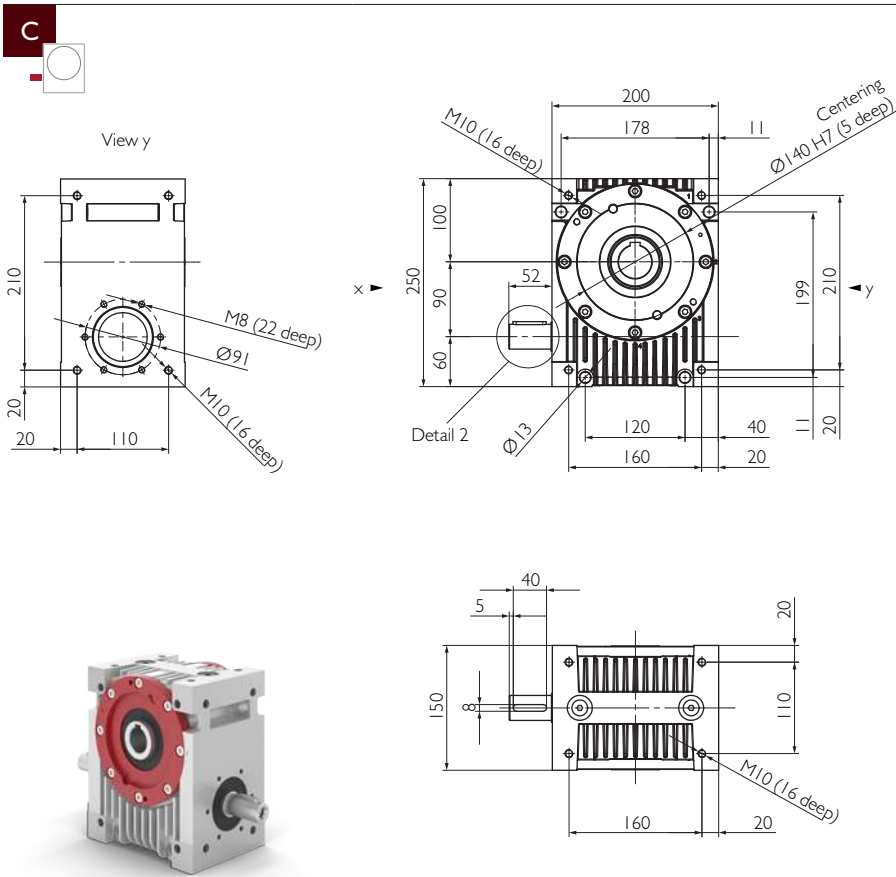
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60	
Nominal torque at the output Efficiency	n _{1N} = 500rpm	T _{2N}	[Nm]	469	679	784	761	674	782	726	712	700	727	527	752	527	
		η	[%]	92	92	91	91	90	88	87	84	80	74	71	61	50	
	n _{1N} = 1000rpm	T _{2N}	[Nm]	350	528	624	615	551	644	601	592	660	645	527	640	527	
		η	[%]	92	92	92	92	91	89	88	85	82	76	72	63	57	
	n _{1N} = 1500rpm	T _{2N}	[Nm]	279	432	518	516	466	547	513	507	565	553	527	550	527	
		η	[%]	92	93	92	92	91	90	88	85	83	77	72	64	57	
	n _{1N} = 3000rpm	T _{2N}	[Nm]	174	279	343	348	318	377	356	354	395	388	396	386	396	
		η	[%]	92	92	92	92	91	89	88	85	82	76	70	62	55	
	n _{1N} = 4500rpm	T _{2N}	[Nm]	126	206	257	262	241	288	273	272	303	298	305	297	305	
		η	[%]	91	92	92	91	90	88	86	83	81	74	68	60	53	
Max. acceleration torque		T _{2B}	[Nm]	470	790										530	790	530
Emergency stop torque		T _{2N} ot	[Nm]	900										700	900	700	
Idling torque ^{a)}		T ₀₁₂	[Nm]	2.8			2.5			2							
Max. input speed		n ₁ Max	[rpm]	4500													
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<10	<8	<7	<7	<6	<6					<5			
	PR	j _t	[arcmin]	<6.5	<5	<4.5	<4	<4	<3.5					<3			
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	5.5	10.8	15.9	18.3	20.8	23.3	25.8	28.3	31.3	33.2	32	35	32	
Stability at the output		C _{2K}	[Nm/arcmin]	95													
Max. axial force ^{c)d)} at the output		F _{a2} max	[N]	6200	8200	7800	9200	11000	12000	14000	17000	18000	18000	18000	19000	19000	
Max. radial force ^{c)e)} at the output		F _{r2} max	[N]	5300	6400	5500	5800	6500	6800	7500	8400	8600	8700	8800	8800	8800	
Max. overturning torque ^{c)} at the output		M ₂ max	[Nm]	590	700	600	640	710	750	830	920	940	960	970	970	970	
Max. axial force ^{c)d)} at the input		F _{a1} max	[N]	3100	1600	1100	1700	2800	2000	2700	2900	2300	2500	2700	2600	2800	
Max. radial force ^{c)f)} at the input		F _{r1} max	[N]	1500	910	640	990	1600	1200	1500	1700	1300	1400	1600	1500	1600	
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁵ kg m ²]	354	193	137	111	97	83	77	72	70	67	66	66	65	
	Type 2 ⁱ⁾	J ₁	[10 ⁻⁵ kg m ²]	424	263	207	181	167	153	147	142	140	137	136	136	135	
Service life		L _h	[h]	25000													
Weight without motor components		m	[kg]	25													
Max. permissible housing temperature			[°C]	+90													
Ambient temperature			[°C]	-15 up to +50													
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)															
Painting		None															
Protection class		IP65															

- a) approximate, at $n_1 = 3000\text{rpm}$ and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
c) Bearing forces: Values valid at $n_1 = 1500\text{rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 110 mm from the middle of the casing.
c) f) at a distance of 125 mm from the middle of the casing.
g) in relation to the input, including coupling.
c) h) Motor shaft diameter $\varnothing d$ from $\varnothing 14$ to $\varnothing 35$, calculated at $\varnothing 24\text{mm}$.
c) i) Motor shaft diameter $\varnothing d$ from $\varnothing 36$ to $\varnothing 42$, calculated at $\varnothing 38\text{mm}$.

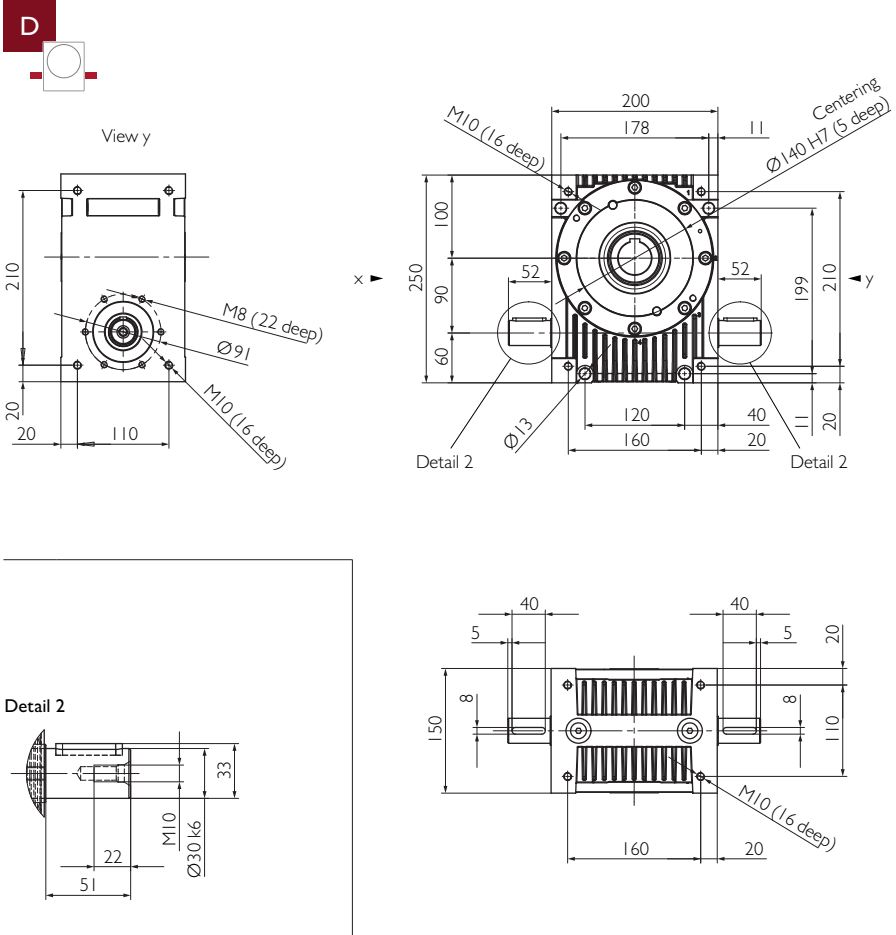
Bearing forces



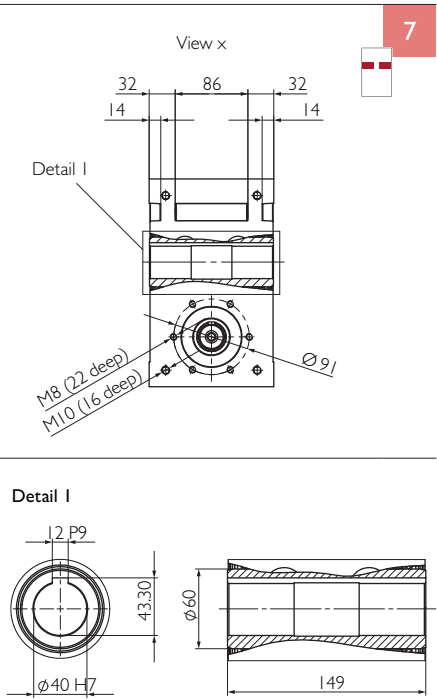
Input



Example HPG 090 D7



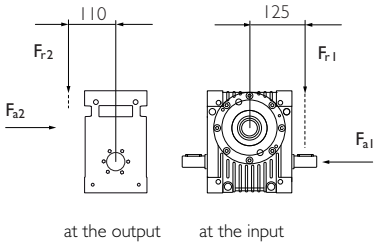
Output

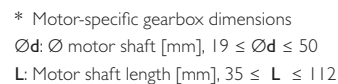


Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500rpm	T _{2N}	[Nm]	469	679	784	761	674	782	726	712	700	727	527	752	527
		η	[%]	92	92	91	91	90	88	87	84	80	74	71	61	50
	n _{1N} = 1000rpm	T _{2N}	[Nm]	350	528	624	615	551	644	601	592	660	645	527	640	527
		η	[%]	92	92	92	92	91	89	88	85	82	76	72	63	57
	n _{1N} = 1500rpm	T _{2N}	[Nm]	279	432	518	516	466	547	513	507	565	553	527	550	527
		η	[%]	92	93	92	92	91	90	88	85	83	77	72	64	57
	n _{1N} = 3000rpm	T _{2N}	[Nm]	174	279	343	348	318	377	356	354	395	388	396	386	396
		η	[%]	92	92	92	92	91	89	88	85	82	76	70	62	55
	n _{1N} = 4500rpm	T _{2N}	[Nm]	126	206	257	262	241	288	273	272	303	298	305	297	305
		η	[%]	91	92	92	91	90	88	86	83	81	74	68	60	53
Max. acceleration torque		T _{2B}	[Nm]	470	790									530	790	530
Emergency stop torque		T _{2not}	[Nm]	900										700	900	700
Idling torque ^{a)}		T ₀₁₂	[Nm]	2.8			2.5			2						
Max. input speed		n _{1Max}	[rpm]	4500												
Max. backlash ^{b)} at the output	PS	j _k	[arcmin]	<10	<8	<7	<7	<6	<6					<5		
	PR	j _k	[arcmin]	<6.5	<5	<4.5	<4	<4	<3.5					<3		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	5.5	10.8	15.9	18.3	20.8	23.3	25.8	28.3	31.3	33.2	32	35	32
Stability at the output		C _{2K}	[Nm/arcmin]	95												
Max. axial force ^{c)d)} at the output		F _{a2max}	[N]	6200	8200	7800	9200	11000	12000	14000	17000	18000	18000	18000	19000	19000
Max. radial force ^{c)e)} at the output		F _{r2max}	[N]	5300	6400	5500	5800	6500	6800	7500	8400	8600	8700	8800	8800	8800
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	590	700	600	640	710	750	830	920	940	960	970	970	970
Max. axial force ^{c)d)} at the input		F _{a1max}	[N]	3100	1600	1100	1700	2800	2000	2700	2900	2300	2500	2700	2600	2800
Max. radial force ^{c)f)} at the input		F _{r1max}	[N]	1500	910	640	990	1600	1200	1500	1700	1300	1400	1600	1500	1600
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁵ kg m ²]	308	147	91	65	51	37	30	25	23	21	20	19	19
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	22												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000\text{rpm}$ and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
c) Bearing forces: Values valid at $n_1 = 1500\text{rpm}$; $1/2 T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 110 mm from the middle of the casing.
c) f) at a distance of 125 mm from the middle of the casing.
g) in relation to the input.

Bearing forces





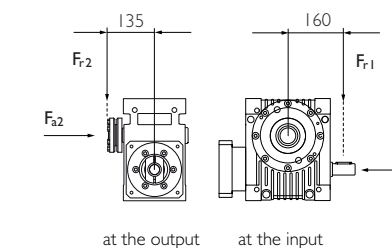
Technical drawing showing a shaft-hub assembly. The shaft has a diameter of $\varnothing 40$ k6 and a length of 60. The hub has an inner diameter of M12 and an outer diameter of 43. The shaft is inserted into the hub, and the assembly is shown with a semi-circular end view on the left.



* Motor-specific gearbox dimensions
S: min. 95 [mm], **R:** Pitch circle Ø [mm], **M:** Bore hole Ø or thread [mm], **□F/ØD:** Specify flange [mm]

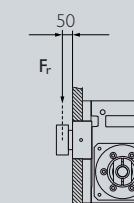
- approximate, at $n_1 = 3000$ rpm and operating temperature.
- Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- Bearing forces: Values valid at $n_1 = 1500$ rpm; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
 - in relation to shaft center.
 - at a distance of 135 mm from the middle of the casing.
 - at a distance of 160 mm from the middle of the casing.
- in relation to the input, including coupling and shrink disc at the output (output 1 & 2) with two shrink discs (output 3) increase values by 340/1².
 - Motor shaft diameter $\varnothing d$ from $\varnothing 19$ to $\varnothing 42$, calculated at $\varnothing 28$ mm.
 - Motor shaft diameter $\varnothing d$ from $\varnothing 43$ to $\varnothing 50$, calculated at $\varnothing 48$ mm.

Bearing forces



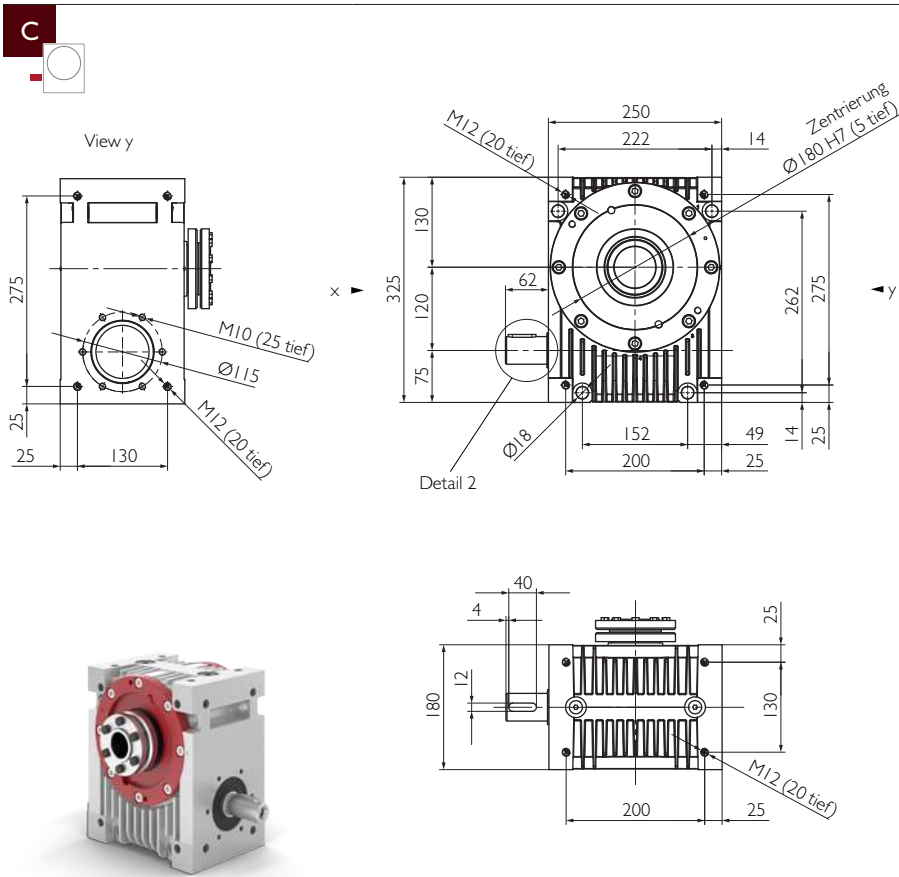
			Output Flange including Bearing & Pinion				
Radial rigidity	C ₃	[N/mm]	47000				
Speed	n _{2N}	[rpm]	1500	750	400	150	100
Max. radial force ¹⁾	F _{rmax}	[N]	11500	13000	17000	21000	24000

j) Bearing forces: Values valid at duty cycle of 40% at a distance of 50mm from the end of the bearing.

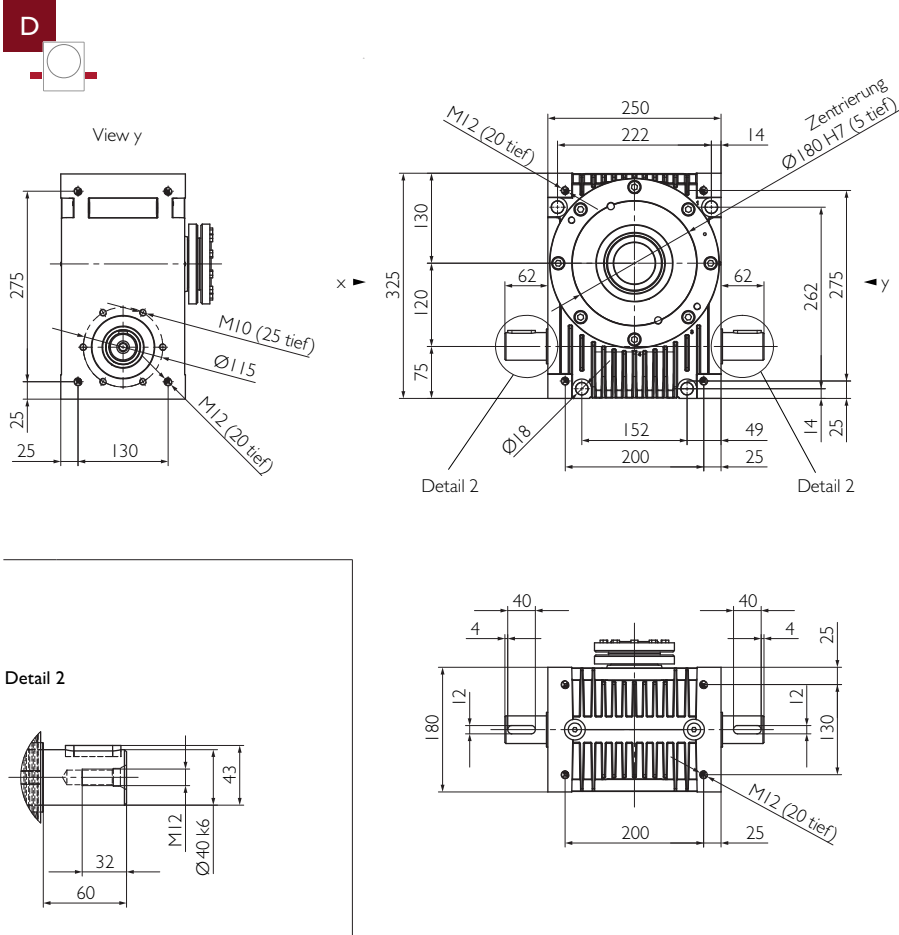


Detailed information about the **Package, Options & Accessories** on pages 88 and 89.

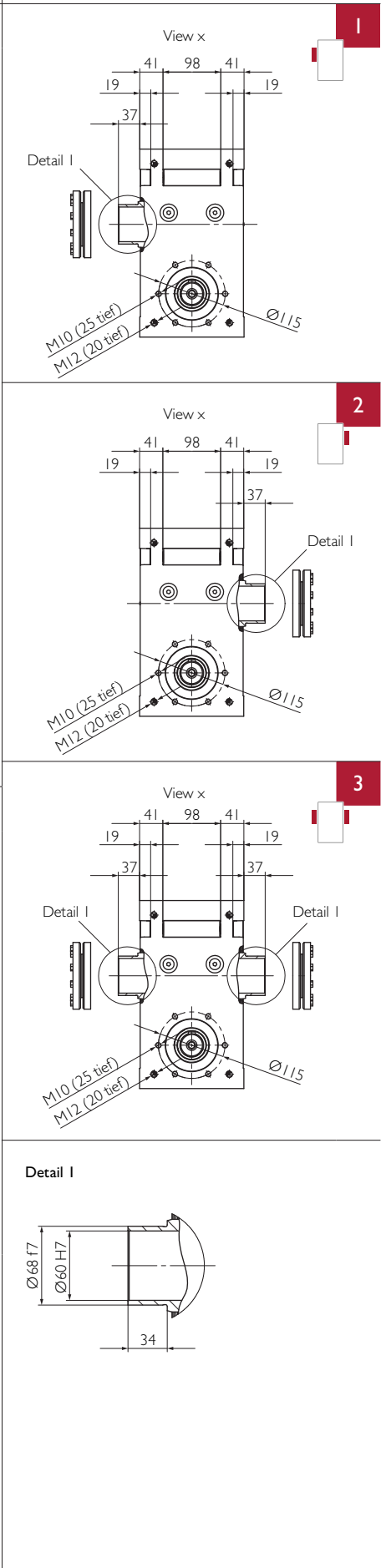
Input



Example HPG 020 A1



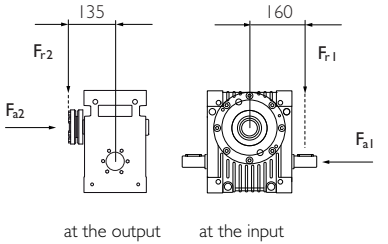
Output



Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N}	[Nm]	1177	1732	2018	1969	1752	2038	1895	1863	1824	1900	1364	1970	1364
		η	[%]	93	93	93	93	92	90	89	87	84	78	75	66	61
	n _{1N} = 1000 rpm	T _{2N}	[Nm]	836	1284	1534	1523	1371	1609	1505	1487	1658	1622	1364	1612	1364
		η	[%]	94	94	94	93	93	91	90	88	85	80	76	68	62
	n _{1N} = 1500 rpm	T _{2N}	[Nm]	648	1020	1237	1241	1126	1329	1248	1237	1380	1353	1364	1345	1364
		η	[%]	94	94	94	93	93	91	90	88	86	80	76	69	62
	n _{1N} = 3000 rpm	T _{2N}	[Nm]	387	631	783	798	733	873	826	822	918	903	921	899	921
		η	[%]	93	94	93	93	93	91	90	88	85	80	74	68	60
	n _{1N} = 4500 rpm	T _{2N}	[Nm]	276	457	573	588	543	650	617	616	688	677	689	675	689
		η	[%]	93	93	93	93	92	91	89	87	84	79	73	66	58
Max. acceleration torque		T _{2B}	[Nm]	1200	2040									1400	2040	1400
Emergency stop torque		T _{2not}	[Nm]	2300										1600	2300	1600
Idling torque ^{a)}		T ₀₁₂	[Nm]	4.5			4			3						
Max. input speed		n _{1Max}	[rpm]	4500												
Max. backlash ^{b)} at the output	PS	j _k	[arcmin]	<8	<7	<6	<6	<5	<5					<4		
	PR	j _k	[arcmin]	<5.5	<4.5	<4	<3.5	<3	<3					<2.5		
Torsional rigidity vom Abtrieb zum Eintrieb		C ₂₁	[Nm/arcmin]	11.5	19	24.5	26.5	29	31.5	34	36.5	38.5	40.5	39	42.5	39
Stability at the output		C _{2K}	[Nm/arcmin]	165												
Max. axial force ^{c)} ^{d)} at the output		F _{a2max}	[N]	7000	9600	9500	12000	16000	17000	21000	25000	26000	27000	27000	27000	28000
Max. radial force ^{c)} ^{e)} at the output		F _{r2max}	[N]	7700	8100	7300	8800	9900	10000	12000	13000	13000	14000	14000	14000	14000
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	1000	1100	980	1200	1300	1400	1600	1800	1800	1800	1800	1900	1900
Max. axial force ^{c)} ^{d)} at the input		F _{a1max}	[N]	3600	1800	730	1700	3600	2100	3300	3700	2500	2900	2700	3100	2700
Max. radial force ^{c)} ^{f)} at the input		F _{r1max}	[N]	1900	950	390	930	1900	1200	1800	2000	1300	1600	1400	1700	1500
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁵ kg m ²]	1392	660	403	285	220	156	127	103	94	83	80	76	75
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	48												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000 \text{ rpm}$ and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
c) Bearing forces: Values valid at $n_1 = 1500 \text{ rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 135 mm from the middle of the casing.
c) f) at a distance of 160 mm from the middle of the casing.
g) in relation to the input, including shrink disc at the output (output 1 & 2), with two shrink discs (output 3) increase values by 340/i².

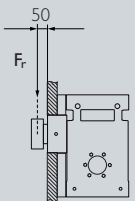
Bearing forces



Package

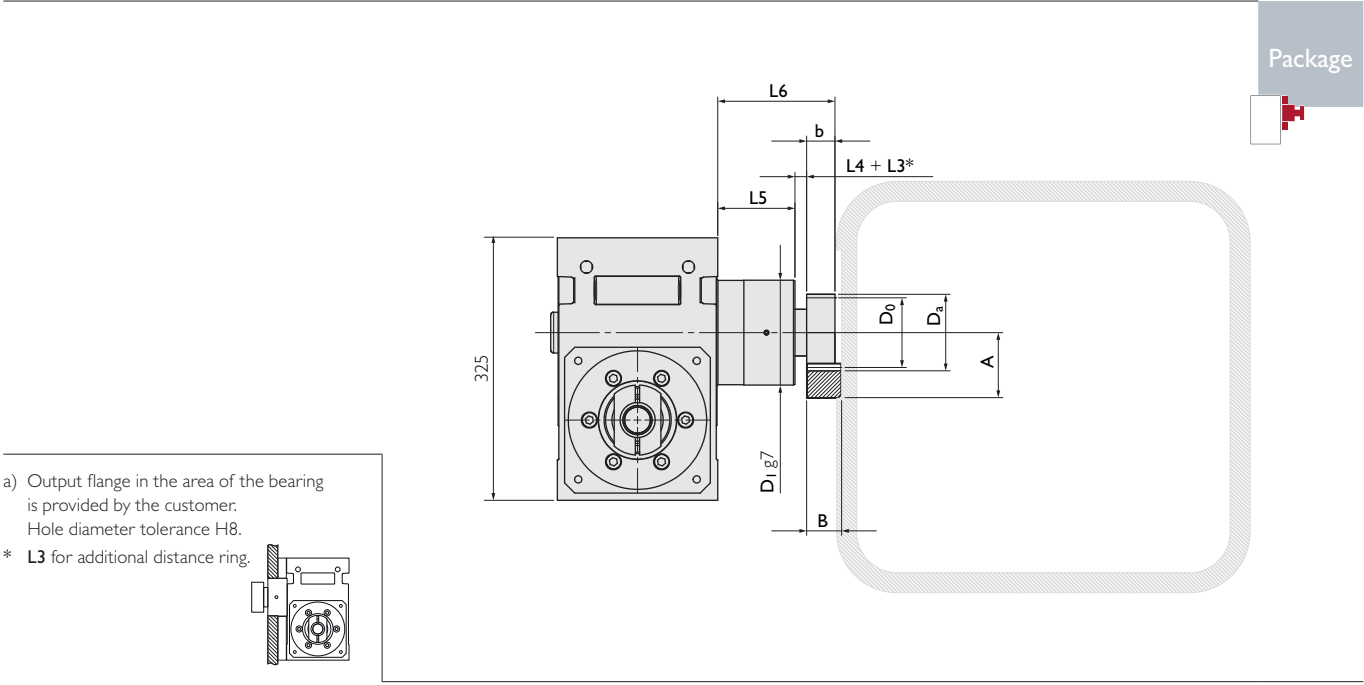
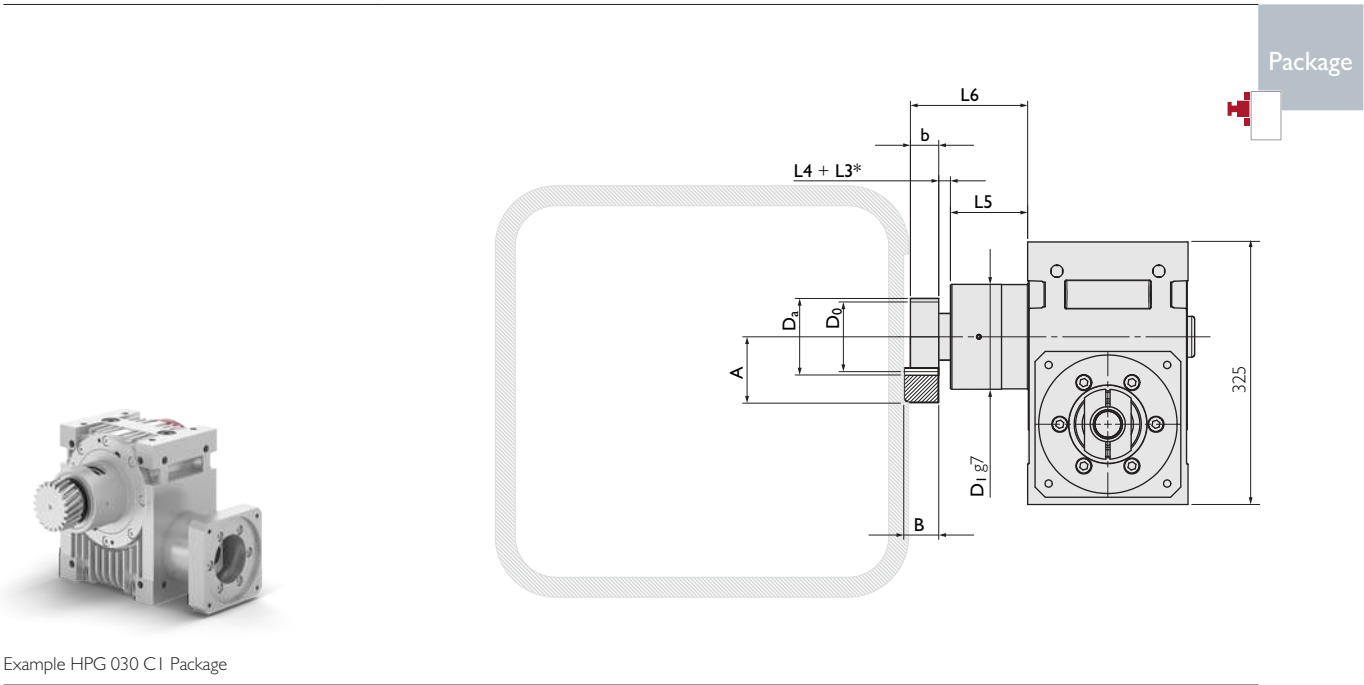
			Output Flange including Bearing & Pinion				
Radial rigidity	C ₃	[N/mm]	47000				
Speed	n _{2N}	[rpm]	1500	750	400	150	100
Max. radial force ¹⁾	F _{rmax}	[N]	11500	13000	17000	21000	24000

j) Bearing forces: Values valid at duty cycle of 40% at a distance of 50 mm from the end of the bearing.



Detailed information about the Package, Options & Accessories on pages 88 and 89.

Output Flange including Bearing & Pinion^{a)}



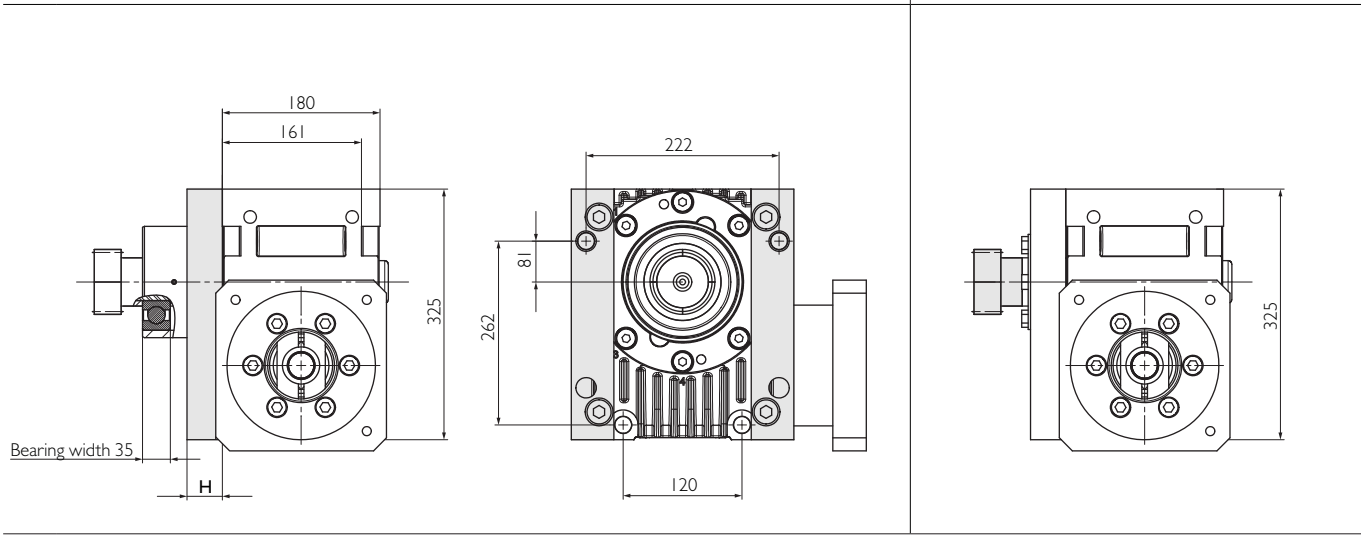
Geometric information

Helical modular pitch	Part. No.	m	z	A	b	B	D _a	D ₀	D _I	L4	L5	L6
Pinion 1	211521	4	20	77.44	40	39	92.9	84.88	180	14.5	123	177.5
Pinion 2	211620	5	20	87.05	50	49	116.1	106.1	180	35	123	208

Straight modular pitch	Part. No.	m	z	A	b	B	D _a	D ₀	D _I	L4	L5	L6
Pinion 3	201620	5	20	84.0	50	49	110.0	100.0	180	35	123	208
Pinion 4	201720	6	20	103.0	60	60	132.0	120.0	180	35	123	218
Pinion 5	201820	8	20	151.0	80	79	176.0	160.0	180	35	123	238

Spacer Elements

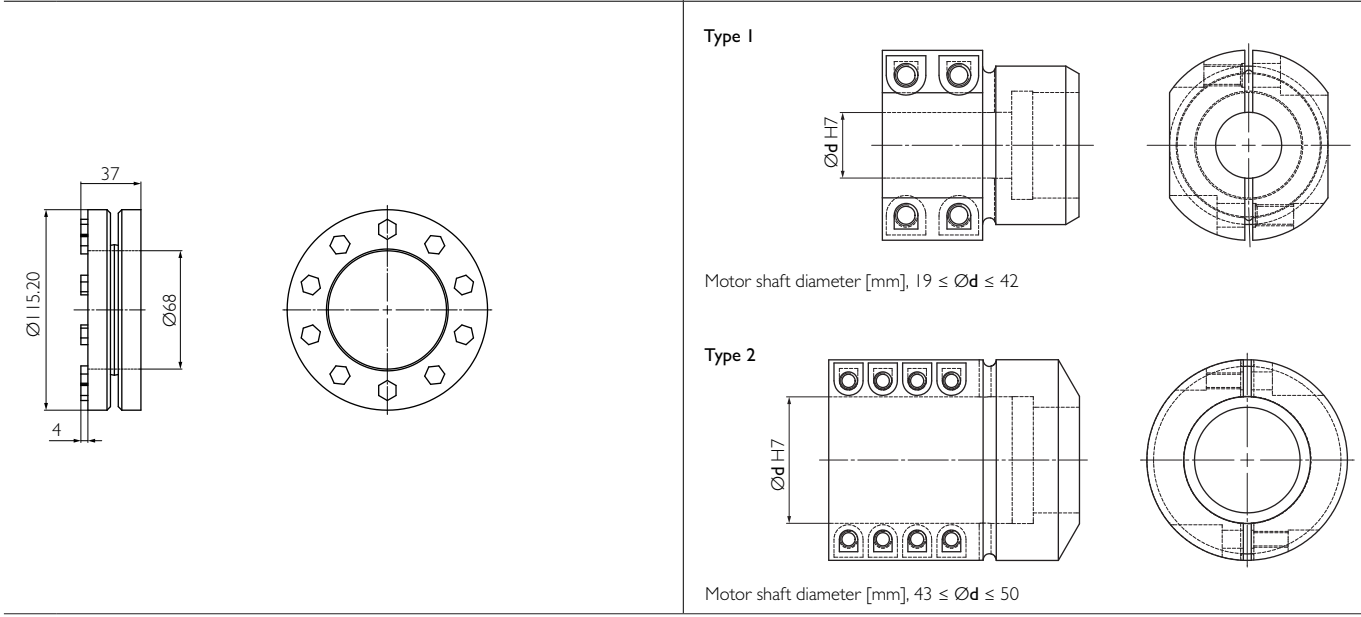
with Pinion special solutions on request



Casing can only be fastened with long screws as per the bore hole pattern.
Screws M16 of length 161 mm + H + thread depth, tightening torque 120Nm.

Shrink Disc

Coupling



Your ideal Drive Train

Our Function Package with high-performance angle gearbox, output flange, pinion and rack by Güdel.

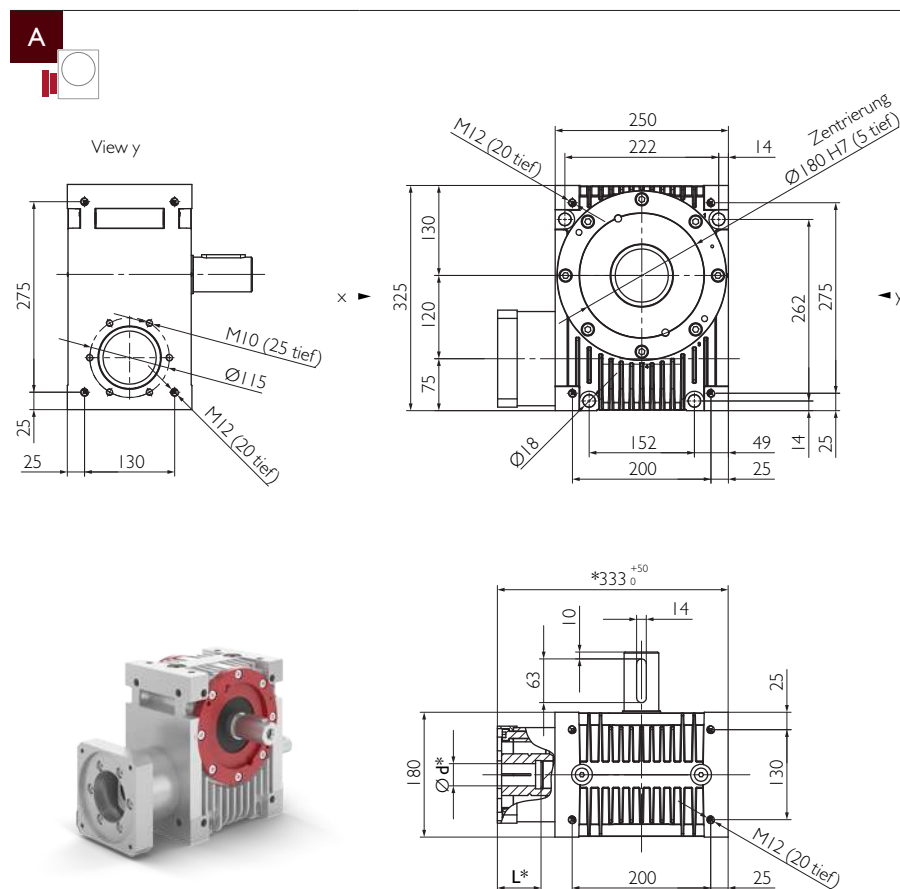
			Pinion 1	Pinion 2	Pinion 3	Pinion 4	Pinion 5
Maximum acceleration force	F _N	[N]	25420	40680	37317	52880	91220
Maximum acceleration torque	T _N	[Nm]	1079	2158	1866	3173	7298

Higher value for rack and pinion taking account of the number of load cycles:
1×10⁶ for the rack; 1×10⁷ for the pinion. Both in cycle mode.

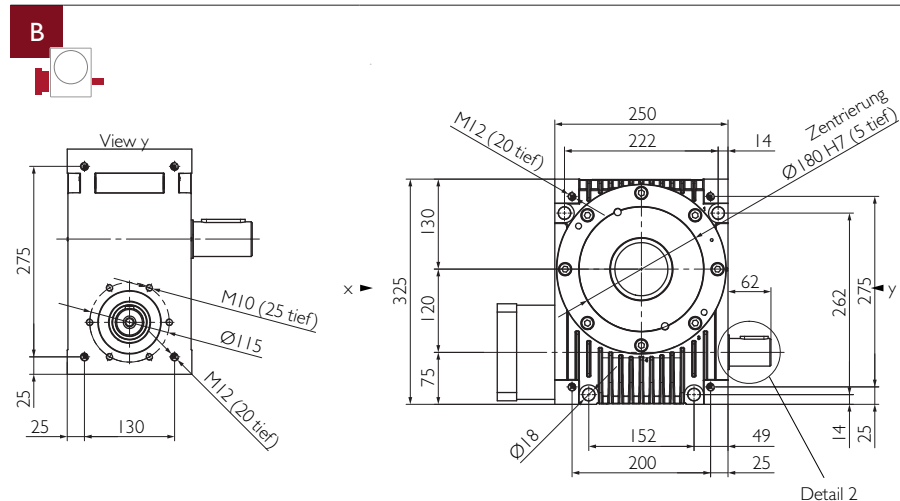
See **Rack & Pinion Program** of your ideal Drive Train on pages 104 et seq.

See **Flowcharts** to find your ideal Drive Train on pages 116 et seq.

Input

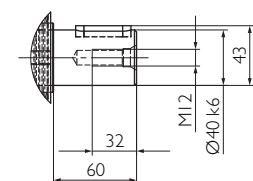


Example HPG 120 B5

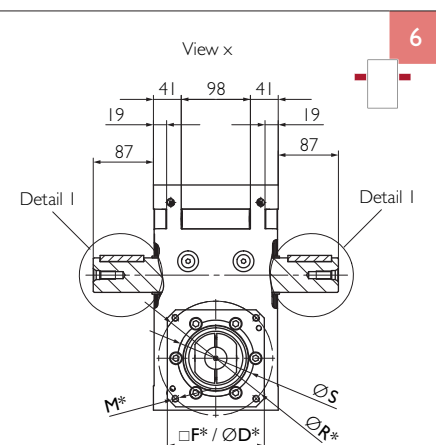
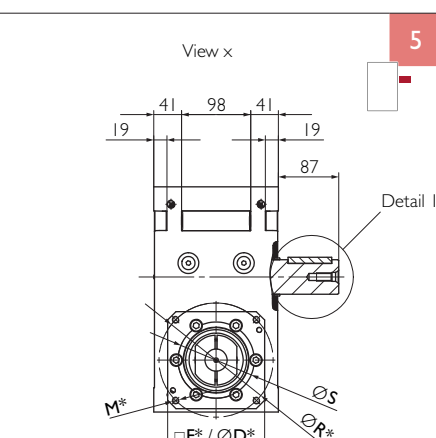
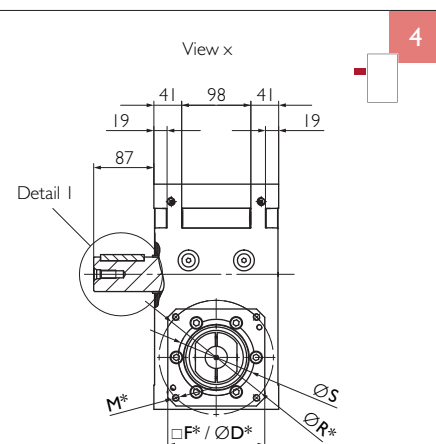


* Motor-specific gearbox dimensions
 $\varnothing d$: $\varnothing$ motor shaft [mm], $19 \leq \varnothing d \leq 50$
 L: Motor shaft length [mm], $35 \leq L \leq 112$

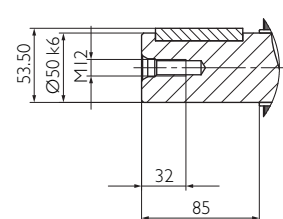
Detail 2



Output



Detail I

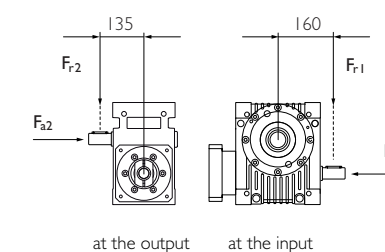


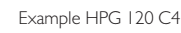
* Motor-specific gearbox dimensions
 S: min. 95 [mm], R: Pitch circle $\varnothing$ [mm], M: Bore hole $\varnothing$ or thread [mm], $\square F / \varnothing D$: Specify flange [mm]

Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500 rpm	T _{2N} η	[Nm] [%]	1177 93	1732 93	2018 93	1969 93	1752 92	2038 90	1895 89	1863 87	1824 84	1900 78	1364 75	1970 66	1364 61
	n _{1N} = 1000 rpm	T _{2N} η	[Nm] [%]	836 94	1284 94	1534 94	1523 93	1371 93	1609 91	1505 90	1487 88	1658 85	1622 80	1364 76	1612 68	1364 62
	n _{1N} = 1500 rpm	T _{2N} η	[Nm] [%]	648 94	1020 94	1237 94	1241 93	1126 93	1329 91	1248 90	1237 88	1380 86	1353 80	1364 76	1345 69	1364 62
	n _{1N} = 3000 rpm	T _{2N} η	[Nm] [%]	387 93	631 94	783 93	798 93	733 93	873 91	826 90	822 88	918 85	903 80	921 74	899 68	921 60
	n _{1N} = 4500 rpm	T _{2N} η	[Nm] [%]	276 93	457 93	573 93	588 93	543 92	650 91	617 89	616 87	688 84	677 79	689 73	675 66	689 58
Max. acceleration torque		T _{2B}	[Nm]	1200	2040									1400	2040	1400
Emergency stop torque		T _{2not}	[Nm]	2300									1600	2300	1600	
Idling torque ^{a)}		T ₀₁₂	[Nm]	4.5			4			3						
Max. input speed		n _{1Max}	[rpm]	4500												
Max. backlash ^{b)} at the output	PS	j _k	[arcmin]	<8	<7	<6	<6	<5	<5					<4		
	PR	j _k	[arcmin]	<5.5	<4.5	<4	<3.5	<3	<3					<2.5		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	11.5	19	24.5	26.5	29	31.5	34	36.5	38.5	40.5	39	42.5	39
Stability at the output		C _{2K}	[Nm/arcmin]	138												
Max. axial force ^{c) d)} at the output		F _{a2max}	[N]	2400	3900	3600	6200	9100	10000	13000	16000	17000	18000	18000	19000	19000
Max. radial force ^{c) e)} at the output		F _{r2max}	[N]	2500	2500	2700	3600	6200	6500	7500	8600	8700	9000	9100	9200	9200
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	340	340	360	480	830	880	1000	1200	1200	1200	1200	1200	1200
Max. axial force ^{c) d)} at the input		F _{a1max}	[N]	3600	1800	730	1700	3600	2100	3300	3700	2500	2900	2700	3100	2700
Max. radial force ^{c) f)} at the input		F _{r1max}	[N]	1900	950	390	930	1900	1200	1800	2000	1300	1600	1400	1700	1500
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁵ kg m ²]	1473	741	485	366	302	237	208	185	176	164	161	157	157
	Type 2 ⁱ⁾	J ₁	[10 ⁻⁵ kg m ²]	1596	864	607	489	424	360	331	308	298	287	284	280	279
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	50												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

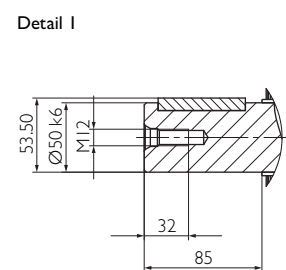
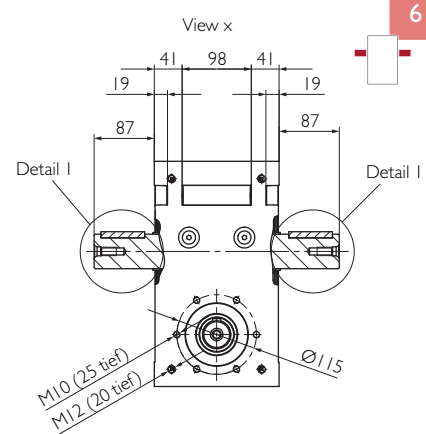
- a) approximate, at $n_1 = 3000 \text{ rpm}$ and operating temperature.
 b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
 Precision grade PR (reduced backlash) for precise process applications.
 c) Bearing forces: Values valid at $n_1 = 1500 \text{ rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
 Consult with Güdel for composite bearing forces, axial and radial forces.
 c) d) in relation to shaft center.
 c) e) at a distance of 135 mm from the middle of the casing.
 c) f) at a distance of 160 mm from the middle of the casing.
 g) in relation to the input, including coupling.
 g) h) Motor shaft diameter $\varnothing d$ from $\varnothing 19$ to $\varnothing 42$, calculated at $\varnothing 28 \text{ mm}$.
 g) i) Motor shaft diameter $\varnothing d$ from $\varnothing 43$ to $\varnothing 50$, calculated at $\varnothing 48 \text{ mm}$.

Bearing forces





	4

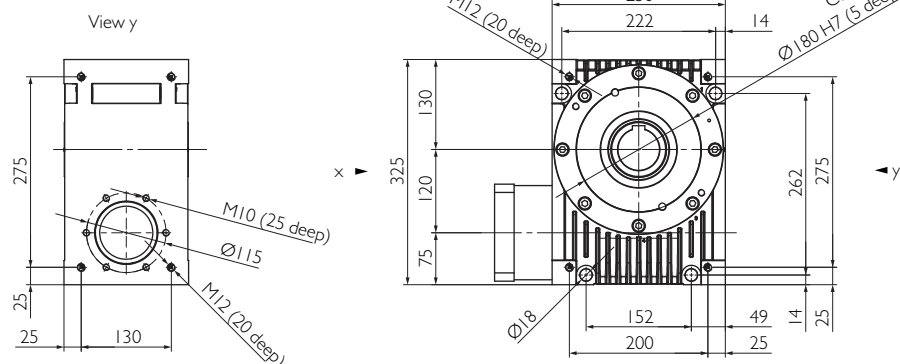


- approximate, at $n_1 = 3000\text{rpm}$ and operating temperature.
- Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- Bearing forces: Values valid at $n_1 = 1500\text{rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- d) in relation to shaft center.
- e) at a distance of 135 mm from the middle of the casing.
- f) at a distance of 160 mm from the middle of the casing.
- g) in relation to the input.

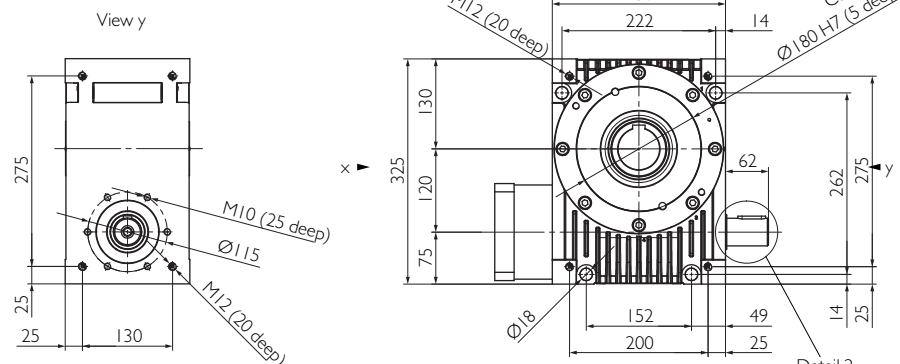
Diagram illustrating the forces at the input and output of the gearbox:

- Input side (right):** Shows a torque F_{a1} and a reaction force F_{r1} acting at a distance of 160 mm from the center of rotation.
- Output side (left):** Shows a torque F_{a2} and a reaction force F_{r2} acting at a distance of 135 mm from the center of rotation.

Input

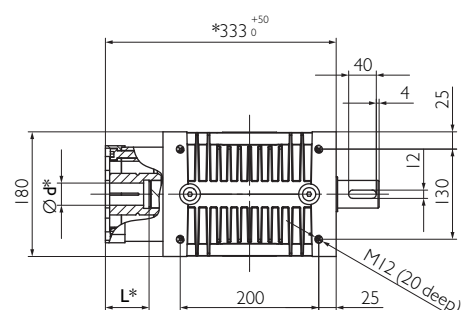
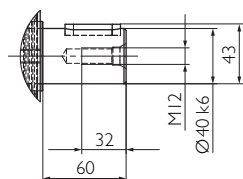


Example HPG 120 A7



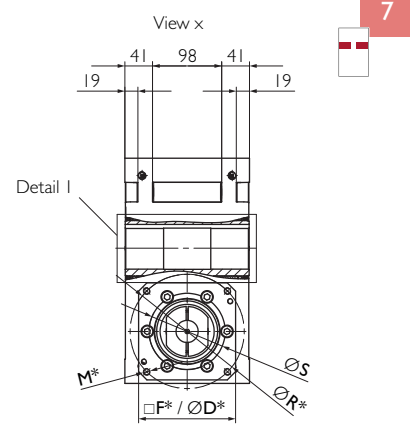
* Motor-specific gearbox dimensions
 $\varnothing d$: $\varnothing$ motor shaft [mm], $19 \leq \varnothing d \leq 50$
 L: Motor shaft length [mm], $35 \leq L \leq 112$

Detail 2

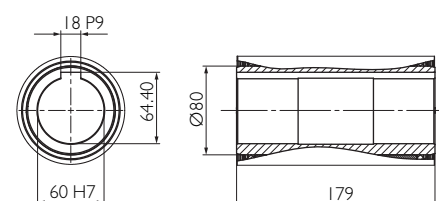


* Motor-specific gearbox dimensions
S: min. 95 [mm], **R:** Pitch circle Ø [mm], **M:** Bore hole Ø or thread [mm], **□F/ØD:** Specify flange [mm]

Output



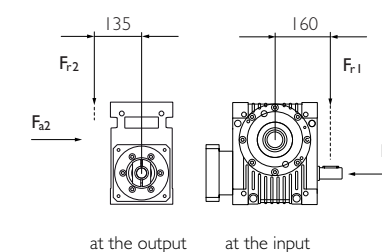
Detail 1



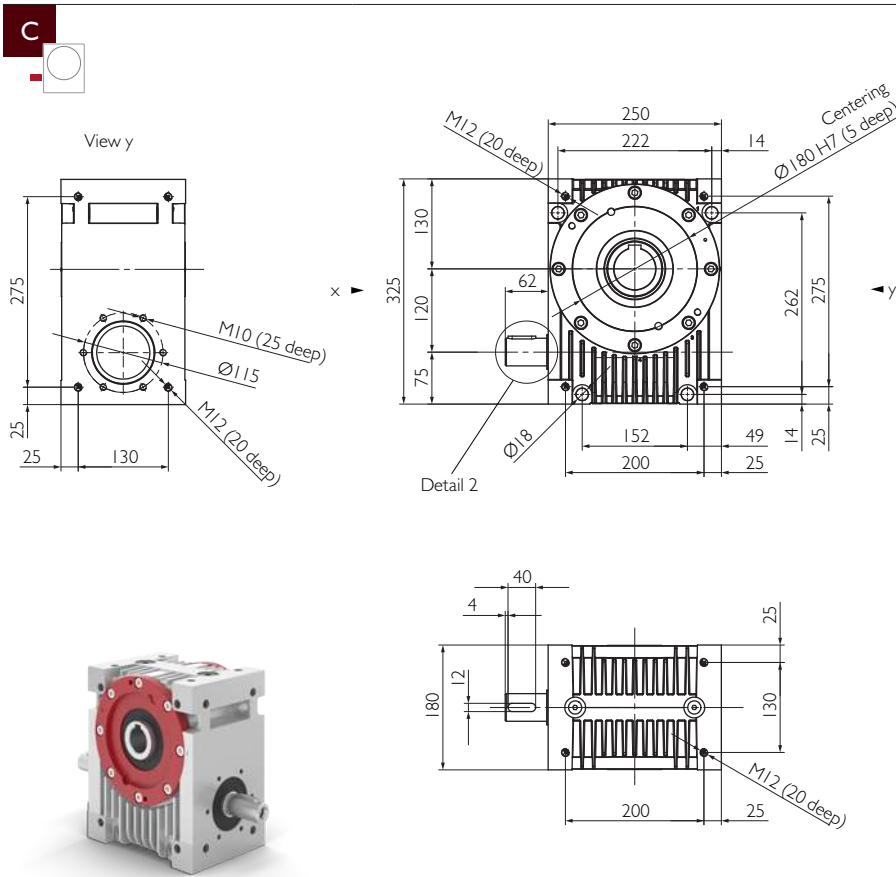
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60
Nominal torque at the output Efficiency	n _{1N} = 500rpm	T _{2N}	[Nm]	1177	1732	2018	1969	1752	2038	1895	1863	1824	1900	1364	1970	1364
		η	[%]	93	93	93	93	92	90	89	87	84	78	75	66	61
	n _{1N} = 1000rpm	T _{2N}	[Nm]	836	1284	1534	1523	1371	1609	1505	1487	1658	1622	1364	1612	1364
		η	[%]	94	94	94	93	93	91	90	88	85	80	76	68	62
	n _{1N} = 1500rpm	T _{2N}	[Nm]	648	1020	1237	1241	1126	1329	1248	1237	1380	1353	1364	1345	1364
		η	[%]	94	94	94	93	93	91	90	88	86	80	76	69	62
	n _{1N} = 3000rpm	T _{2N}	[Nm]	387	631	783	798	733	873	826	822	918	903	921	899	921
		η	[%]	93	94	93	93	93	91	90	88	85	80	74	68	60
	n _{1N} = 4500rpm	T _{2N}	[Nm]	276	457	573	588	543	650	617	616	688	677	689	675	689
		η	[%]	93	93	93	93	92	91	89	87	84	79	73	66	58
Max. acceleration torque		T _{2B}	[Nm]	1200	2040									1400	2040	1400
Emergency stop torque		T _{2not}	[Nm]	2300									1600	2300	1600	
Idling torque ^{a)}		T ₀₁₂	[Nm]	4.5			4				3					
Max. input speed		n _{1Max}	[rpm]	4500												
Max. backlash ^{b)} at the output	PS	j _k	[arcmin]	<8	<7	<6	<6	<5	<5					<4		
	PR	j _k	[arcmin]	<5.5	<4.5	<4	<3.5	<3	<3					<2.5		
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	11.5	19	24.5	26.5	29	31.5	34	36.5	38.5	40.5	39	42.5	39
Stability at the output		C _{2K}	[Nm/arcmin]	165												
Max. axial force ^{c)d)} at the output		F _{a2max}	[N]	7000	9600	9500	12000	16000	17000	21000	25000	26000	27000	27000	27000	28000
Max. radial force ^{c)e)} at the output		F _{r2max}	[N]	7700	8100	7300	8800	9900	10000	12000	13000	13000	14000	14000	14000	14000
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	1000	1100	980	1200	1300	1400	1600	1800	1800	1800	1800	1900	1900
Max. axial force ^{c)d)} at the input		F _{a1max}	[N]	3600	1800	730	1700	3600	2100	3300	3700	2500	2900	2700	3100	2700
Max. radial force ^{c)f)} at the input		F _{r1max}	[N]	1900	950	390	930	1900	1200	1800	2000	1300	1600	1400	1700	1500
Mass moment of inertia ^{g)}	Type 1 ^{h)}	J ₁	[10 ⁻⁵ kg m ²]	1388	703	463	352	292	232	204	183	174	164	161	157	156
	Type 2 ⁱ⁾	J ₁	[10 ⁻⁵ kg m ²]	1511	826	586	475	415	355	327	306	297	286	283	280	279
Service life		L _h	[h]	25000												
Weight without motor components		m	[kg]	50												
Max. permissible housing temperature			[°C]	+90												
Ambient temperature			[°C]	-15 up to +50												
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)														
Painting		None														
Protection class		IP65														

- a) approximate, at $n_1 = 3000\text{rpm}$ and operating temperature.
- b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
- c) Bearing forces: Values valid at $n_1 = 1500\text{rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
- c) d) in relation to shaft center.
- c) e) at a distance of 135 mm from the middle of the casing.
- c) f) at a distance of 160 mm from the middle of the casing.
- g) in relation to the input, including coupling.
- g) h) Motor shaft diameter $\varnothing d$ from $\varnothing 19$ to $\varnothing 42$, calculated at $\varnothing 28\text{mm}$.
- g) i) Motor shaft diameter $\varnothing d$ from $\varnothing 43$ to $\varnothing 50$, calculated at $\varnothing 48\text{mm}$.

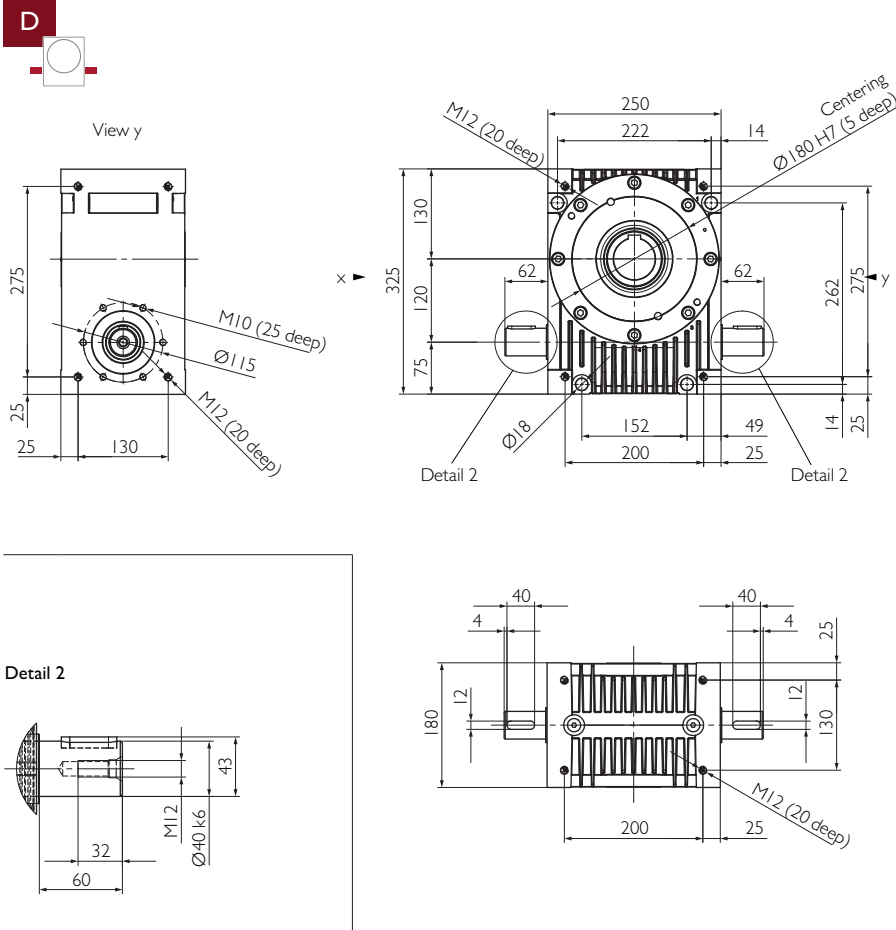
Bearing forces



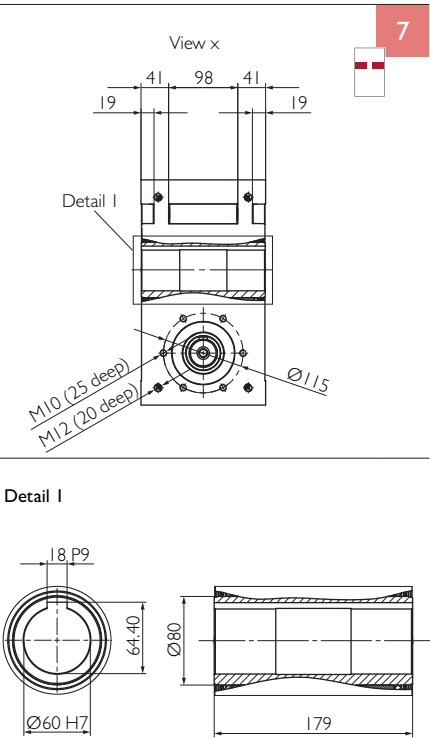
Input



Example HPG 120 D7



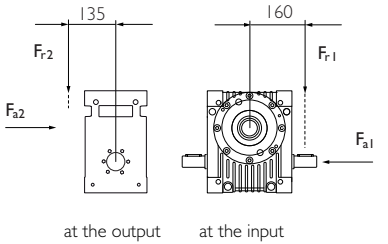
Output



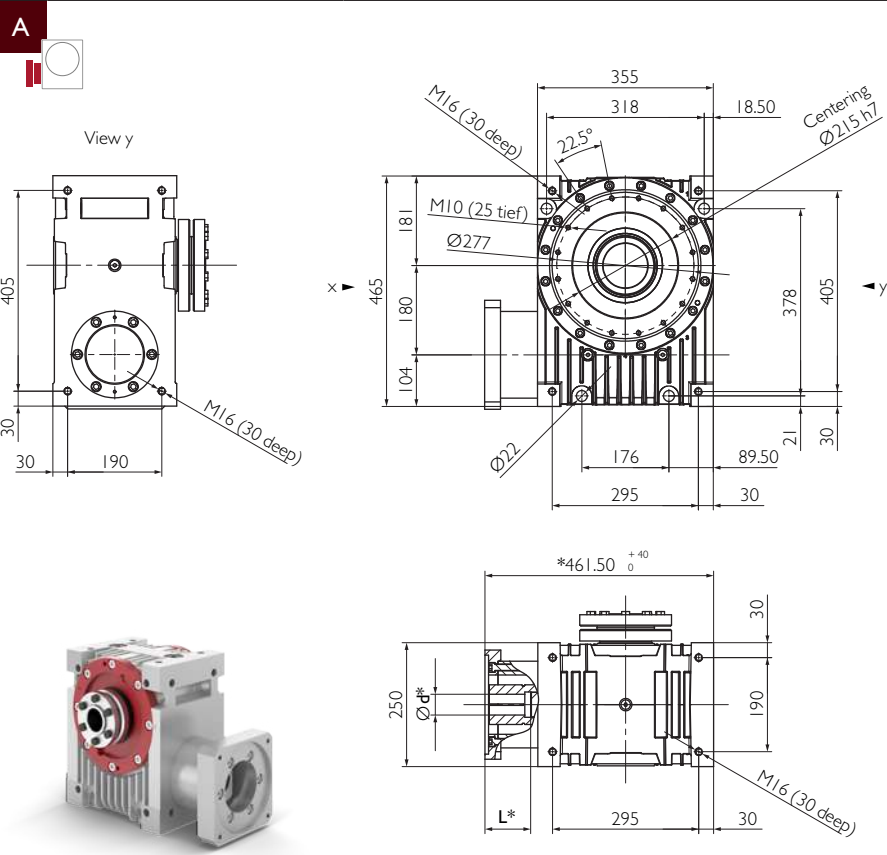
Ratio	i			2	3	4	5	6	8	10	13.33	16	24	30	47	60	
Nominal torque at the output Efficiency	n _{1N} = 500rpm	T _{2N}	[Nm]	1177	1732	2018	1969	1752	2038	1895	1863	1824	1900	1364	1970	1364	
		η	[%]	93	93	93	93	92	90	89	87	84	78	75	66	61	
	n _{1N} = 1000rpm	T _{2N}	[Nm]	836	1284	1534	1523	1371	1609	1505	1487	1658	1622	1364	1612	1364	
		η	[%]	94	94	94	93	93	91	90	88	85	80	76	68	62	
	n _{1N} = 1500rpm	T _{2N}	[Nm]	648	1020	1237	1241	1126	1329	1248	1237	1380	1353	1364	1345	1364	
		η	[%]	94	94	94	93	93	91	90	88	86	80	76	69	62	
	n _{1N} = 3000rpm	T _{2N}	[Nm]	387	631	783	798	733	873	826	822	918	903	921	899	921	
		η	[%]	93	94	93	93	93	91	90	88	85	80	74	68	60	
	n _{1N} = 4500rpm	T _{2N}	[Nm]	276	457	573	588	543	650	617	616	688	677	689	675	689	
		η	[%]	93	93	93	93	92	91	89	87	84	79	73	66	58	
Max. acceleration torque		T _{2B}	[Nm]	1200	2040										1400	2040	1400
Emergency stop torque		T _{2not}	[Nm]	2300										1600	2300	1600	
Idling torque ^{a)}		T ₀₁₂	[Nm]	4.5			4				3						
Max. input speed		n _{1Max}	[rpm]	4500													
Max. backlash ^{b)} at the output	PS	j _k	[arcmin]	<8	<7	<6	<6	<5	<5					<4			
	PR	j _k	[arcmin]	<5.5	<4.5	<4	<3.5	<3	<3					<2.5			
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	11.5	19	24.5	26.5	29	31.5	34	36.5	38.5	40.5	39	42.5	39	
Stability at the output		C _{2K}	[Nm/arcmin]	165													
Max. axial force ^{c) d)} at the output		F _{a2max}	[N]	7000	9600	9500	12000	16000	17000	21000	25000	26000	27000	27000	27000	28000	
Max. radial force ^{c) e)} at the output		F _{r2max}	[N]	7700	8100	7300	8800	9900	10000	12000	13000	13000	14000	14000	14000	14000	
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	1000	1100	980	1200	1300	1400	1600	1800	1800	1800	1800	1900	1900	
Max. axial force ^{c) d)} at the input		F _{a1max}	[N]	3600	1800	730	1700	3600	2100	3300	3700	2500	2900	2700	3100	2700	
Max. radial force ^{c) f)} at the input		F _{r1max}	[N]	1900	950	390	930	1900	1200	1800	2000	1300	1600	1400	1700	1500	
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁵ kg m ²]	1307	622	382	271	211	151	123	102	93	82	79	76	75	
Service life		L _h	[h]	25000													
Weight without motor components		m	[kg]	46													
Max. permissible housing temperature			[°C]	+90													
Ambient temperature			[°C]	-15 up to +50													
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)															
Painting		None															
Protection class		IP65															

- a) approximate, at $n_1 = 3000\text{rpm}$ and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
Precision grade PR (reduced backlash) for precise process applications.
c) Bearing forces: Values valid at $n_1 = 1500\text{rpm}$; $\frac{1}{2} T_{2N}$ and duty cycle of 40%.
Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 135 mm from the middle of the casing.
c) f) at a distance of 160 mm from the middle of the casing.
g) in relation to the input.

Bearing forces

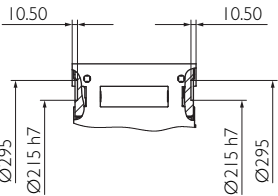


Input

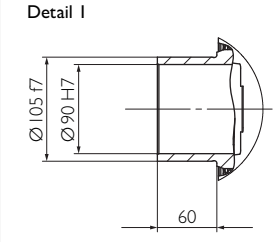
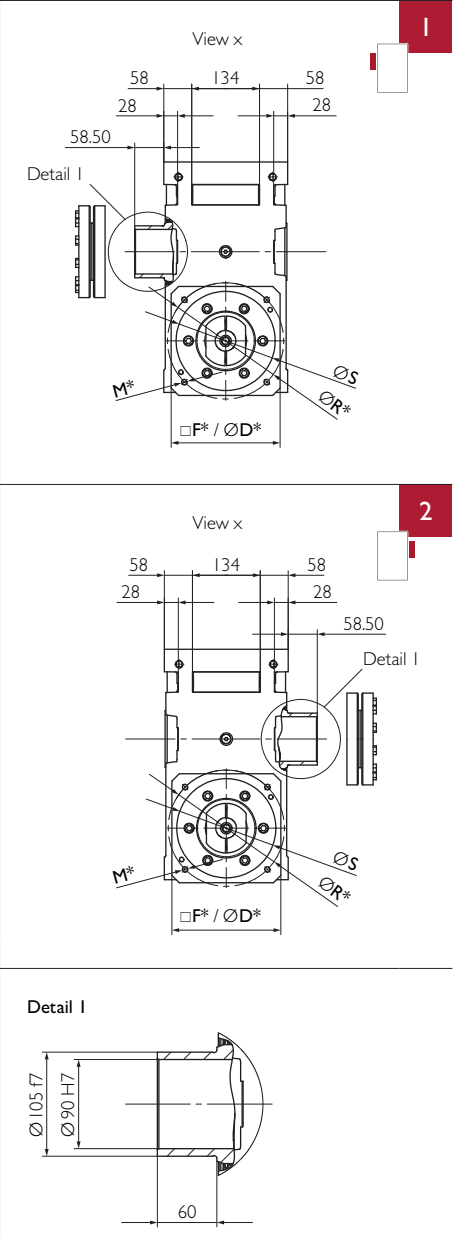


Example HPG 120 AI
* Motor-specific gearbox dimensions
Ød: Ø motor shaft [mm], 20 ≤ Ød ≤ 60
L: Motor shaft length [mm], 60 ≤ L ≤ 120

Centering on the Output



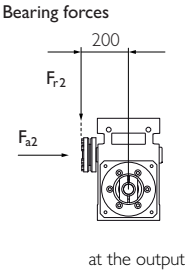
Output



* Motor-specific gearbox dimensions
S: min. 120 [mm], R: Pitch circle Ø [mm], M: Bore hole Ø or thread [mm], □F/ØD: Specify flange [mm]

Ratio	i			6	8	10	13.33	16	24	47
Nominal torque at the output Efficiency	n _{1N} = 500rpm	T _{2N}	[Nm]	5091	5950	5553	5473	6100	5963	5920
		η	[%]	95	94	93	92	90	86	76
	n _{1N} = 1000rpm	T _{2N}	[Nm]	3726	4396	4131	4093	4566	4477	4452
		η	[%]	95	94	94	92	90	87	77
	n _{1N} = 1500rpm	T _{2N}	[Nm]	2938	3486	3289	3268	3649	3583	3566
		η	[%]	95	94	94	92	90	87	77
	n _{1N} = 3000rpm	T _{2N}	[Nm]	1798	2150	2041	2037	2277	2241	2234
		η	[%]	95	94	93	91	90	86	76
Max. acceleration torque		T _{2B}	[Nm]	6100						
Emergency stop torque		T _{2Not}	[Nm]	8000						
Idling torque ^{a)}		T ₀₁₂	[Nm]	7.5			5.5			
Max. input speed		n _{1Max}	[rpm]	3000						
Max. backlash ^{b)} at the output		PS	j _t	[arcmin]	<3				<2.5	
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	292	342	385	425	470	510	540
Stability at the output		C _{2K}	[Nm/arcmin]	500						
Max. axial force ^{c)} d) at the output		F _{a2max}	[N]	30000	35000	43000	45000	45000	47000	49000
Max. radial force ^{c)} e) at the output		F _{r2max}	[N]	18000	20000	23000	24000	23000	24000	24000
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	3700	4000	4600	4700	4600	4800	4900
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁵ kg m ²]	2042	1564	1343	1171	1103	1018	967
Service life		L _h	[h]	25000						
Weight without motor components		m	[kg]	145						
Max. permissible housing temperature			[°C]	+90						
Ambient temperature			[°C]	-15 up to +50						
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)								
Painting		None								
Protection class		IP65								

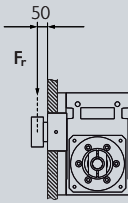
- a) approximate, at n₁ = 2000rpm and operating temperature.
- b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
- c) Bearing forces: Values valid at n₁ = 1000rpm; ½ T_{2N} and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
- c) d) in relation to shaft center.
- c) e) at a distance of 200 mm from the middle of the casing.
- g) in relation to the input, including coupling and shrink disc at the output (output 1 & 2), Coupling: Motor shaft diameter Ød from Ø20 to Ø60, calculated at Ø32mm.



Package

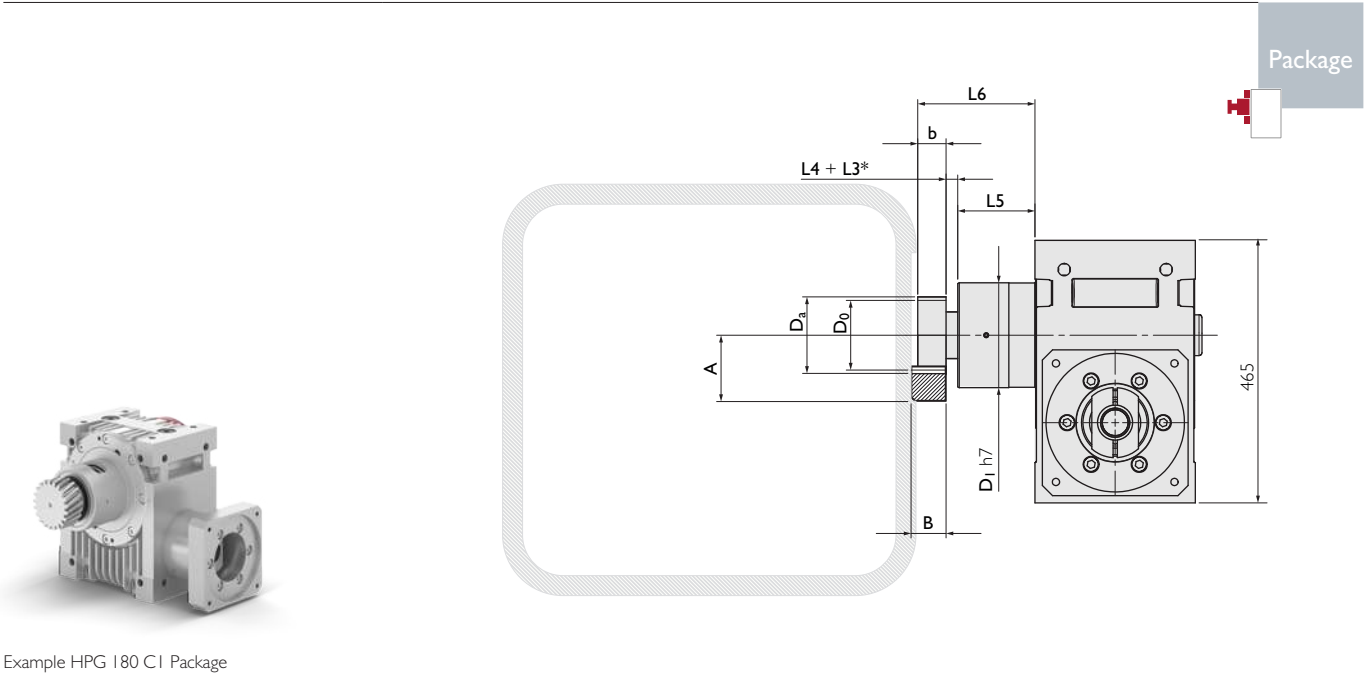
Output Flange including Bearing & Pinion			
Radial rigidity	C ₃	[N/mm]	80000
Speed	n _{2N}	[rpm]	400 200 100
Max. radial force ^{j)}	F _{rmax}	[N]	90000 95000 100000

j) Bearing forces: Values valid at duty cycle of 40% at a distance of 50 mm from the end of the bearing.

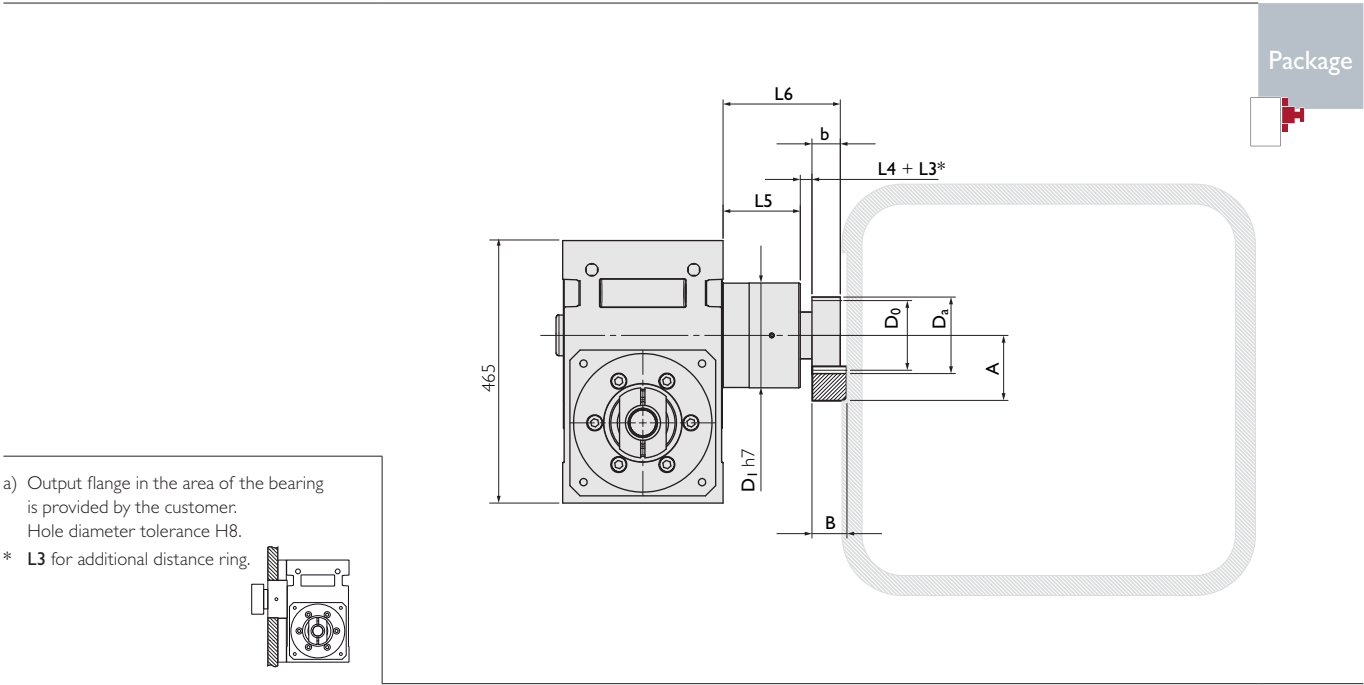


Detailed information about the Package, Options & Accessories on pages 100 and 101.

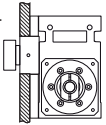
Output Flange including Bearing & Pinion^{a)}



Example HPG 180 C1 Package



a) Output flange in the area of the bearing is provided by the customer. Hole diameter tolerance H8.
* L3 for additional distance ring.



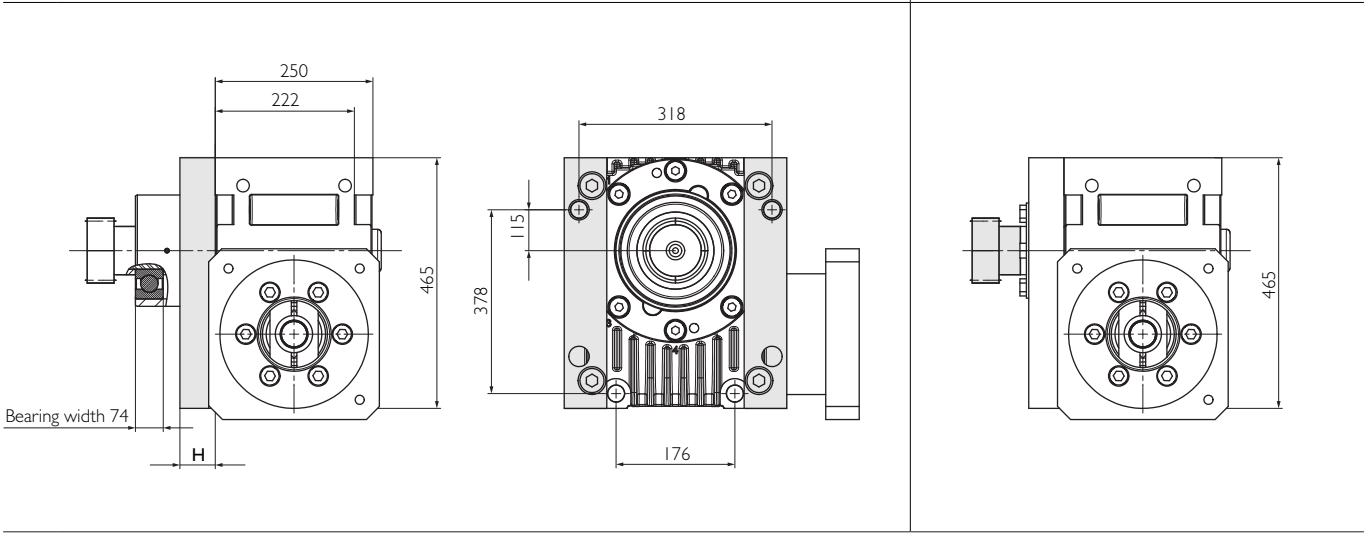
Geometric information

Helical modular pitch	Part. No.	m	z	A	b	B	Da	D0	D1	L4	L5	L6
Pinion 1	211720	6	20	106.66	60	59	139.3	127.32	220	20	160	240
Pinion 2	211820	8	20	155.88	80	79	185.7	169.76	220	35	160	275
Pinion 3	211915	10	15	171.58	100	99	185.2	165.16	220	40	160	300

Straight modular pitch	Part. No.	m	z	A	b	B	Da	D0	D1	L4	L5	L6
Pinion 4	201821	8	20	151.0	80	79	176.0	160.0	220	35	160	275
Pinion 5	201916	10	16	172.0	100	99	186.0	166.0	220	40	160	300

Spacer Elements

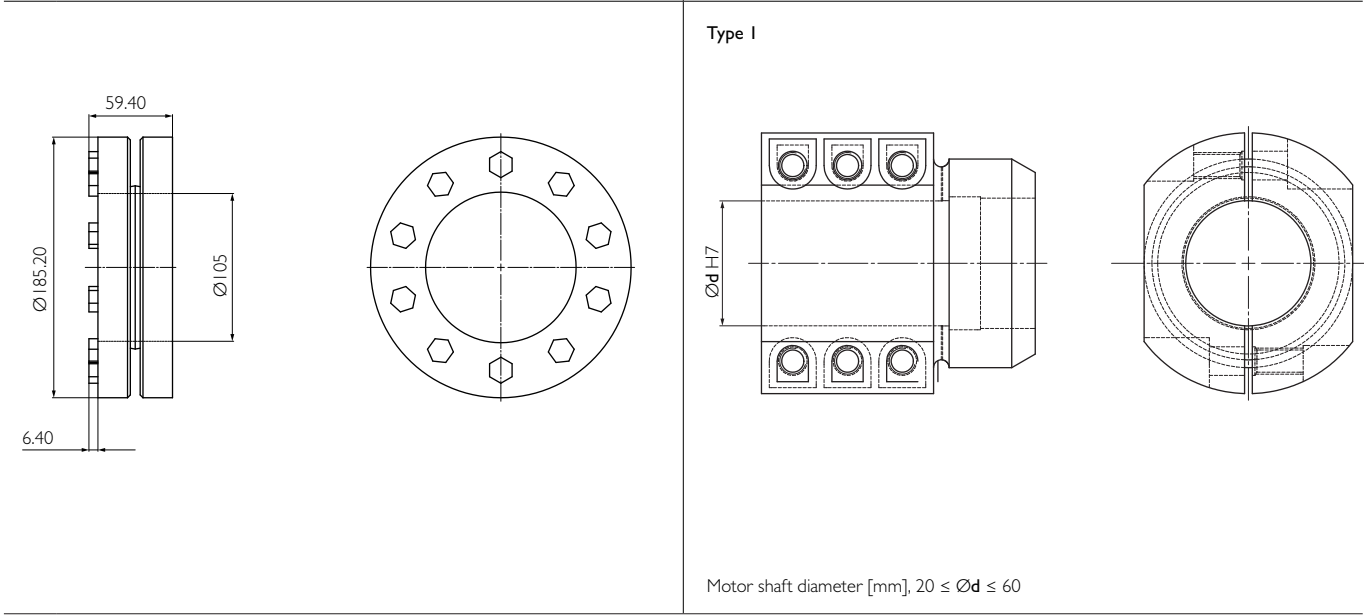
with Pinion special solutions on request



Casing can only be fastened with long screws as per the bore hole pattern.
Screws M20 of length 222mm + H + thread depth, tightening torque 240Nm.

Shrink Disc

Coupling



Motor shaft diameter [mm], 20 ≤ Ød ≤ 60

Your ideal Drive Train

Our Function Package with high-performance angle gearbox, output flange, pinion and rack by Güdel.

			Pinion 1	Pinion 2	Pinion 3	Pinion 4	Pinion 5
Maximum acceleration force	F_N	[N]	58870	114380	160516	91220	137151
Maximum acceleration torque	T_N	[Nm]	3748	9709	12773	7298	10972

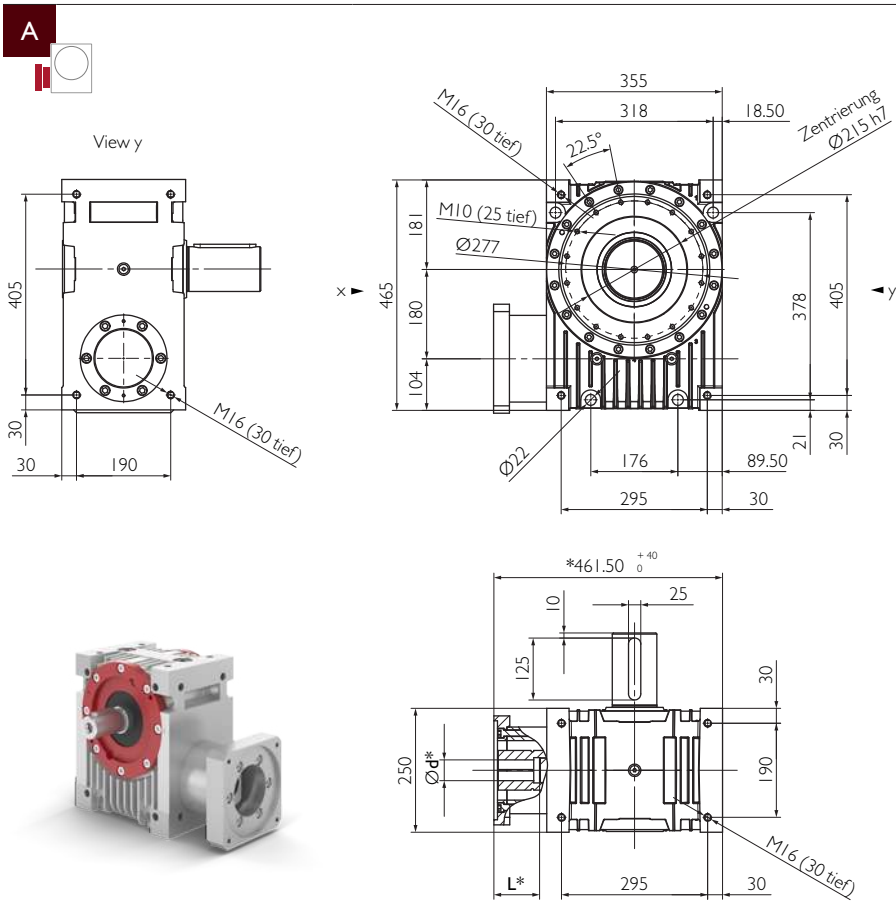
Higher value for rack and pinion taking account of the number of load cycles:
1x10⁶ for the rack; 1x10⁷ for the pinion. Both in cycle mode.



See **Rack & Pinion Program** of your ideal Drive Train on pages 104 et seq.

See **Flowcharts** to find your ideal Drive Train on pages 116 et seq.

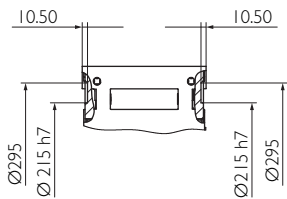
Input



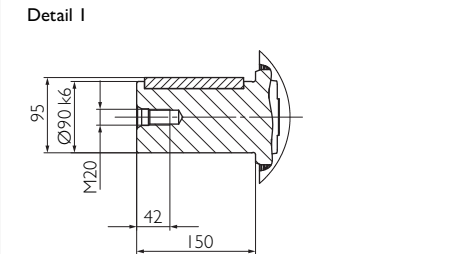
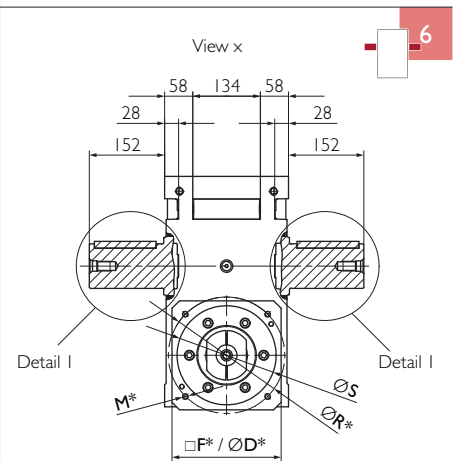
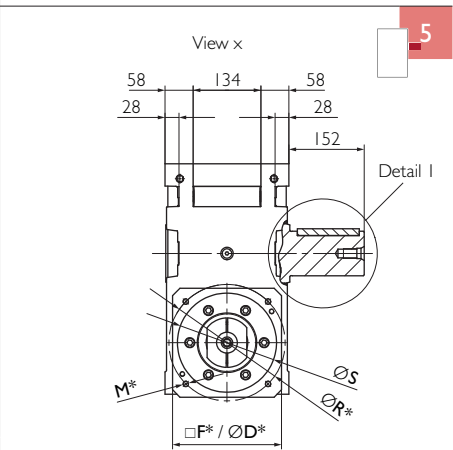
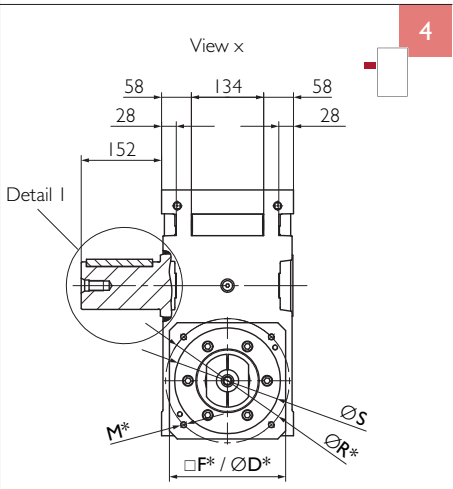
Example HPG 180 A4

* Motor-specific gearbox dimensions
Ød: Ø motor shaft [mm], 20 ≤ Ød ≤ 60
L: Motor shaft length [mm], 60 ≤ L ≤ 120

Centering on the Output



Output

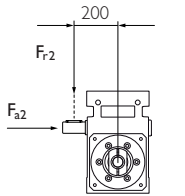


* Motor-specific gearbox dimensions
S: min. 120 [mm], R: Pitch circle Ø [mm], M: Bore hole Ø or thread [mm], □F/ØD: Specify flange [mm]

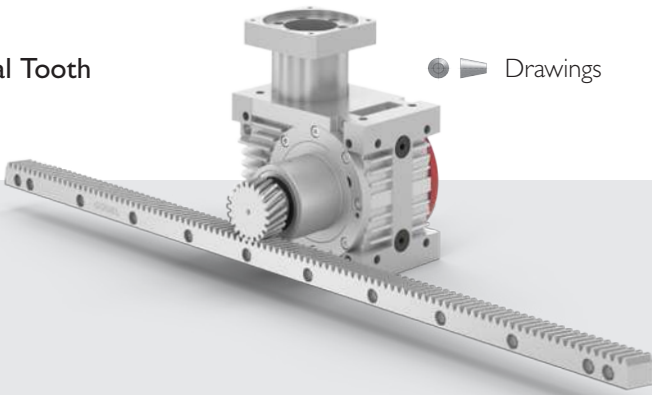
Ratio	i			6	8	10	13.33	16	24	47
Nominal torque at the output Efficiency	n _{1N} = 500rpm	T _{2N}	[Nm]	5091	5950	5553	5473	6100	5963	5920
		η	[%]	95	94	93	92	90	86	76
	n _{1N} = 1000rpm	T _{2N}	[Nm]	3726	4396	4131	4093	4566	4477	4452
		η	[%]	95	94	94	92	90	87	77
	n _{1N} = 1500rpm	T _{2N}	[Nm]	2938	3486	3289	3268	3649	3583	3566
		η	[%]	95	94	94	92	90	87	77
	n _{1N} = 3000rpm	T _{2N}	[Nm]	1798	2150	2041	2037	2277	2241	2234
		η	[%]	95	94	93	91	90	86	76
Max. acceleration torque		T _{2B}	[Nm]	6100						
Emergency stop torque		T _{2not}	[Nm]	8000						
Idling torque ^{a)}		T ₀₁₂	[Nm]	7.5			5.5			
Max. input speed		n _{1Max}	[rpm]	3000						
Max. backlash ^{b)} at the output	PS	j _t	[arcmin]	<3					<2.5	
Torsional rigidity vom Abtrieb zum Eintrieb		C _{t21}	[Nm/arcmin]	292	342	385	425	470	510	540
Stability at the output		C _{2K}	[Nm/arcmin]	500						
Max. axial force ^{c) d)} at the output		F _{a2max}	[N]	30000	35000	43000	45000	45000	47000	49000
Max. radial force ^{c) e)} at the output		F _{r2max}	[N]	18000	20000	23000	24000	23000	24000	24000
Max. overturning torque ^{c)} at the output		M _{2max}	[Nm]	3700	4000	4600	4700	4600	4800	4900
Mass moment of inertia ^{g)}		J ₁	[10 ⁻⁵ kg m ²]	2042	1564	1343	1171	1103	1018	967
Service life		L _h	[h]	25000						
Weight without motor components		m	[kg]	155						
Max. permissible housing temperature			[°C]	+90						
Ambient temperature			[°C]	-15 up to +50						
Lubrication		synthetic gear oil (as per DIN 51502: CLP PG 460)								
Painting		None								
Protection class		IP65								

- a) approximate, at n₁ = 2000rpm and operating temperature.
b) Precision grade PS (standard backlash) for classic mechanical engineering applications.
c) Bearing forces: Values valid at n₁ = 1000rpm; ½ T_{2N} and duty cycle of 40%. Consult with Güdel for composite bearing forces, axial and radial forces.
c) d) in relation to shaft center.
c) e) at a distance of 200 mm from the middle of the casing.
g) in relation to the input, including coupling.
Coupling: Motor shaft diameter Ød from Ø20 to Ø60, calculated at Ø32mm.

Bearing forces



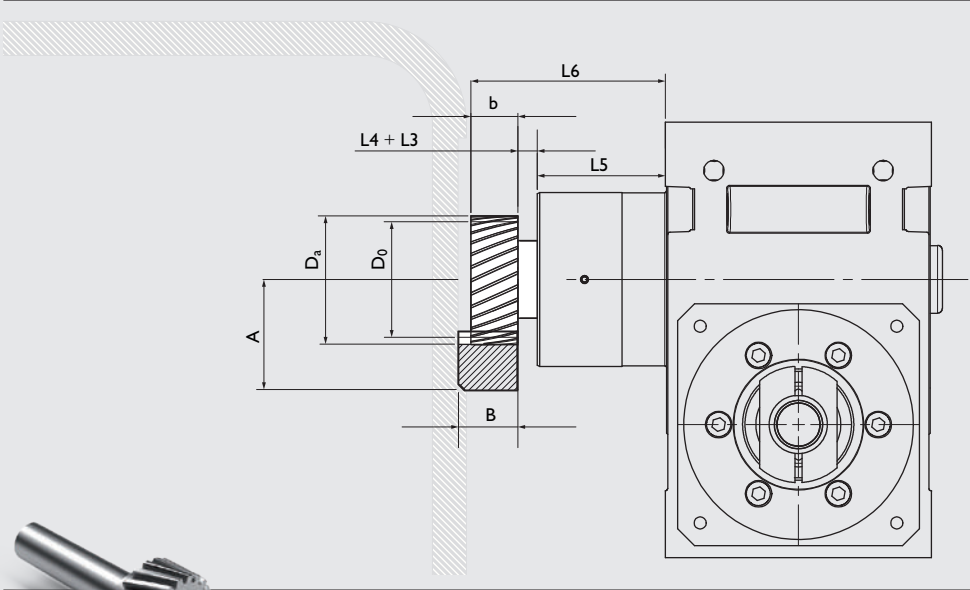
at the output



Rack & Pinon Program

Our Function Package with gearbox, output flange, pinion and rack by Güdel.

Helical modular pitch



Hardened and ground

Material
1.6MnCr5 DIN 1.7131
shaft/bore soft

Teeth
pressure angle $\alpha = 20^\circ$
helical tooth system
helix angle $\beta = 19^\circ 31'42''$
hardened (58 $\frac{1}{2}$ HRC)
ground, crowned

Quality
6f24 DIN 3962/63/67

f_p [mm]
Adjacent pitch error
modul m ≤ 3 ; 0.006
modul m > 3 ; 0.008

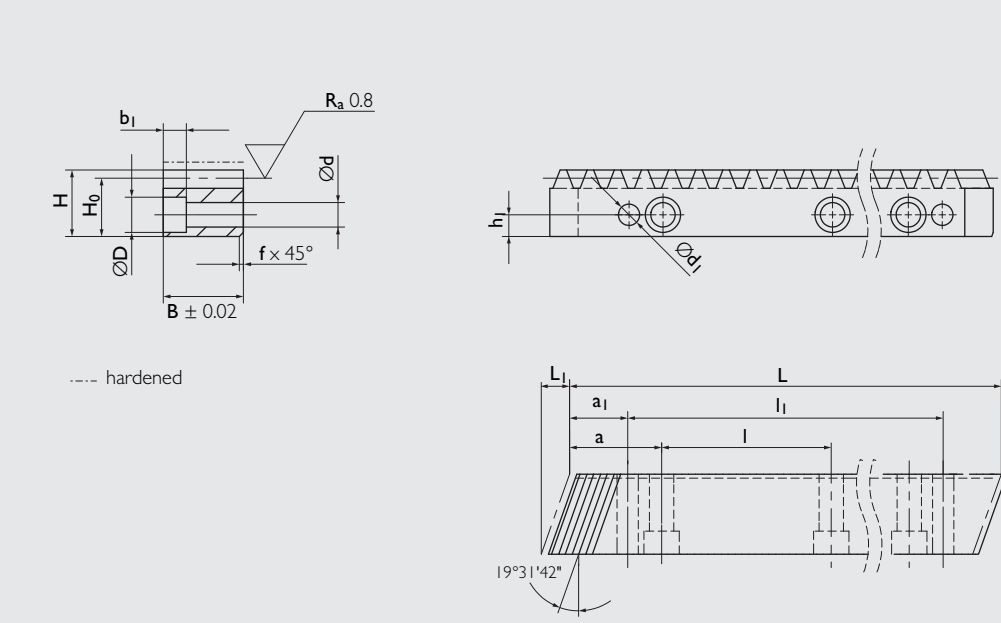
Geometric Information

Size	m	z	A	b	D _a	D ₀	L4	L5	L6	M	Part. No.
030	1.5	16	30.68	20	29.36	26.36	4.5	38	62.5	0.14	211116
								43	67.5		
045	1.5	20	33.415	20	34.83	31.83	4.5	43	67.5	0.34	211120
								53	77.5		
	2	16	39.575		39.15	35.15	8	43	71	0.39	211216
								53	81		
060	2	20	43.22	20	46.44	42.44	8	53	81	0.7	211220
								58	86		
								83	111		
	2.5	20	48.025	25	58.05	53.05		53	86	0.91	211320
								58	91		
								83	116		
	3	16	52.365	30	58.73	52.73		53	91	0.99	211416
								58	96		
83							121				
090	3	20	57.83	30	69.66	63.66	12.5	63	105.5	2.38	211420
								104.5	147		
	4		77.44	40	92.88	84.88	18	63	121	3.43	211520
								104.5	162.5		
120	4	20	77.44	40	92.88	84.88	14.5	123	177.5	7.89	211521
	5		87.05	50	116.1	106.1	35	123	208	9.96	211620
180	6	20	106.66	60	139.3	127.32	20	160	240	20.7	211720
	8		155.88	80	185.7	169.76	35	160	275	28.2	211820
	10	15	171.58	100	185.2	165.16	40	160	300	31.63	211915

m: modul, z: number of teeth, M: Weight [kg]

Rack

Helical modular pitch



Hardened and ground

Material
C45E DIN 1.1191
1.7131 (1.6MnCr5) on request

Profil
all faces ground

Teeth
pressure angle $\alpha = 20^\circ$
helical tooth system right
 $\beta = 19^\circ 31'42''$
hardened (54 $\frac{1}{2}$ HRC)
and ground

Quality
6h23 DIN 3962/63/67

f_p [mm]
Adjacent pitch error
modul m ≤ 3 ; 0.006
modul m > 3 ; 0.008

p_f [mm]
-0.05/-0.2. Tolerance of cut
for continuous mounting

F_{pL} [mm]
Cumulative pitch error;
based on length L

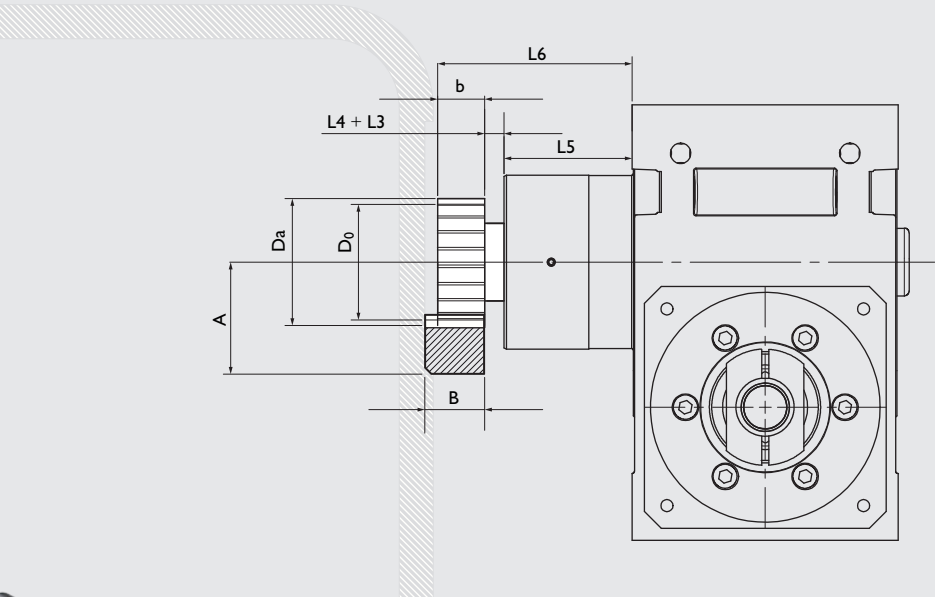
Geometric Information

Size	p _t	m	L	L ₁	z	B	H	H ₀	f+0.5	a	l	h ₁	d	D	b ₀	a ₁	l ₁	d ₁	F _{pL}	M	Part. No.
30 45	5	1.5	500	6.7	100	19	19	17.50 0/-027	2	62.5	125.00	8	7	11	7	31.7	436.6	5.7	0.029	1.3	246012
			1000		200														0.043	2.6	246013
45 60	6.67	2	500	8.5	75	24	24	22.00 0/-027	2	62.5	125.00	8	7	11	7	31.7	436.6	5.7	0.025	2.1	246022
			1000		150														0.036	4.1	246023
			2000		300														0.058	8.2	246024
60	8.33	2.5	500	8.5	60	24	24	21.50 0/-027	2	62.5	125.00	9	7	11	7	31.7	436.6	5.7	0.027	2.0	246032
			1000		120														0.036	4.1	246033
			2000		240														0.053	8.2	246034
60 90	10.00	3	500	10.3	50	29	29	26.00 0/-034	2	62.5	125.00	9	10	15	9	35.0	430.0	7.7	0.028	3.0	246042
			1000		100														0.037	5.9	246043
			2000		200														0.054	11.2	246044
90 120	13.33	4	506.67	13.8	38	39	39	35.00 0/-034	3	62.5	125.00	12	10	15	9	33.3	433.0	7.7	0.030	5.4	246052
			1000		75														0.036	10.7	246053
			2000		150														0.050	20.5	246054
120	16.67	5	500	17.4	30	49	39	34.00 0/-034	3	62.5	125.00	12	14	20	13	37.5	425.0	11.7	0.028	6.5	246062
			1000		60														0.034	13.1	246063
			2000		120														0.045	24.5	246064
180	20.00	6	500	20.9	25	59	49	43.00 0/-041	3	62.5	125.00	16	18	26	17	37.5	425.0	15.7	0.031	10.0	246072
			1000		50														0.036	19.9	246073
			2000		100														0.046	36.5	246074
180	26.66	8	480	28.0	18	79	79	71.00 0/-041	3	60.0	125.00	25	22	33	21	120.0	240.0	19.7	0.029	22.0	246082
			960		36														0.033	44.0	246083
			1920		72														0.040	78.0	246084
180	33.33	10	500	35.1	15	99	99	89.00 0/-041	3	62.5	125.00	32	33	48	32	125.0	250.0	19.7	0.029	34.0	246092
			1000		30														0.032	68.0	246093

m: modul, z: number of teeth p: pitch, p_t: transvers, M: Weight [kg]

Pinion

Straight modular pitch



Hardened and ground

Material
16MnCr5 DIN 1.7131
shaft / bore soft

Teeth
pressure angle $\alpha = 20^\circ$
straight teeth
hardened (58 $\frac{1}{2}$ HRC)
ground, crowned

Quality
6f24 DIN 3962/63/67

f_p [mm]
Adjacent pitch error
modul m ≤ 3 ; 0.006
modul m > 3 ; 0.008



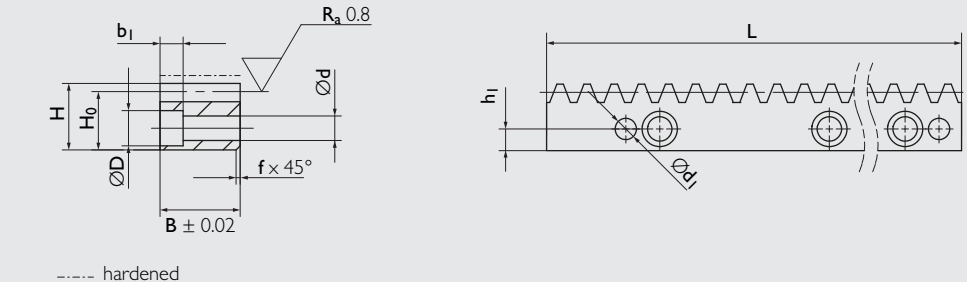
Geometric Information

Size	m	z	A	b	D _a	D ₀	L ₄	L ₅	L ₆	M	Part. No.
030	1.5	16	29.95	20	27.9	24.9	4.5	38	82.5	0.14	201116
								43	67.5		
045	1.5	20	32.5	20	33.0	30.0	4.5	43	67.5	0.34	201120
								53	77.5		
	2	16	38.6		37.2	33.2	8	43	71	0.37	201216
								53	81		
060	2	20	42.0	20	44.0	40.0	8	53	81	0.68	201220
								58	86		
								83	111		
	2.5	20	46.0	25	55.0	50.0		53	86	0.86	201320
								58	91		
								83	116		
	3	16	50.9	30	55.8	49.8		53	91	0.93	201416
								58	96		
								83	121		
090	3	20	56.0	30	66.0	60.0	12.5	63	105.5	2.30	201420
								104.5	147		
	4		75.0	40	88.0	80.0	18	63	121	3.24	201520
								104.5	162.5		
120	5	20	84.0	50	110.0	100.0	35	123	208	9.57	201620
	6		103.0	60	132.0	120.0	35		218	11.8	201720
	8		151.0	80	176.0	160.0	35		238	28.31	201820
180	8	20	151.0	80	176.0	160.0	35	160	275	28.31	201821
	10	16	172.0	100	186.0	166.0	40		300	31.78	201916

m: modul, z: number of teeth, M: Weight [kg]

Rack

Straight modular pitch



Hardened and ground

Material
C45E DIN 1.1191
1.7131 (16MnCr5) on request

Profil
all faces ground

Teeth
pressure angle $\alpha = 20^\circ$
straight tooth system
hardened (54 $\frac{1}{2}$ HRC)
and ground

Quality
6h23 DIN 3962/63/67

f_p [mm]
Adjacent pitch error
modul m ≤ 3 ; 0.006
modul m > 3 ; 0.008

pr [mm]
-0.05/-0.2, Tolerance of cut
for continuous mounting

F_{pL} [mm]
Cumulative pitch error; based on
length L



Geometric Information

Size	p	m	L	z	B	H	H ₀	f+0.5	a	l	h ₁	d	D	b ₁	a ₁	l ₁	d ₁	F _{pL}	M	Part. No.
30 45	4.712	1.5	499.51	106	19	19	17.50 0/-027	2	62.44	124.88	8	7	11	7	29	441.5	5.7	0.029	1.3	240012
			999.03	212														0.043	2.6	240013
			502.65	80														0.025	2.1	240022
45 60	6.283	2	1005.31	160	24	24	22.00 0/-027	2	62.83	125.66	8	7	11	7	31.3	942.7	5.7	0.036	4.2	240023
			2010.62	320														0.058	8.0	240024
			502.65	64														0.027	2.0	240032
60	7.854	2.5	1005.31	128	24	24	21.50 0/-027	2	62.83	125.66	9	7	11	7	31.3	942.7	5.7	0.036	4.1	240033
			2010.62	256														0.053	8.0	240034
			508.94	54														0.029	3.0	240042
60 90	9.425	3	1017.88	108	29	29	26.00 0/-034	2	63.62	127.23	9	10	15	9	34.4	949.1	7.7	0.037	6.0	240043
			2035.75	216														0.055	11.5	240044
			502.65	40														0.030	5.40	240052
90	12.566	4	1005.31	80	39	39	35.00 0/-034	2	62.83	125.66	12	10	15	9	37.5	930.3	7.7	0.037	10.8	240053
			2010.62	160														0.050	21.0	240054
			502.65	32														0.028	6.6	240062
120	15.708	5	1005.31	64	49	39	34.00 0/-034	3	62.83	125.66	12	14	20	13	30.2	944.9	11.7	0.034	13.1	240063
			2010.62	128														0.045	24.7	240064
			508.94	27														0.031	10.1	240072
120	18.850	6	1017.88	54	59	49	43.00 0/-041	3	63.62	127.23	16	18	26	17	31.4	955.0	15.7	0.036	20.3	240073
			2035.75	108														0.047	37.5	240074
			502.65	20														0.029	22.1	240082
120 180	25.133	8	1005.31	40	79	79	71.00 0/-041	3	62.83	125.66	25	22	33	21	26.7	952.0	19.7	0.033	44.3	240083
			2010.62	80														0.041	82.5	240084
			502.65	16														0.029	34.8	240092
180	31.416	10	1005.31	32	99	99	89.00 0/-041	3	62.83	125.66	32	33	48	32	125.2	755.0	19.7	0.032	69.5	240093

m: modul, z: number of teeth p: pitch, p_t: transvers, M: Weight [kg]



Technical Information
GÜDEL

Define the Code of your High Performance Angle Gearbox

Package
(Output Flange including
Bearing & Pinion)

Type Size Configuration Ratio Precision Grades Centering

HPG 060 - A I - 5 - PS - 0

HPG High Performance Angle Gearbox

030 045 060 090 120 180

Input Output

A I B 2 C 3 D 4 5 6 7

i = 2 3 4 5 6 8 10 13.33 16 24 30 47 60

PS Standard circumferential backlash
PR Reduced circumferential backlash *

* PR can not be selected in sizes 030 and 180

0 without I at input I for configuration C and D
2 at input 2 (input shaft) for configuration B and D
3 for input I and 2 for configuration B and D

Güdel Pinion 211320

Request of the Output Flange 86 53

Assembly -

Spacer Elements (optional) 22

Part. No. acc. to catalogue

L6 Distance between pinion and housing [mm]

L5 Length Output flange acc. to catalogue [mm]

R Assembly right
L Assembly left

H Height of spacer elements [mm]

Mandatory for configuration 3, Shrink Disc on both sides.

Clamping set

Coupling

Motor

Unless a pinion is required

Unless a Package is required (Output Flange including Bearing & Pinion)

Unless no spacer elements are required



Example
HPG 060-AI-5-PS-0-211320-86-53-22-SU

Mounting Position

SU

Motor

SS vertical standing worm
SU vertical worm below
SL flat lying worm
SO vertical worm top

HPG 060 AI-A2-A3-B1-B2-B3 High Performance Angle Gearboxes

Technical Data Sheets on pages 26 et seq.

HPG 060 AI-A2-A3-B1-B2-B3 High Performance Angle Gearboxes

HPG 060 AI-A2-A3-B1-B2-B3 High Performance Angle Gearboxes

HPG 060 AI-A2-A3-B1-B2-B3 High Performance Angle Gearboxes



Example
HPG060-AI-5-PS-0-SU

SS vertical standing worm

SU vertical worm below

SL flat lying worm

SO vertical worm top

See General Introduction about Positions on page 21.

Order Reference

Choose your appropriate Motor Interface

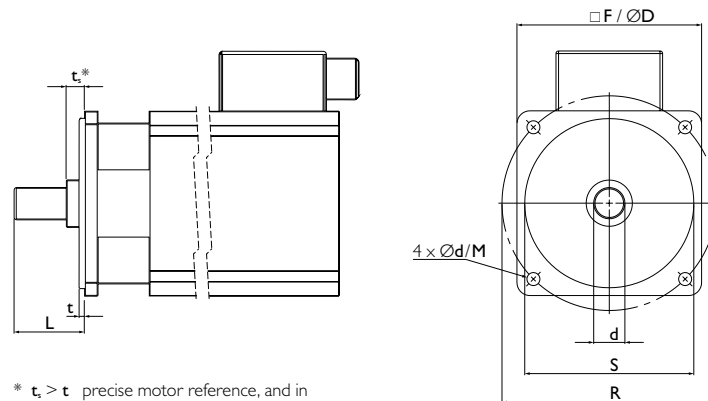
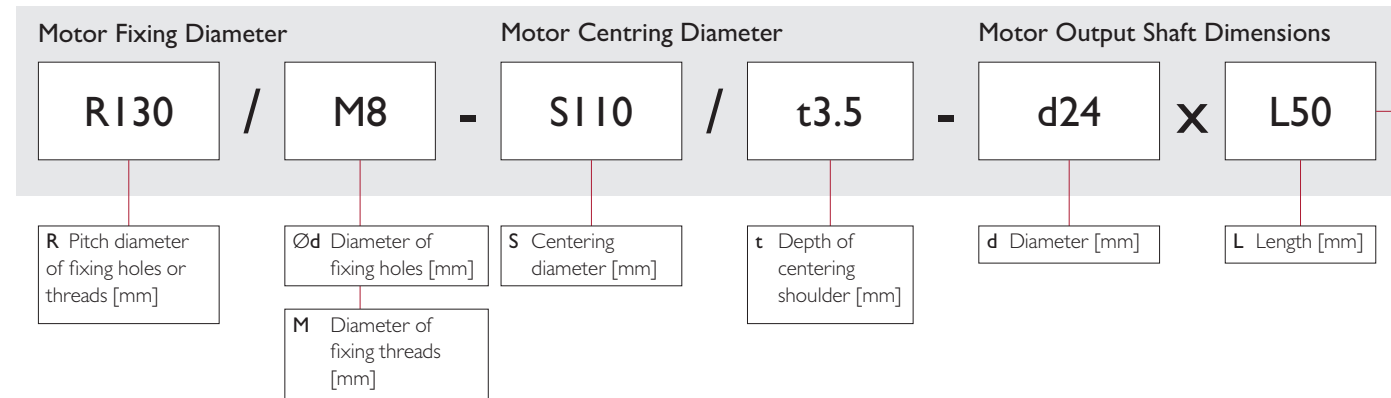
Motor Flange Diameter R130 / MB

Motor Mounting Diameter S110 / c3.5

Motor Output Shaft Dimensions d24 x L50

See Motor Interfaces on pages 112 et seq.

Choose your appropriate Motor Interface



* $t_s > t$ precise motor reference, and in this case change t by t_s in the reference of motor flange.

	Motor				
R	Ød/M	S	t	d	L
63	d 4.5	40	2.5	9	20
63	d 5.4	40	2.5	9	20
63	d 5.5	40	2.5	9	25
64	d 5.4	40	2	9	20
70	d 4.5	40	2.5	9	20
70	d 4.5	50	3	11	30
70	d 4.5	50	3	14	30
70	d 5.5	50	3	14	30
75	d 5.5	60	2.5	11	23

[illegible]

Code
R63 / d4.5-S40 / t2.5-d9 x20
R63 / d5.4-S40 / t2.5-d9 x20
R63 / d5.5-S40 / t2.5-d9 x25
R64 / d5.4-S40 / t2-d9 x20
R70 / d4.5-S40 / t2.5-d9 x20
R70 / d4.5-S50 / t3-d11 x30
R70 / d4.5-S50 / t3-d14 x30
R70 / d5.5-S50 / t3-d14 x30
R75 / d5.5-S60 / t2.5-d11 x23

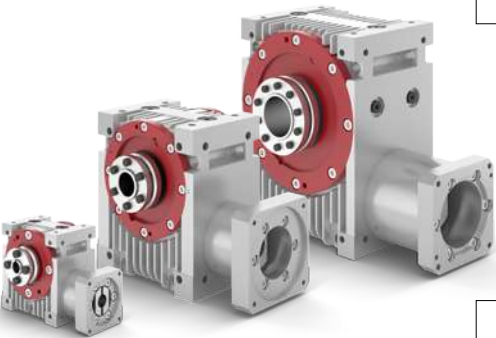
R	Motor				
	Ød/M	S	t	d	L
75	d 5.5	60	2.5	14	30
75	d 5.5	60	3	14	30
75	d 5.8	60	2.5	11	23
75	d 6.5	60	3	14	30
90	d 6	70	3	19	35
90	d 7	70	3	14	30
90	d 7	70	3	16	40
95	d 6.6	50	2.5	14	30
100	d 7	80	3	14	30
100	d 7	80	3	19	40
100	d 6.5	80	2.5	14	30
100	d 6.5	80	3	19	40
100	d 6.6	80	4	10	32
100	d 6.6	80	5	14	37
100	d 6.6	80	5	16	40
115	d 9	95	3	19	40
115	d 7	95	3	24	45
115	d 10	95	3	19	40
130	d 9	95	3	19	40
130	d 9	95	3	24	50
130	d 9	110	3	24	50
130	d 9	110	3.5	24	50
130	d 9	110	3.5	19	40
130	M8	110	3.5	19	40
130	M8	110	3.5	24	50
130	M8	110	3.5	28	60
130	M8	110	3.5	38	80
145	d 9	110	6	19	55
145	d 9	110	6	19	58
145	d 9	110	6	22	58
145	d 9	110	6	24	58
145	d 9	110	6	28	63
145	d 10	110	3.5	16	40
145	d 10	110	3.5	19	40
165	d 11	110	4	24	50
165	d 11	130	3	28	60
165	d 11	130	3.5	19	28
165	d 11	130	3.5	24	50
165	d 11	130	3.5	32	58
165	d 11	130	4	32	58
190	d 11	155	3.5	32	60
190	d 11	155	3.5	35	60
200	d 13.5	114.3	3.2	35	79
200	d 13.5	114.3	3.2	42	113
215	d 14	130	4	32	60
215	d 14	130	4	38	60
215	d 13	180	4	28	60
215	d 13	180	4	38	80
215	d 14	180	4	28	42
215	d 14	180	4	28	60
215	d 14	180	4	32	58
215	d 14	180	4	32	60
215	d 14	180	4	32	80
215	d 14	180	4	38	80
235	d 13.5	200	4	42	116
265	d 13	230	4	38	80
265	d 14	230	4	38	80
265	d 14	230	4	55	110
300	d 18	250	5	42	110
300	d 18	250	5	48	82
300	d 18	250	5	48	110
300	d 19	250	5	48	110
350	d 18	300	5	55	110
350	d 18	300	5	60	110

* Motorenflansch dicker als üblich.

[illegible]

Code
R75 / d5.5-S60 / t2.5-d14x30
R75 / d5.5-S60 / t3-d14x30
R75 / d5.8-S60 / t2.5-d11x23
R75 / d6.5-S60 / t3-d14x30
R90 / d6-S70 / t3-d19x35
R90 / d7-S70 / t3-d14x30
R90 / d7-S70 / t3-d16x40
R95 / d6.6-S50 / t2.5-d14x30
R100 / d7-S80 / t3-d14x30
R100 / d7-S80 / t3-d19x40
R100 / d6.5-S80 / t2.5-d14x30
R100 / d6.5-S80 / t3-d19x40
R100 / d6.6-S80 / t4-d10x32
R100 / d6.6-S80 / t5-d14x37
R100 / d6.6-S80 / t5-d16x40
R115 / d9-S95 / t3-d19x40
R115 / d7-S95 / t3-d24x45
R115 / d10-S95 / t3-d19x40
R130 / d9-S95 / t3-d19x40
R130 / d9-S95 / t3-d24x50
R130 / d9-S110 / t3-d24x50
R130 / d9-S110 / t3.5-d24x50
R130 / d9-S110 / t3.5-d19x40
R130 / M8-S110 / t3.5-d19x40
R130 / M8-S110 / t3.5-d24x50
R130 / M8-S110 / t3.5-d28x60
R130 / M8-S110 / t3.5-d38x80
R145 / d9-S110 / t6-d19x55
R145 / d9-S110 / t6-d19x58
R145 / d9-S110 / t6-d22x58
R145 / d9-S110 / t6-d24x58
R145 / d9-S110 / t6-d28x63
R145 / d10-S110 / t3.5-d16x40
R145 / d10-S110 / t3.5-d19x40
R165 / d11-S110 / t4-d24x50
R165 / d11-S130 / t3-d28x60
R165 / d11-S130 / t3.5-d19x28
R165 / d11-S130 / t3.5-d24x50
R165 / d11-S130 / t3.5-d32x58
R165 / d11-S130 / t4-d32x58
R190 / d11-S155 / t3.5-d32x60
R190 / d11-S155 / t3.5-d35x60
R200 / d13.5-S114.3 / t3.2-d35x79
R200 / d13.5-S114.3 / t3.2-d42x113
R215 / d14-S130 / t4-d32x60
R215 / d14-S130 / t4-d38x60
R215 / d13-S180 / t4-d28x60
R215 / d13-S180 / t4-d38x80
R215 / d14-S180 / t4-d28x42
R215 / d14-S180 / t4-d28x60
R215 / d14-S180 / t4-d32x58
R215 / d14-S180 / t4-d32x60
R215 / d14-S180 / t4-d32x80
R215 / d14-S180 / t4-d38x80
R235 / d13.5-S200 / t4-d42x116
R265 / d13-S230 / t4-d38x80
R265 / d14-S230 / t4-d38x80
R265 / d14-S230 / t4-d55x110
R300 / d18-S250 / t5-d42x110
R300 / d18-S250 / t5-d48x82
R300 / d18-S250 / t5-d48x110
R300 / d19-S250 / t5-d48x110
R350 / d18-S300 / t5-d55x110
R350 / d18-S300 / t5-d60x110

Calculate your High Performance Angle Gearbox

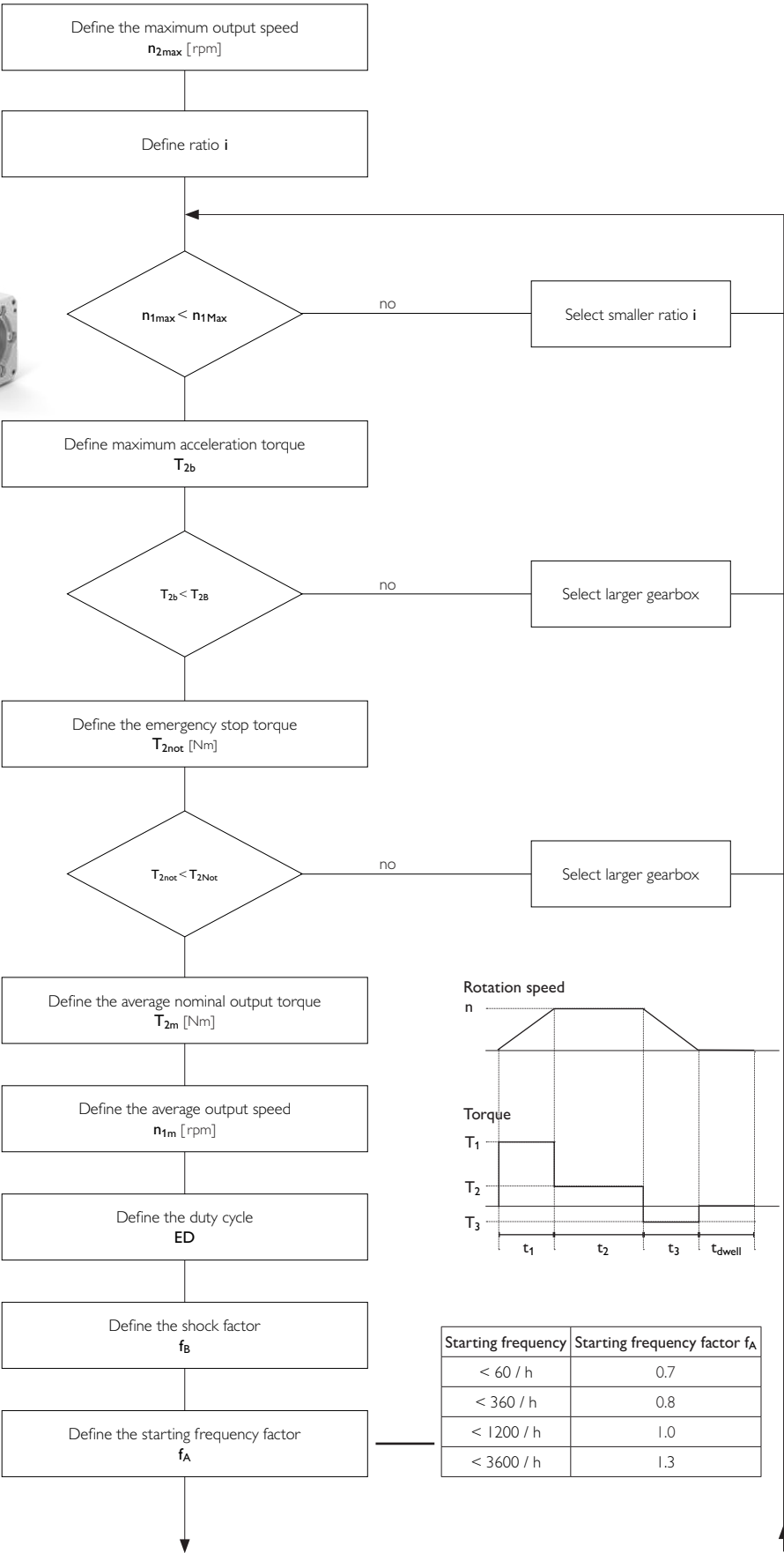


$$T_{2m} = 3 \sqrt{\frac{(|n|/2) \times t_1 \times |T_1|^3 + |n| \times t_2 \times |T_2|^3 + (|n|/2) \times t_3 \times |T_3|^3}{(|n|/2) \times t_1 \times |n| \times t_2 + (|n|/2) \times t_3}}$$

$$n_{1m} = \frac{(|n|/2) \times t_1 + |n| \times t_2 + (|n|/2) \times t_3}{t_1 + t_2 + t_3}$$

$$ED = (t_1 + t_2 + t_3) / (t_1 + t_2 + t_3 + t_{dwell}) \times 100\%$$

Input	S hock factor f_B
Polynomia	1.0
Standard Servo / Sinus2	1.1
FU / VFD	1.25
AC- Motor	1.4
External Output-shock	1.6



Starting frequency	Starting frequency factor f_A
< 60 / h	0.7
< 360 / h	0.8
< 1200 / h	1.0
< 3600 / h	1.3

	Size					
	030	045	060	090	120	180
$n_{1m} < 500$ rpm	5.50	3.00	1.70	1.10	1.00	1.00
$n_{1m} < 1000$ rpm	4.00	2.30	1.40	1.05	1.00	1.00
$n_{1m} < 1500$ rpm	3.30	2.00	1.30	1.05	1.00	1.00
$n_{1m} < 3000$ rpm	2.30	1.50	1.15	1.05	1.00	1.00
$n_{1m} < 4500$ rpm	1.70	1.30	1.05	1.00	1.00	
$n_{1m} < 6000$ rpm	1.50	1.20	1.00			

Abrasion factor f_P^* for high-accuracy applications, otherwise $f_P = 1$.

	Size					
	030	045	060	090	120	180
$n_{1m} < 500$ rpm	0.40	0.40	0.40	0.60	0.80	0.90
$n_{1m} < 1000$ rpm	0.40	0.40	0.45	0.70	0.90	1.10 ^{a)}
$n_{1m} < 1500$ rpm	0.40	0.40	0.55	0.80	1.20	1.30 ^{a)}
$n_{1m} < 3000$ rpm	0.40	0.40	0.70	0.95 ^{a)}	2.00 ^{a)}	2.40 ^{b)}
$n_{1m} < 4500$ rpm	0.40	0.40	0.70	1.00 ^{a)}	2.80 ^{a)}	
$n_{1m} < 6000$ rpm	0.40	0.40	0.75			

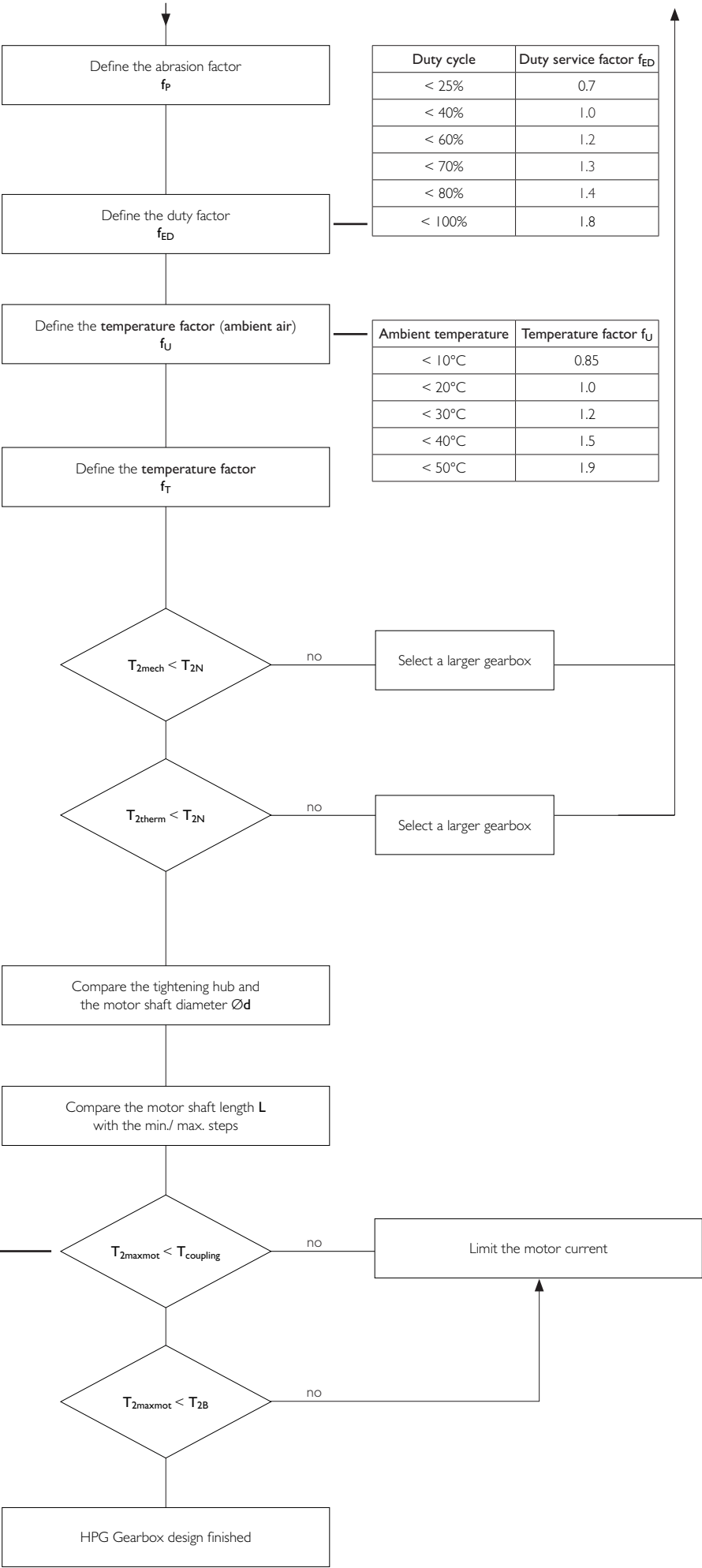
a) Maximum duty cycle 80%
b) Maximum duty cycle 60%

$$T_{2mech} = T_{2m} \times f_B \times f_A \times f_P^*$$

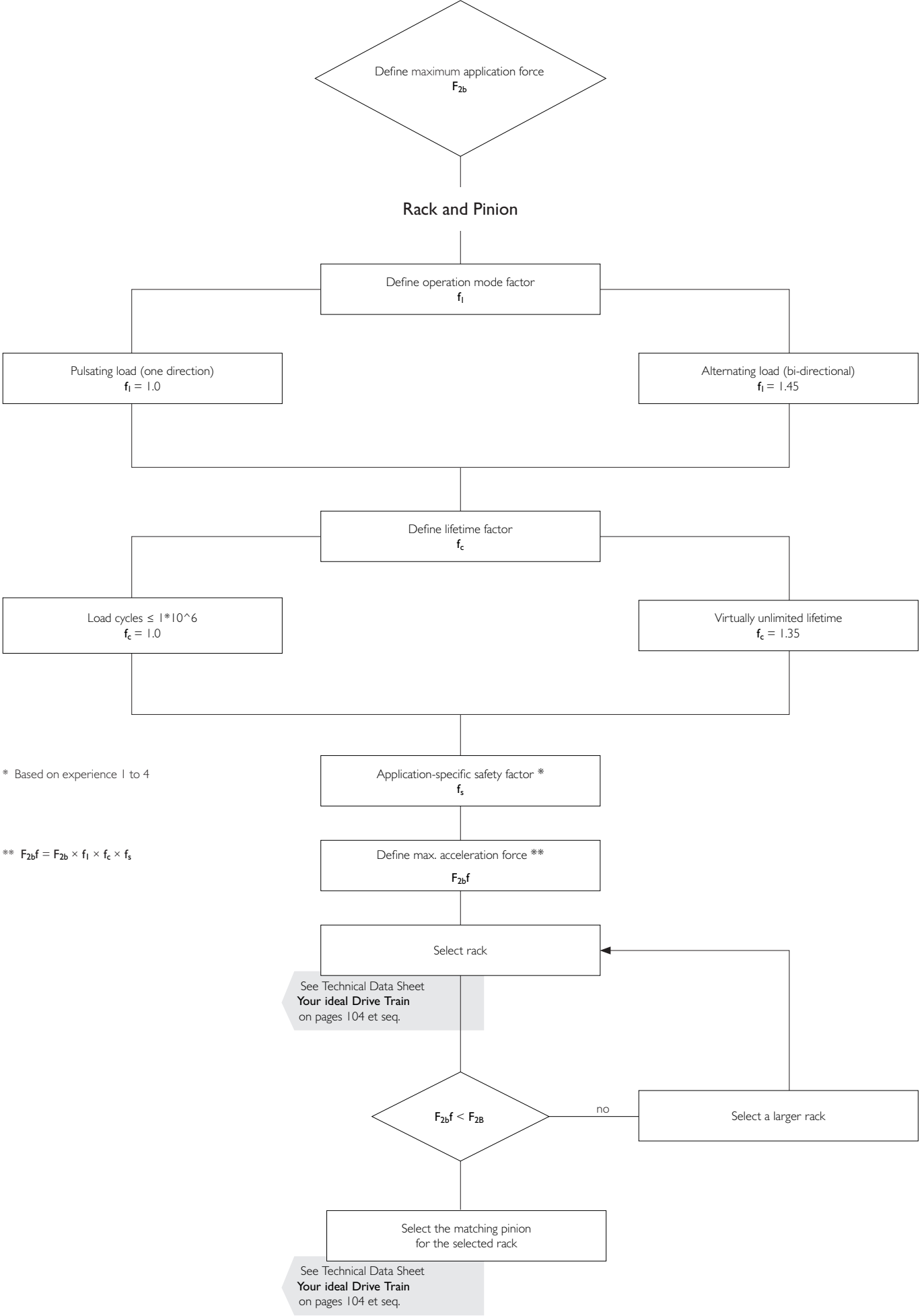
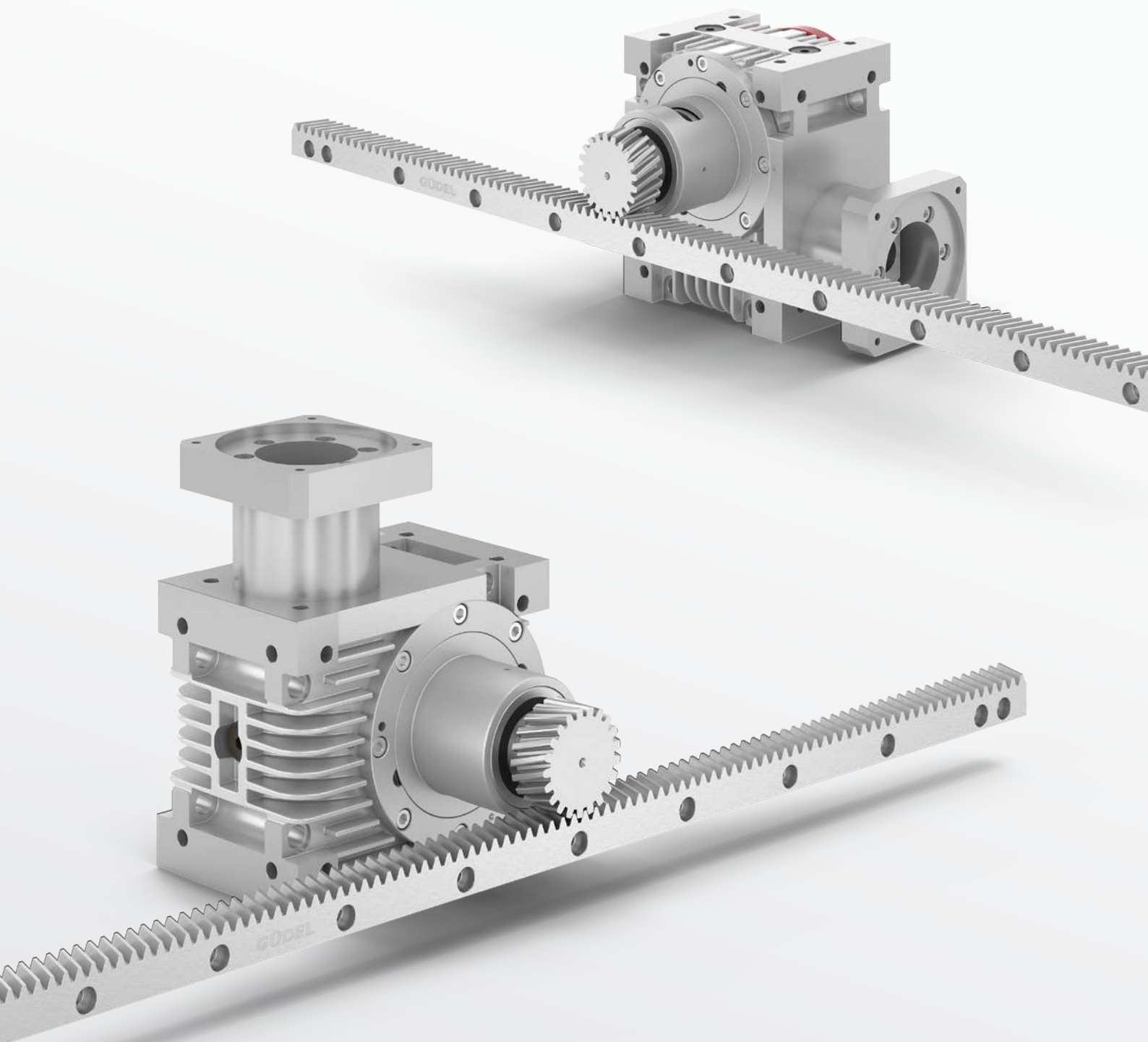
$$T_{2therm} = T_{2m} \times f_{ED} \times f_T \times f_U$$

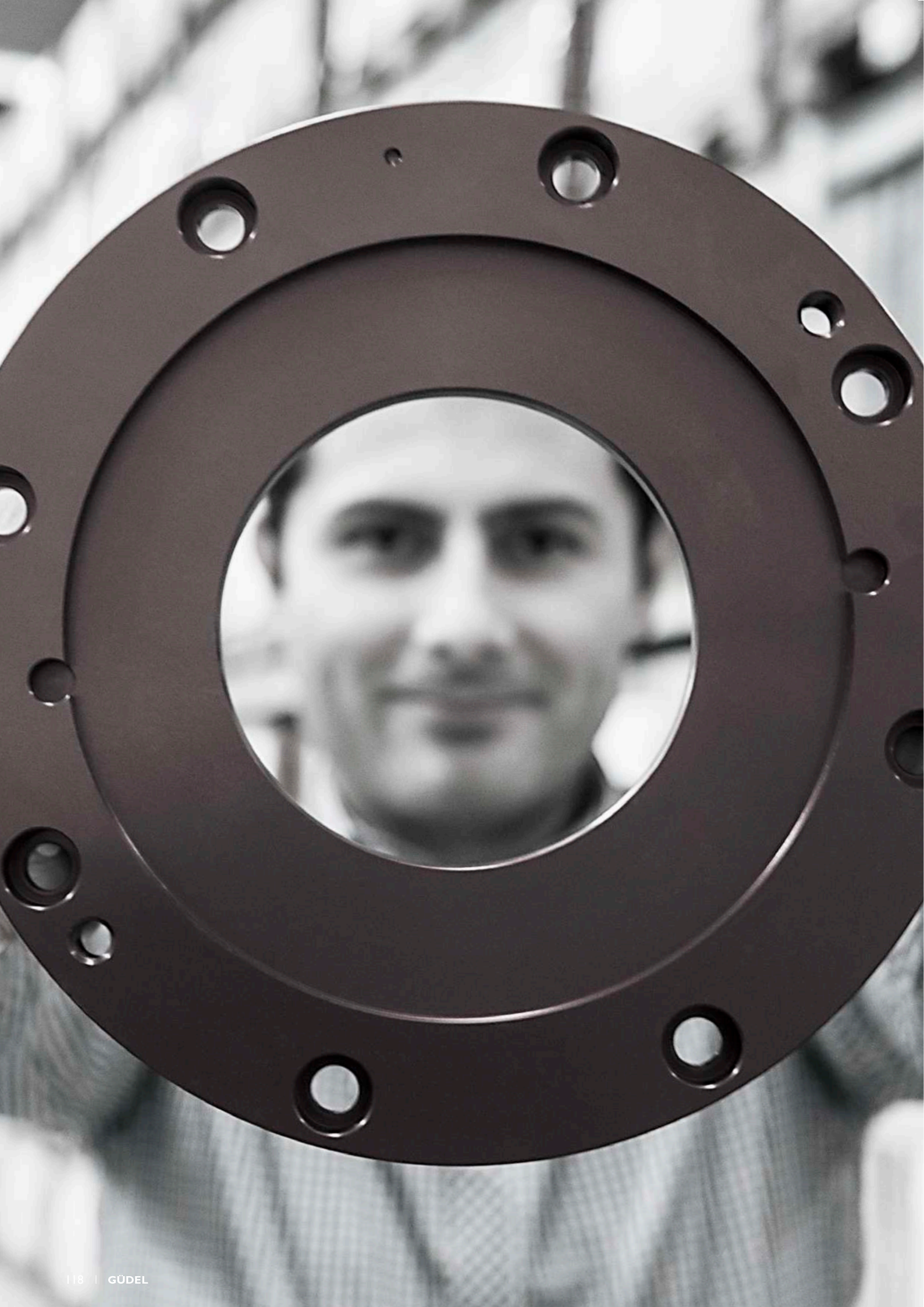
Transmittable torque of the coupling [Nm]

	Size					
	030	045	060	090	120	180
8	3.5					
9	3.9	6.8				
10	4.3	7.6	17.5			
11	4.8	8.3	19.2			
14	6.1	10.6	24.5	44.9		
16	6.9	12.1	28.0	51.3		
19	8.2	14.4	33.2	61.0	61.0	
22		19.1	38.4	70.6	70.6	168
24		20.8	41.9	77.0	77.0	183
28			42.3	89.8	89.8	214
32			48.4	103	103	244
35			52.9	112	112	267
38				133	122	290
42				147	135	321
48					168	367
55						420
60						458



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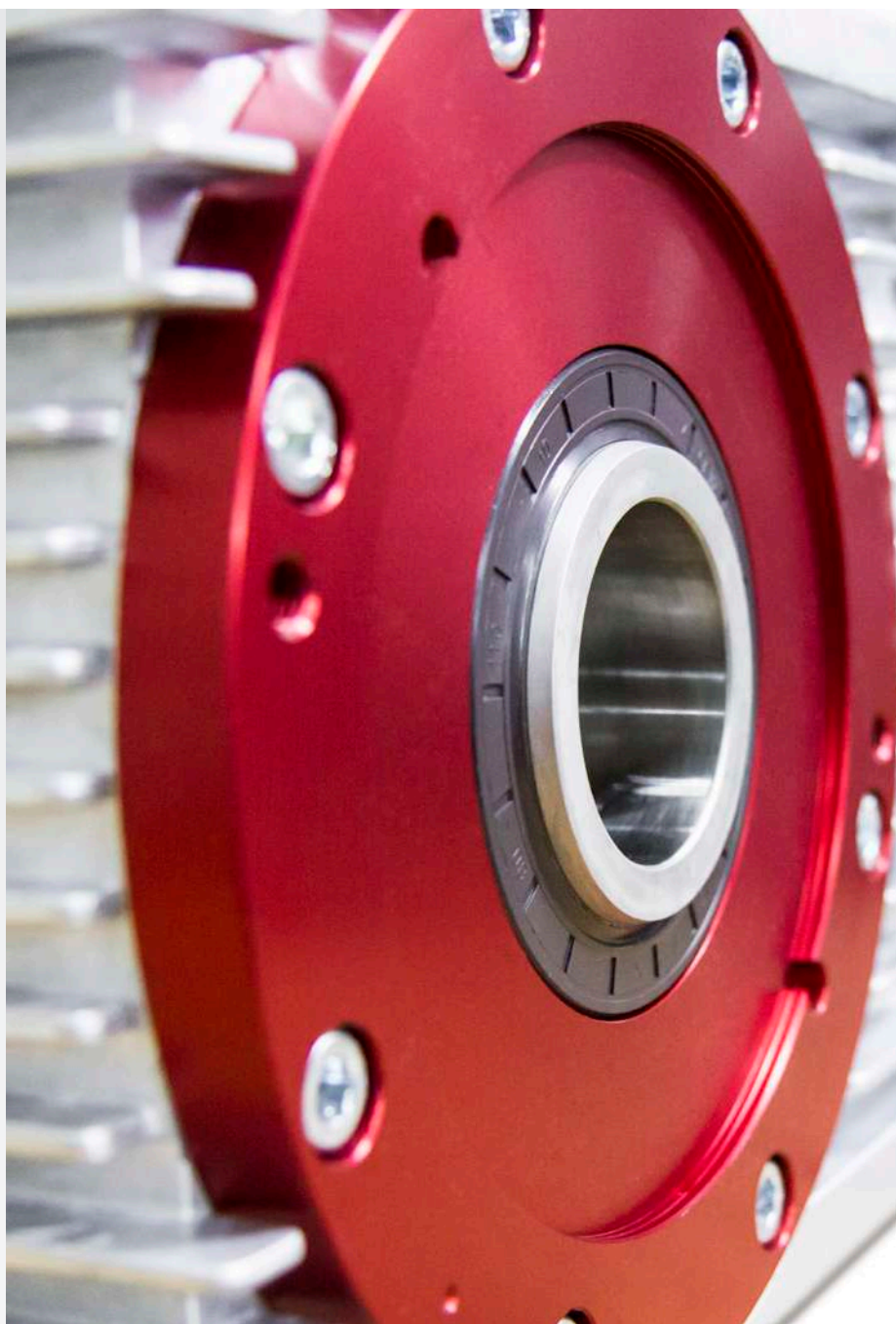
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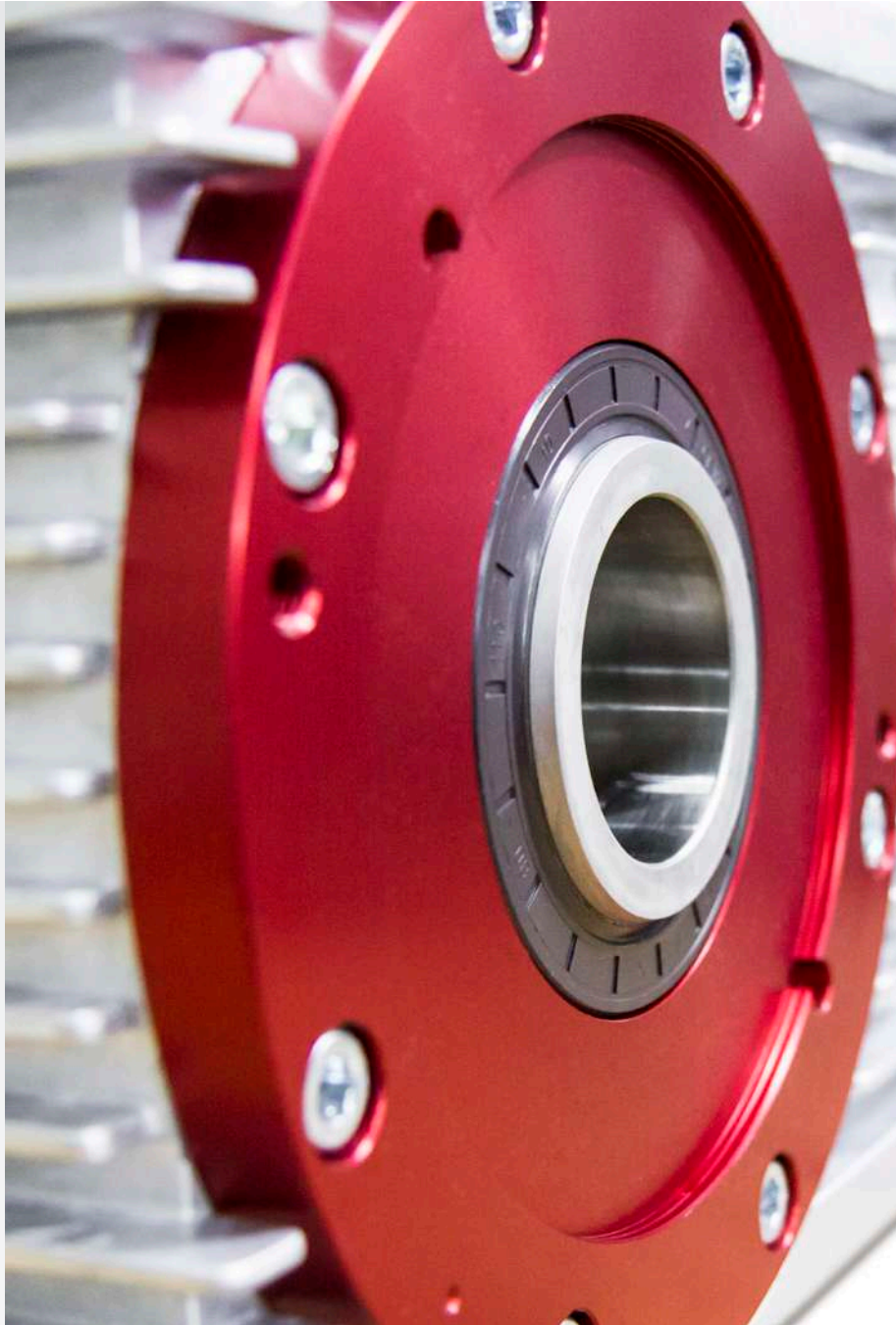
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High Performance Angle Gearboxes

